



S.C Department of Natural Resources

LiDAR Campaign (Sumter County, SC) Report of Survey

2011

EXECUTIVE SUMMARY

S.C. Department of Natural Resources contracted with Sanborn to provide LiDAR mapping services for Sumter County. Utilizing multi-return systems, Light Detection and Ranging (LiDAR) data in the form of 3-dimensional positions of a dense set of mass points was collected for approximately 680 square miles between February 21st 2010 and March 27th 2010. All systems consist of geodetic GPS positioning, orientation derived from high-end inertial sensors and high-accurate lasers. The sensor is attached to the aircraft's underside and emits rapid pulses of light that are used to determine distances between the plane and terrain below.

Specifically, the Leica ALS-50 system was used to collect data for the survey campaign. The LiDAR system is calibrated by conducting flight passes over a known ground surface before and after each LiDAR mission. During final data processing, the calibration parameters are inserted into post-processing software.

Seven airborne GPS (Global Positioning System) base stations were used in the Sumter County project. NGS points with PID's AE3535, DF3844, DE3192, AJ7022, EC2483, AJ7047, and DF7761 were used as monuments for the GPS base station placement. These four base stations were tied to each other to create a GPS survey network. The coordinates of these stations were checked against each other with the three dimensional GPS baseline created at the airborne support set up and determined to be within project specifications.

The acquired LiDAR data was processed to obtain first and last return point data. The last return data was further filtered to yield a LiDAR surface representing the bare earth.

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1.0 INTRODUCTION

This document contains the technical write-up of the LiDAR campaign, including standard specifications, system calibration techniques, field procedures, and the accuracy of the LiDAR data.

1.1 Contact Information

Questions regarding the technical aspects of this report should be addressed to:

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1.2 Purpose of the LiDAR Acquisition

As stated in the Statement of Work for Acquisition and Production of High Resolution Elevation data for the SCDNR 2010 project, this LiDAR operation was designed to create high resolution data sets that will establish an authoritative source for elevation information for Sumter County.

1.3 Project Location

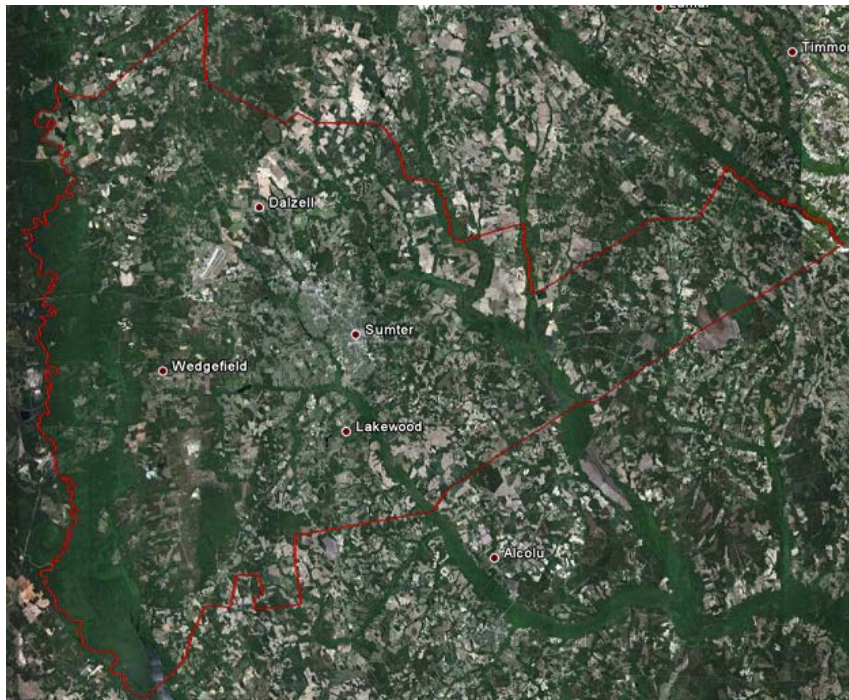


Figure 1: Area of Collection

1.4 Standard Specifications for LiDAR

Table 1: LiDAR Specifications

Data Acquisition		
Requirement	Description	
Returns per pulse	LiDAR sensor shall be capable of recording up to 3 (or more) returns per pulse, including 1st and last returns	
Scan angle	≤ ±20 degrees	*
Swath overlap	Nominal sidelap on adjoining swaths, i.e., survey shall be designed for 50% overlap coverage at planned aircraft height above ground	50%
Design pulse density (nominal)	Pulses/m ² (includes swath overlap; e.g., with 30% sidelap, ≥ 2 pulse/m ² in each swath)	≥1
GPS procedures	At least 2 GPS reference stations in operation during all missions, sampling positions at 1 Hz or higher frequently. Differential GPS baseline lengths shall not exceed 30 km. Differential GPS unit in aircraft shall sample position at 2 Hz or higher. LiDAR data shall only be acquired when GPS PDOP is ≤ 3.5 and at least 6 satellites are in view.	*
Data Collection Season	Target window for collection of LiDAR data ends Spring of 2010. This may be extended with approval by State program managers	*
Survey conditions	Leaf-off and no significant snow cover, as observed by state contract representatives.	*
Geographic Coverage and Continuity		
Coverage	No voids between swaths. No voids because of cloud cover or instrument failure.	
Swath overlap	≤ 50% no-overlap area per project.	

2.0 LIDAR CALIBRATION

2.1 Introduction

LiDAR calibrations are performed to determine and therefore eliminate systematic biases that occur within the hardware of the Leica ALS-50 system. Once the biases are determined they can be modeled out. The systematic biases are corrected for include heading, roll, and pitch.

The following procedures are intended to prevent operational errors in the field and office work, and are designed to detect inconsistencies. The emphasis is not only on the quality control (QC) aspects, but also on the documentation, i.e., on the quality assurance (QA).

2.2 Calibration Procedures

When Sanborn receives raw point cloud data from its subcontractors, calibration procedures using TerraSolid products are applied- including TerraScan and TerraMatch. Utilizing these two tools, Sanborn is able to correct each individual raw data strip to precisely match the two overlapping swaths. In return, the RMSE of the entire project is substantially lower, resulting in a more accurate dataset. TerraMatch samples the data perpendicular to the flight pattern to assess and correct for roll errors, pitch errors, and heading errors.

Throughout the Sumter County project, flight direction consisted of a southwest to northeast flight pattern. Rows of small sample tiles were placed perpendicular to the raw strips, and populated with the raw point cloud data. Once the population of the data is complete, a filter is applied to each sample tile. The filter classifies bare earth and building rooftops per flight line in order for TerraMatch to recognize the individual strips and their features, allowing the software to find corrections for roll, pitch, and heading throughout the project. Once the adjustments are calculated, the settings are applied to the final delivery tiles.

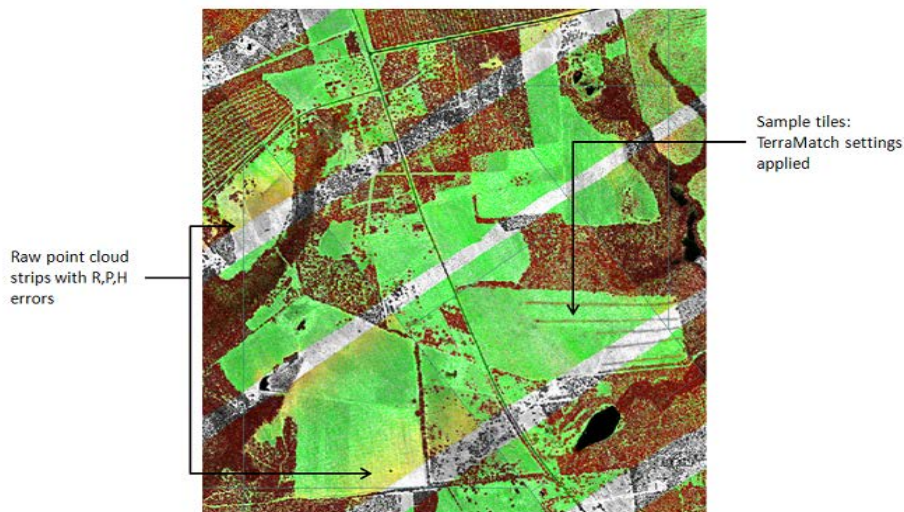


Figure 2: TerraMatch Tiling Sample

3.0 LIDAR FLIGHT AND SYSTEM REPORT

3.1 Introduction

This section addresses LiDAR system, flight reporting and data acquisition methodology used during the collection of the Sumter county campaign. Although Sanborn and Keystone conducts all LiDAR with the same rigorous and strict procedures and processes, all LiDAR collections are unique.

3.2 Field Work Procedures

A minimum of two GPS base stations were set for the Sumter County project, which is within the project area or within the required baseline specifications of the project.

Pre-flight checks such as cleaning the sensor head glass are performed. A four minute INS initialization is conducted on the ground, with the engines running, prior to flight, to establish fine-alignment of the INS. GPS ambiguities are resolved by flying within ten kilometers of the base stations.

The flight missions were typically four or five hours in duration including runway calibration flights flown at the beginning and the end of each mission. During the data collection, the operator recorded information on log sheets which includes weather conditions, LiDAR operation parameters, and flight line statistics. Near the end of the mission GPS ambiguities are again resolved by flying within ten kilometers of the base stations, to aid in post-processing.

Table 2 shows the planned LiDAR acquisition parameters with a flying height of 1500-1700 meters above ground level (AGL) for the Leica system on a mission to mission basis.

Table 2: LiDAR Acquisition Parameters

Average Altitude	1500-1700 Meters AGL
Airspeed	~120-140 knots
Scan Frequency	26.5-36 Hertz
Scan Width Half Angle	20 Degrees
Pulse Rate	70,000-71,800 Hertz

Preliminary data processing was performed in the field immediately following the missions for quality control of GPS data and to ensure sufficient overlap between flight lines. Any problematic data could then be re-flown immediately as required. Final data processing was completed in the Colorado Springs office.

Table 3: Collection Dates, Times, Average Per Flight Collection Parameters and PDOP

Mission	Date	Sensor # (Sanborn 1,2)	Start Time	End Time	Altitude (m)	Airspeed (Knots)	Scan Angle	Scan Rate	Pulse Rate	PDOP (Ave)
052b	Feb 21	ALS50-S1	20:07	00:33	1500	140	40°	36	71800	1.8
057b	Feb 26	ALS50-S1	18:31	22:34	1500	140	40°	36	71800	2.0
078a	Mar 19	ALS50-S2	12:51	18:28	1500	140	40°	36	71800	1.7
078b	Mar 19	ALS50-S2	20:25	22:23	1500	140	40°	36	71800	1.7
079a	Mar 20	ALS50-S1	17:26	23:08	1500	140	40°	36	71800	1.9
083a	Mar 24	ALS50-S1	20:53	02:19	1500	140	40°	36	71800	1.8
083a	Mar 24	ALS50-S2	14:32	19:38	1500	140	40°	36	71800	1.7
083b	Mar 24	ALS50-S2	20:49	22:45	1500	140	40°	36	71800	1.9
083c	Mar 24	ALS50-S2	23:20	01:00	1500	140	40°	36	71800	1.7
084a	Mar 25	ALS50-S1	14:46	18:29	1500	140	40°	36	71800	1.8
084a	Mar 25	ALS50-S2	15:58	18:30	1500	140	40°	36	71800	1.8
084b	Mar 25	ALS50-S2	19:07	21:44	1500	140	40°	36	71800	1.7
086a	Mar 27	ALS50-S2	16:24	20:37	1500	140	40°	36	71800	1.6
077a	Mar 18	ALS50-Key	13:48	18:57	1700	120	40°	26.5	70000	1.9
078a	Mar 19	ALS50-Key	14:41	19:01	1700	120	40°	26.5	70000	2.0
078b	Mar 19	ALS50-Key	19:46	22:24	1700	120	40°	26.5	70000	1.9
082a	Mar 23	ALS50-Key	13:46	18:15	1700	120	40°	26.5	70000	1.7
082b	Mar 23	ALS50-Key	20:18	23:19	1700	120	40°	26.5	70000	1.8
083a	Mar 24	ALS50-Key	14:14	19:57	1700	120	40°	26.5	70000	1.8
083b	Mar 24	ALS50-Key	21:52	01:20	1700	120	40°	26.5	70000	1.9
084a	Mar 25	ALS50-Key	14:35	14:45	1700	120	40°	26.5	70000	1.8

3.3 Final LiDAR Processing

LiDAR filtering was accomplished using TerraSolid, TerraScan LiDAR processing and modeling software. The filtering process reclassifies all the data into classes within the LAS formatted file based scheme set using the LAS format 1.2 specifications or by the client. Once the data is classified, the entire data set is reviewed and manually edited for anomalies that are outside the required guidelines of the product specification or contract guidelines, whichever apply. Table 4 indicates the required product specifications.

The coordinate and datum transformations are then applied to the data set to reflect the required deliverable projection, coordinate and datum systems as provided in the contract.

The client required deliverables are then generated. At this time, a final QC process is undertaken to validate all deliverables for the project. Prior to release of data for delivery, Sanborn's quality control/quality assurance department reviews the data and then releases it for delivery.

Table 4: Processing Accuracies and Requirements

Accuracy of LiDAR Data (H)	1m RMSE
Accuracy of LiDAR data in bare areas (Z)	15 cm RMSE

4.0 GEODETIC AUTHENTICATION

4.1 Final LiDAR Verification

The LiDAR data was evaluated using a collection of 19 NGS benchmarks; see figure 3 for diagram. For Sumter County, the standard deviation is 0.370 feet and the root mean squared is 0.39 feet. The LiDAR data was compared to each of these benchmarks yielding a better result than was required for the project. Table 5 indicates the results for Sumter County and each point including the overall results as it compares to the LiDAR data set.

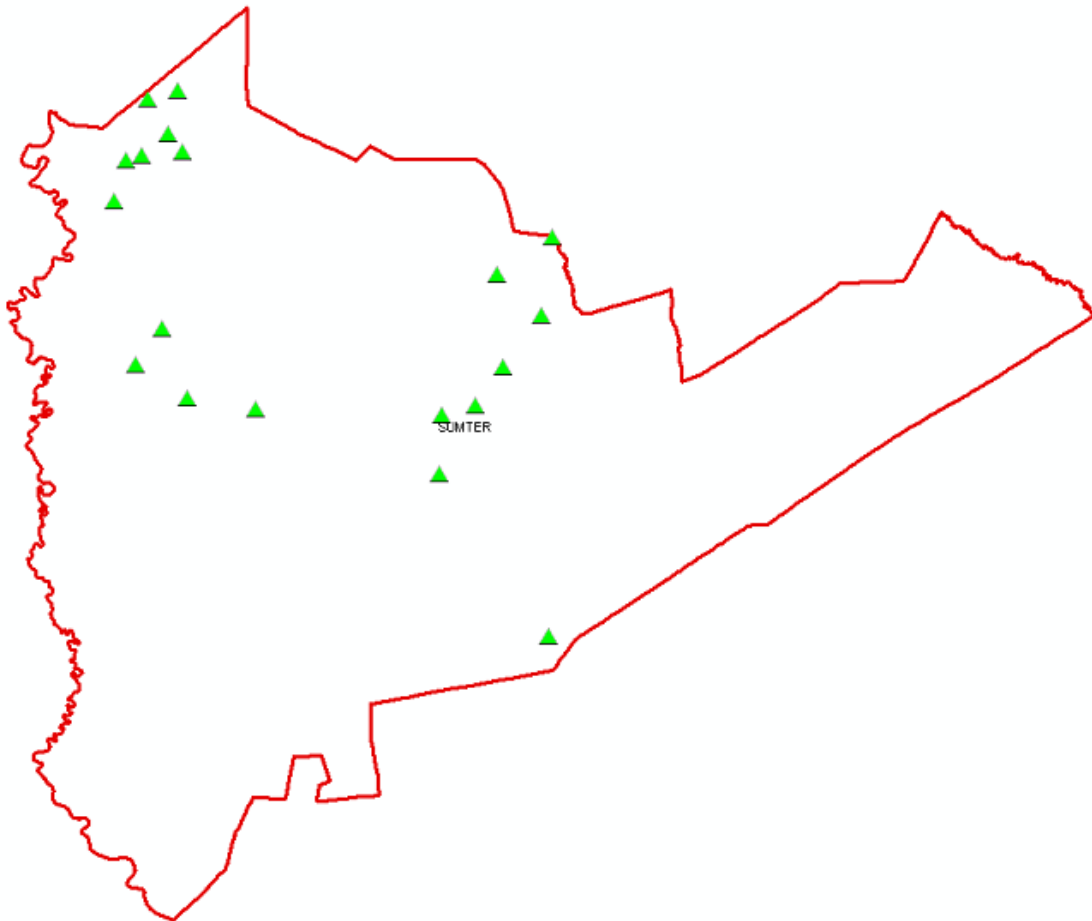


Figure 3: Sumter Survey Checkpoint Diagram

Table 5: LiDAR Accuracy Assessment based on the Checkpoint Survey (Feet)

Name	Vegetation Class	Easting	Northing	Known Z	Laser Z	Dz
EC2953	Bare Earth	2129713.700	809526.690	153.940	154.560	+0.620
EC2479	Bare Earth	2135346.680	819103.120	184.660	185.000	+0.340
DE1748	Bare Earth	2205382.300	766700.510	146.210	146.380	+0.170
EC2477	Bare Earth	2209795.970	794303.700	159.310	159.470	+0.160
EC1261	Bare Earth	2143021.480	832702.920	262.780	262.850	+0.070
DE3142	Bare Earth	2159259.030	766104.970	215.400	215.450	+0.050
EC3142	Bare Earth	2132094.930	818053.670	171.940	171.950	+0.010
DE1742	Bare Earth	2134118.440	775286.660	139.140	139.070	-0.070
DE1702	Bare Earth	2220652.220	718431.160	128.110	128.030	-0.080
EC2475	Bare Earth	2136720.130	831004.990	192.170	192.060	-0.110
EC3140	Bare Earth	2141014.380	823696.590	222.280	222.140	-0.140
DE3138	Bare Earth	2211231.460	774730.820	140.460	140.190	-0.270
DE3390	Bare Earth	2198221.930	764850.860	175.450	175.160	-0.290
DE3158	Bare Earth	2139732.180	782817.480	213.200	212.900	-0.300
DE1699	Bare Earth	2197689.960	752467.400	157.910	157.440	-0.470
DE3155	Bare Earth	2219189.750	785604.950	147.890	147.390	-0.500
EC2478	Bare Earth	2143999.790	819771.810	185.190	184.540	-0.650
EC1263	Bare Earth	2221403.860	801890.620	154.290	153.560	-0.730
DE3399	Bare Earth	2145014.630	768205.460	378.680	377.870	-0.810
Average dz		-0.158				
Minimum dz		-0.810				
Maximum dz		+0.620				
Average Magnitude		0.307				
Root Mean Square		0.393				
Std deviation		0.370				

5.0 COORDINATES AND DATUM

5.1 Introduction

The final adjustment was constrained to the published NAD83 geodetic coordinates (ϕ , λ) and NAVD88 elevations. The adjustment was cross-referenced to the GEOID03 model to enable the estimation of orthometric heights.

5.2 Horizontal Datum

The final horizontal coordinates are provided in State Plane HARN South Carolina FIPS 3900 on the North American Datum of 1983 (NAD83 adjustment of 1992) units of intl feet.

5.3 Vertical Datum

The final orthometric elevations were determined for all points in the network using Geoid03 model and are provided on the North American Vertical Datum of 1988 in units of survey feet.