



FINAL REPORT OF SPECIFIC PURPOSE LIDAR SURVEY



LiDAR, Breaklines and Contours for Franklin County, Florida

State of Florida
Division of Emergency Management
Contract 07-HS-34-14-00-22-469
Task Order 20070525-492718a
PDS Task Order B

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**Final Report of Specific Purpose LiDAR Survey, including
LiDAR-Generated Breaklines and Contours for Franklin County, Florida
Contract 07-HS-34-14-00-22-469; T.O. No. 20070525-492718a, Task Order B**

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Report of Specific Purpose LiDAR Survey, LiDAR-Generated Breaklines and Contours Franklin County, Florida

Type of Survey: Specific Purpose Survey

This report pertains to a Specific Purpose LiDAR Survey of Franklin County, Florida, conducted in the summer of 2007, and breaklines and contours generated in 2007 and 2008, for the Florida Division of Emergency Management (FDEM).

The LiDAR dataset, breaklines and contours were prepared by the Program and Data Solutions (PDS) team under FDEM contract 07-HS-34-14-00-22-469, Task Order 20070525-492718a (PDS Task Order B). The LiDAR dataset of Franklin County was acquired by AeroMetric, Inc. in the western half of the county, and Terrapoint in the eastern half of the county, in the summer of 2007 and processed to a bare-earth digital terrain model (DTM); it was produced to FDEM vertical accuracy specifications that differ from NOAA specifications previously used in Walton County, Santa Rosa County, Escambia County and northern Bay County. These differences are summarized in Table 1.

Table 1. Comparison of FDEM and NOAA Vertical Accuracy Criteria

Vertical Accuracy Criteria	FDEM Specifications	NOAA Specifications
Fundamental Vertical Accuracy (FVA) at the 95% confidence level, in open terrain (non-vegetated) land cover only	≤ 18.2-cm (0.60-ft) (based on RMSE _z of 9.25-cm x 1.9600)	≤ 29.4-cm (0.96-ft) (based on RMSE _z of 15-cm x 1.9600)
Consolidated Vertical Accuracy (CVA) at the 95% confidence level, in all land cover categories combined	≤ 36.3-cm (1.19-ft) (based on 95 th percentile) or RMSE _z of 18.5-cm x 1.9600	≤ 36.3-cm (1.19-ft) (based on 95 th percentile) or RMSE _z of 18.5-cm x 1.9600

Under Task Order B, this is one of 12 similar county reports prepared by the PDS team of coastal areas along the Florida Panhandle, from Escambia County through Levy County, considered by FDEM to be vulnerable to hurricane tidal surges. Of these 12 reports, those for coastal Escambia, Santa Rosa, Walton and northern Bay County are based on LiDAR data previously acquired in support of the Northwest Florida Water Management District (NFWMD) and produced to different accuracy specifications as indicated in Table 1 and to different point densities.

The reports for coastal areas of Franklin County, as well as Okaloosa, Bay, Gulf, Wakulla, Jefferson, Taylor, Dixie, and Levy counties are based on LiDAR data acquired in 2007 by the PDS team under the referenced FDEM contract, produced to the more-rigorous FDEM specifications. Detailed breaklines and contours were produced by the PDS team for areas to be mapped/improved as identified by a tile index provided by FDEM to PDS. Each tile covers an area of 5000 ft by 5000 ft. The map at Appendix A displays the 788 tiles of Franklin County for which LiDAR DTMs and LiDAR-derived breaklines and contours were produced by the PDS team under Task Order B. To avoid double counting, tiles on the county border with Gulf County and Wakulla County were delivered only in one county dataset, as shown at Appendix A.

Rather than describe only the data provided of Franklin County in isolation, this report also explains the differences between LiDAR datasets acquired of Escambia, Santa Rosa, Walton and northern Bay



counties and those of other counties in the Florida Panhandle produced to different specifications. In addition to the differences in vertical accuracy criteria, summarized in Table 1, there are also differences in the geodetic control used for the different contracts, and there are different point densities between the data acquired to NOAA specifications and data acquired to FDEM Baseline Specifications:

- For the nine new counties mapped by the PDS team for FDEM in the Florida Panhandle under Task Order B, a rigorous geodetic control network was established by the PDS team for all coastal counties between Okaloosa and Levy counties, but excluding Walton County which had been previously mapped by NOAA. Thus, the survey control used for Escambia, Santa Rosa, Walton and northern Bay counties may differ from the geodetic control network established for the nine other counties in the Panhandle. Primarily because a rigorous geodetic control network was surveyed by the PDS team for the nine new counties, it is expected that there will be differences in the elevations of topographic surfaces between counties, primarily around the boundaries of Escambia, Santa Rosa and Walton counties where the 2006 LiDAR datasets, controlled to older survey control, merge with the 2007 LiDAR datasets controlled to the new geodetic control network established by the PDS team. Furthermore, northern Bay County was flown to the less-demanding NOAA specifications whereas southern Bay County was flown to the more-demanding FDEM specifications.
- For the nine new counties, including Franklin County, the FDEM Baseline Specifications require a maximum post spacing of 4 feet, i.e., an average point density of less than 1 point per square meter. However, the PDS team required a much higher point density of its subcontractors in order to increase the probability of penetrating dense foliage during the mandated summer acquisition; with nominal post spacing of 0.7 meters per flight line and 50% sidelap between flight lines, the average point density is 4 points per square meter. The NOAA specifications for Escambia County, Santa Rosa County, Walton County, and northern Bay County, required a nominal post spacing of 2 meters, yielding an average point density of 0.25 points per square meter. The significance of this difference is that the nine new counties acquired for FDEM, including Franklin County, have LiDAR point densities approximately 16 times higher than the LiDAR point densities in Escambia County, Santa Rosa County, Walton County, and northern Bay County. With higher point density there is a greater probability of penetrating dense vegetation and minimizing areas defined as “low confidence areas.”

The PDS Team

PDS is a Joint Venture consisting of PBS&J, Dewberry, and URS Corp:

- PBS&J provided local client liaison in Tallahassee. PBS&J was also responsible for the overall ground survey effort including management of field survey subcontractors – Allen Nobles & Associates, Inc. (ANA) and Diversified Design & Drafting Services, Inc. (3DS) – which performed the geodetic control surveys and quality assurance/quality control (QA/QC) checkpoint surveys used for independent accuracy testing by Dewberry and URS. These surveyors executed a network adjustment of control points used throughout the Florida Panhandle. It was important to execute this network adjustment because of widely-held concerns that the survey control was deficient in the Florida Panhandle counties. Mr. Glenn Bryan, PSM, of PBS&J, and Mr. Brett Wood, PSM, of 3DS, were the technical leads for the control surveys and QA/QC surveys.
- Dewberry was responsible for the overall Work Plan and aerial survey effort for the nine new counties, including management of LiDAR subcontractors that performed the LiDAR data



acquisition and post-processing and produced LAS classified data. A staff of QA/QC specialists at Dewberry's Fairfax (VA) office performed quality assessments of the breaklines and contours. Dewberry served as the single point of contact with FDEM. Dr. David Maune, PSM, was Dewberry's technical lead for the digital orthophoto and LiDAR surveys and derived products. Under separate contract with NOAA, Dr. Maune had previously served as Dewberry's Quality Manager for its independent QA/QC of LiDAR data produced by NOAA for the NFWFMD of Escambia, Santa Rosa, and Walton counties. Dewberry did not perform QA/QC of the existing LiDAR dataset of northern Bay County.

- URS Corp. was responsible for data management and information management. URS developed the GeoCue Distributed Production Management System (DPMS), managed and tracked the flow of data, performed independent accuracy testing and quality assessments of FDEM's new LiDAR data acquired in 2007, tracked and reported the status of individual tiles during production, and produced all final deliverables for FDEM. Mr. Robert Ryan, CP, of URS, was the technical lead for this effort.

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Survey Area

The project area for this report encompasses approximately 707 square miles within Franklin County and small adjoining areas of Gulf County and Wakulla County.

Map Reference

There are no hardcopy map sheets for this project. The map at Appendix A provides graphical reference to the 5000-ft x 5000-ft tiles covered by this report.

Summary of FDEM Baseline Specifications

All new data produced for FDEM under the referenced contract are required to satisfy the Florida Baseline Specifications, included as appendices to PDS's Task Order B, dated May 23, 2007, from FDEM. To expedite production, the Florida Baseline Specifications were modified by FDEM to require new LiDAR data acquisition during the summer of 2007 (leaf-on) as opposed to the normal leaf-off.

Task Order B presented demanding technical challenges for the PDS team because the existing geodetic control monuments in the Florida Panhandle are believed to be the most inaccurate in Florida, with elevation discrepancies as much as several feet; and some areas in the Panhandle are subject to subsidence. LiDAR elevations produced relative to some survey control monuments are believed to differ by as much as several feet from LiDAR elevations produced relative to other control monuments in the Panhandle. This caused a new geodetic control network to be established by the PDS team for the counties to be newly surveyed, but without adjusting the geodetic control monuments used for Escambia



County, Santa Rosa County, Walton County, and northern Bay County for which existing LiDAR data was used “as is.”

The official State Plane Coordinate System tiling scheme was provided by FDEM to the PDS team on July 10, 2007 for Florida’s North Zone and West Zone. The Franklin County tiling footprint graphic is shown at Appendix A.

The Florida Baseline Specifications required the LiDAR data to be collected using an approved sensor with a maximum field of view (FOV) of 20° on either side of nadir, with GPS baseline distances limited to 20 miles, with maximum post spacing of 4 feet in unobscured areas for random point data, and with vertical root mean square error ($RMSE_z$) ≤ 0.30 ft and Fundamental Vertical Accuracy (FVA) ≤ 0.60 ft at the 95% confidence level in open terrain (bare-earth and low grass); this accuracy is equivalent to 1 ft contours in open terrain when tested in accordance with the National Map Accuracy Standard (NMAS). In other land cover categories (brush lands and low trees, forested areas fully covered by trees, and urban areas), the Florida Baseline Specifications required the LiDAR data’s $RMSE_z$ to be ≤ 0.61 ft with Supplemental Vertical Accuracy (SVA) and Consolidated Vertical Accuracy (CVA) ≤ 1.19 ft at the 95% confidence level; this accuracy is equivalent to 2 ft contours when tested in accordance with the NMAS. *Low confidence areas*, originally called *obscured vegetated areas*, are defined for areas where the vertical data may not meet the data accuracy requirements due to heavy vegetation.

The Florida Baseline Specifications also required the horizontal accuracy to meet or exceed 3.8 feet at the 95% confidence level, using $RMSE_r \times 1.7308$. This means that the horizontal (radial) RMSE ($RMSE_r$) must meet or exceed 2.20 ft. This is the horizontal accuracy required of maps compiled at a scale of 1:1,200 (1” = 100’) in accordance with the traditional National Map Accuracy Standard.

To meet and exceed these specifications for the nine new county LiDAR datasets, the PDS team established the following more-rigorous specifications for its LiDAR subcontractors:

- Instead of a 20° FOV on either side of nadir, the PDS team limited the FOV to 18°
- Instead of GPS baselines ≤ 20 miles, the PDS team limited baseline lengths to ≤ 20 km, except in one small isolated area where the baseline length was approximately 23 km (14 miles).
- Instead of 4 foot post spacing which yields an average of 0.67 points per m^2 , the PDS team chose 0.7 m point spacing and 50% sidelap that yields an average of 4 points per m^2 . Thus, the PDS team’s average point density is nearly 6 times higher than required by FDEM, greatly increasing the probability of LiDAR points penetrating through dense vegetation so as to minimize areas defined as *low confidence areas*. The PDS team defines *low confidence areas* as vegetated areas of $\frac{1}{2}$ acre or larger that are considered obscured to the extent that adequate vertical data cannot be clearly determined to accurately define the DTM. Such areas indicate where the vertical data may not meet the data accuracy requirements due to heavy vegetation.

The first deliverable is LiDAR mass points, delivered to LAS 1.1 specifications, including the following LAS classification codes:

- Class 1 = Unclassified, and used for all other features that do not fit into the Classes 2, 7, 9, or 12, including vegetation, buildings, etc.
- Class 2 = Ground, includes accurate LiDAR points in overlapping flight lines
- Class 7 = Noise, includes LiDAR points in overlapping flight lines
- Class 9 = Water, includes LiDAR points in overlapping flight lines



- Class 12 = Overlap, including areas of overlapping flight lines which have been deliberately removed from Class 1 because of their reduced accuracy.

Table 2 compares the LiDAR LAS classes specified by the FDEM and NOAA specifications.

Table 2. Comparison of FDEM and NOAA LAS Classes

FDEM LAS Classes	NOAA LAS Classes
Class 1 – Unclassified, including vegetation, buildings, bridges, piers	Class 1 – Unclassified
Class 2 – Ground points (used for contours)	Class 2 – Ground points (used for contours)
Class 7 – Noise	Class 9 – Water
Class 9 – Water	
Class 12 – Overlap points deliberately removed	

For each 500 square mile area within the nine new county datasets, a total of 120 “blind” QA/QC checkpoints were surveyed, totally unknown to (i.e., “blind” from) the LiDAR subcontractors. Each set of 120 QA/QC checkpoints had the goal to include 30 checkpoints in each of the following four land cover categories:

- Category 1 = bare-earth and low grass
- Category 2 = brush lands and low trees
- Category 3 = forested areas fully covered by trees
- Category 4 = urban areas

In a few cases, there were insufficient dispersed areas to acquire 30 QA/QC checkpoints for one or more land cover categories; when this occurred, Dewberry advised the surveyors to select additional QA/QC checkpoints for land cover categories that were predominant in the area and therefore more representative of the area being tested.

The following vertical accuracy guidelines were specified by the Florida Baseline Specifications:

- In category 1, the $RMSE_z$ must be ≤ 0.30 ft ($Accuracy_z \leq 0.60$ ft at the 95% confidence level); $Accuracy_z$ in Category 1 refers to Fundamental Vertical Accuracy (FVA) which defines how accurate the elevation data are when not complicated by asphalt or vegetation that may cause elevations to be either lower or higher than the bare earth terrain. This is equivalent to the accuracy expected of 1 ft contours in non-vegetated terrain.
- In category 2, the $RMSE_z$ must be ≤ 0.61 ft ($Accuracy_z \leq 1.19$ ft at the 95% confidence level); $Accuracy_z$ in Category 2 refers to Supplemental Vertical Accuracy (SVA) in brush lands and low trees and defines how accurate the elevation data are when complicated by such vegetation that frequently causes elevations to higher than the bare earth terrain. This is equivalent to the accuracy expected of 2 ft contours in such terrain.
- In category 3, the $RMSE_z$ must be ≤ 0.61 ft ($Accuracy_z \leq 1.19$ ft at the 95% confidence level); $Accuracy_z$ in Category 3 refers to Supplemental Vertical Accuracy (SVA) in forested areas fully covered by trees and defines how accurate the elevation data are when complicated by such



vegetation that frequently causes elevations to be higher than the bare earth terrain. This is equivalent to the accuracy expected of 2 ft contours in such terrain.

- In category 4, the $RMSE_z$ must be ≤ 0.61 ft ($Accuracy_z \leq 1.19$ ft at the 95% confidence level); $Accuracy_z$ in Category 4 refers to Supplemental Vertical Accuracy (SVA) in urban areas typically paved with asphalt and defines how accurate the elevation data are when complicated by asphalt that frequently causes elevations to be lower than the bare earth terrain. This is equivalent to the accuracy expected of 2 ft contours in such terrain.
- In all land cover categories combined, the $RMSE_z$ must be ≤ 0.61 ft ($Accuracy_z \leq 1.19$ ft at the 95% confidence level); $Accuracy_z$ in all categories combined refers to Consolidated Vertical Accuracy (CVA).
- The terms FVA, SVA and CVA are explained in Chapter 3, *Accuracy Standards & Guidelines*, of “Digital Elevation Model Technologies and Applications: The DEM Users Manual,” published by the American Society for Photogrammetry and Remote Sensing (ASPRS), January, 2007.

A second major deliverable consists of nine types of breaklines, produced in accordance with the PDS team’s Data Dictionary at Appendix C:

1. Coastal shoreline features
2. Single-line hydrographic features
3. Dual-line hydrographic features
4. Closed water body features
5. Road edge-of-pavement features
6. Bridge and overpass features
7. Soft breakline features
8. Island features
9. Low confidence areas

Another major deliverable includes both one-foot and two-foot contours, produced from the mass points and breaklines, certified to meet or exceed NSSDA standards for one-foot contours. Two-foot contours within obscured vegetated areas are not required to meet NSSDA standards. These contours were also produced in accordance with the PDS team’s Data Dictionary at Appendix C.

Table 3 is included below for ease in understanding the accuracy requirements when comparing the traditional National Map Accuracy Standard (NMAS) and the newer National Standard for Spatial Data Accuracy (NSSDA). This table is extracted from Table 13.2 of “Digital Elevation Model Technologies and Applications: The DEM Users Manual,” published in January, 2007 by ASPRS. The traditional NMAS uses Vertical Map Accuracy Standard (VMAS) to define vertical accuracy at the 90% confidence level, whereas the NSSDA uses $Accuracy_z$ to define vertical accuracy at the 95% confidence level. Both the VMAS and $Accuracy_z$ are computed with different multipliers for the very same $RMSE_z$ value which represents vertical accuracy at the 68% confidence level for each equivalent contour interval specified. The term $Accuracy_z$ (vertical accuracy at the 95% confidence level) is comparable to the terms described below as Fundamental Vertical Accuracy (FVA), Consolidated Vertical Accuracy (CVA) and Supplemental Vertical Accuracy (SVA) which also define vertical accuracy at the 95% confidence level. In open (non-vegetated) terrain, $Accuracy_z$ is exactly the same as FVA (both computed as $RMSE_z \times 1.9600$) because there is no logical justification for elevation errors to depart from a normal error



distribution. In vegetated areas, vertical accuracy at the 95% confidence level ($Accuracy_z$) can also be computed as $RMSE_z \times 1.9600$; however, because vertical errors do not always have a normal error distribution in vegetated terrain, alternative guidelines from the National Digital Elevation Program (NDEP) and American Society for Photogrammetry and Remote Sensing (ASPRS) allow the 95th percentile method to be used (as with the CVA and SVA) to report the vertical accuracy at the 95% confidence level in land cover categories other than open terrain.

Table 3. Comparison of NMAS/NSSDA Vertical Accuracy

NMAS Equivalent Contour Interval	NMAS VMAS (90 percent confidence level)	NSSDA $RMSE_z$ (68 percent confidence level)	NSSDA $Accuracy_z$ (95 percent confidence level)
1 ft	0.5 ft	0.30 ft or 9.25 cm	0.60 ft or 18.2 cm
2 ft	1.0 ft	0.61 ft or 18.5 cm	1.19 ft or 36.3 cm

The next major deliverable includes metadata compliant with the Federal Geographic Data Committee’s (FGDC) Content Standard for Spatial Metadata in an ArcCatalog-compatible XML format. Copies of all survey reports, including this Report of Specific Purpose LiDAR Survey, must be delivered in PDF format as attachments to the metadata.

The last major deliverable includes the Vertical Accuracy Report of Franklin County, based on independent comparison of the LiDAR data with the QA/QC checkpoints, surveyed and tested in accordance with guidelines of the National Standard for Spatial Data Accuracy (NSSDA), American Society for Photogrammetry and Remote Sensing (ASPRS), Federal Emergency Management Agency (FEMA), and National Digital Elevation Program (NDEP), and using the QA/QC checkpoints surveyed by PBS&J and listed at Appendix E.

Instead of delivering one vertical accuracy report, using 120 QA/QC checkpoints for each 500 square miles of the project area, separate reports are delivered for each county. Therefore, individual county vertical accuracy reports may be based on fewer than or more than 120 QA/QC checkpoints, depending on whether the area mapped in each county is smaller than or larger than 500 square miles. Regardless, the average density of QA/QC checkpoints remains the same on average for each countywide report.

Datums and Coordinates: North American Datum of 1983 (NAD 83)/HARN for horizontal coordinates and North American Vertical Datum of 1988 (NAVD 88) for vertical coordinates. All coordinates are Florida State Plane Coordinate System (SPCS) in U.S. Survey Feet. All counties listed are in the Florida SPCS North Zone, except for Levy County which is delivered in both Florida SPCS North and West Zones. Levy County is normally in the West Zone but the LiDAR data are also delivered in the North Zone for ease in merger with all Panhandle counties for SLOSH modeling of all counties from Escambia through Levy.

Appendix I to this report provides the Geodatabase structure for all digital vector deliverables in Franklin County.

Acronyms and Definitions

3DS Diversified Design & Drafting Services, Inc.
 Accuracy_r Horizontal (radial) accuracy at the 95% confidence level, defined by the NSSDA



Accuracy _z	Vertical accuracy at the 95% confidence level, defined by the NSSDA
ANA	Allen Nobles & Associates, Inc.
ASFPM	Association of State Floodplain Managers
ASPRS	American Society for Photogrammetry and Remote Sensing
CFM	Certified Floodplain Manager (ASFPM)
CMAS	Circular Map Accuracy Standard, defined by the NMAS
CP	Certified Photogrammetrist (ASPRS)
CVA	Consolidated Vertical Accuracy, defined by the NDEP and ASPRS
DEM	Digital Elevation Model (gridded DTM)
DTM	Digital Terrain Model (mass points and breaklines to map the bare earth terrain)
DSM	Digital Surface Model (top reflective surface, includes treetops and rooftops)
FDEM	Florida Division of Emergency Management
FEMA	Federal Emergency Management Agency
FGDC	Federal Geographic Data Committee
FOV	Field of View
FVA	Fundamental Vertical Accuracy, defined by the NDEP and ASPRS
GS	Geodetic Surveyor
GIS	Geographic Information System Surveyor
LAS	LiDAR data format as defined by ASPRS
LiDAR	Light Detection and Ranging
LMSI	Laser Mapping Specialists Inc.
MHHW	Mean Higher High Water
MHW	Mean High Water, defines official shoreline in Florida
MLLW	Mean Lower Low Water
MLW	Mean Low Water
MSL	Mean Sea Level
NAD 83	North American Datum of 1983
NAVD 88	North American Vertical Datum of 1988
NDEP	National Digital Elevation Program
NMAS	National Map Accuracy Standard
NOAA	National Oceanic and Atmospheric Administration
NSSDA	National Standard for Spatial Data Accuracy
NSRS	National Spatial Reference System
NWFWMD	Northwest Florida Water Management District
PDS	Program & Data Solutions, joint venture between PBS&J, Dewberry and URS Corp
PS	Photogrammetric Surveyor
PSM	Professional Surveyor and Mapper (Florida)
QA/QC	Quality Assurance/Quality Control
RMSE _h	Vertical Root Mean Square Error (RMSE) of ellipsoid heights
RMSE _r	Horizontal (radial) Root Mean Square Error (RMSE) computed from RMSE _x and RMSE _y
RMSE _z	Vertical Root Mean Square Error (RMSE) of orthometric heights
SLOSH	Sea, Lake, and Overland Surges from Hurricanes
SRWMD	Suwannee River Water Management District
SVA	Supplemental Vertical Accuracy, defined by the NDEP and ASPRS
TIN	Triangulated Irregular Network
VMAS	Vertical Map Accuracy Standard, defined by the NMAS



Ground Surveys and Dates

Past experience with control in the Florida Panhandle area indicated a need to improve the accuracy of the existing survey monuments. For the nine newly-mapped counties in the Florida Panhandle, including Franklin County, the PDS team established a geodetic control network to provide accurate and consistent horizontal and vertical control for LiDAR and photogrammetric mapping using GPS technology. The project consisted of a Primary and two Secondary control networks supporting the mapping of approximately 6,113 square miles located in Northwest Florida. PBS&J managed the overall ground survey effort including management of field survey subcontractors, Allen Nobles & Associates, Inc. (ANA) and Diversified Design & Drafting Services, Inc. (3DS), which performed control surveys and QA/QC checkpoint surveys used for independent accuracy testing, and executed a network adjustment of control points used throughout the Florida panhandle.

The Primary network stations (see Figure 1) were used as base stations supporting the airborne GPS data acquisition, and as a consistent control framework for the more densely spaced Secondary control networks, and all subsequent control surveying activity on the project. They were setup at 40 kilometer spacing per the 2 centimeter requirements for Primary Control stated in the NOS NGS-58. The Primary Control network consisted of 55 stations, including 10 Continuously Operating Reference Stations (CORS), 27 existing monuments from the National Spatial Reference System (NSRS) and 18 new monuments set so as to limit LiDAR GPS baseline lengths to 20 Km relative to GPS base stations on either side of stations spaced ≈ 40 Km apart. Third order differential leveling was used to establish elevations on 20 Primary network stations in specific areas where published vertical stations could not be occupied directly with GPS. A minimally constrained (free) Least Squares adjustment was run to verify the internal accuracy of the Primary network. After evaluating and removing any outliers, a final free adjustment was generated, consisting of 191 independent vectors. The input error estimates were scaled by a factor of 14.90 which resulted in a properly weighted adjustment with a variance factor of 1.0154, with no flagged residuals. A constrained (fixed) 3-D horizontal adjustment was run using the same input error estimates as were used in the free adjustment; the variance factor was 1.3712 and there were no flagged residuals. A constrained (fixed) 1-D vertical adjustment was run using the same input error estimates as were used in the free adjustment; Station BE3991 was fixed in latitude, longitude and orthometric height; the variance factor was 1.2866 and there were no flagged residuals.

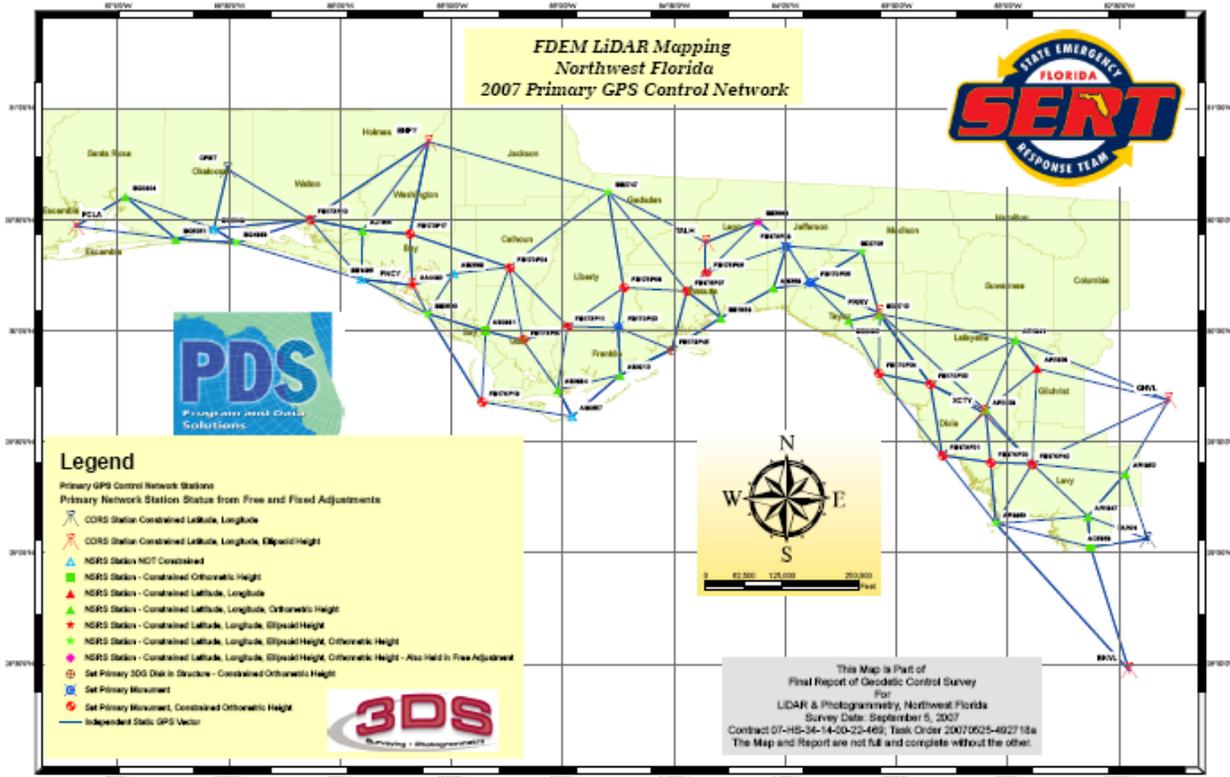


Figure 1. Primary Control Network

The Secondary network stations (see Figure 2) were used to support the measurement of both LiDAR and orthophoto QA/QC checkpoint sites. They were setup at 15 kilometer spacing per the 2 centimeter requirements for Secondary Control stated in NOS NGS-58.

The first Secondary Control network consisted of 4 stations in the Okaloosa County area. The second Secondary Control network consisted of all remaining mapping areas in the Florida Panhandle. The Secondary Control networks included a total of 80 control points, including 16 recovered NSRS monuments, 2 recovered DNR monuments, and 62 new monuments set for this network. A minimally constrained (free) Least Squares adjustment was run to verify the internal accuracy of the Secondary networks. After evaluating and removing any outliers, a final free adjustment was generated. This final free adjustment consisted of 254 independent vectors. The input error estimates were scaled by a factor of 6.234, which resulted in a properly weighted adjustment with a variance factor of 1.000; there were no flagged residuals. A constrained (fixed) 3-D horizontal adjustment was run using the same input error estimates as were used in the free adjustment; the variance factor was 1.6339 and there were six flagged residuals. A constrained (fixed) 1-D vertical adjustment was run using the same input error estimates as were used in the free adjustment; Station BE3991 was fixed in latitude, longitude and orthometric height; the variance factor was 1.2136 and there were no flagged residuals.

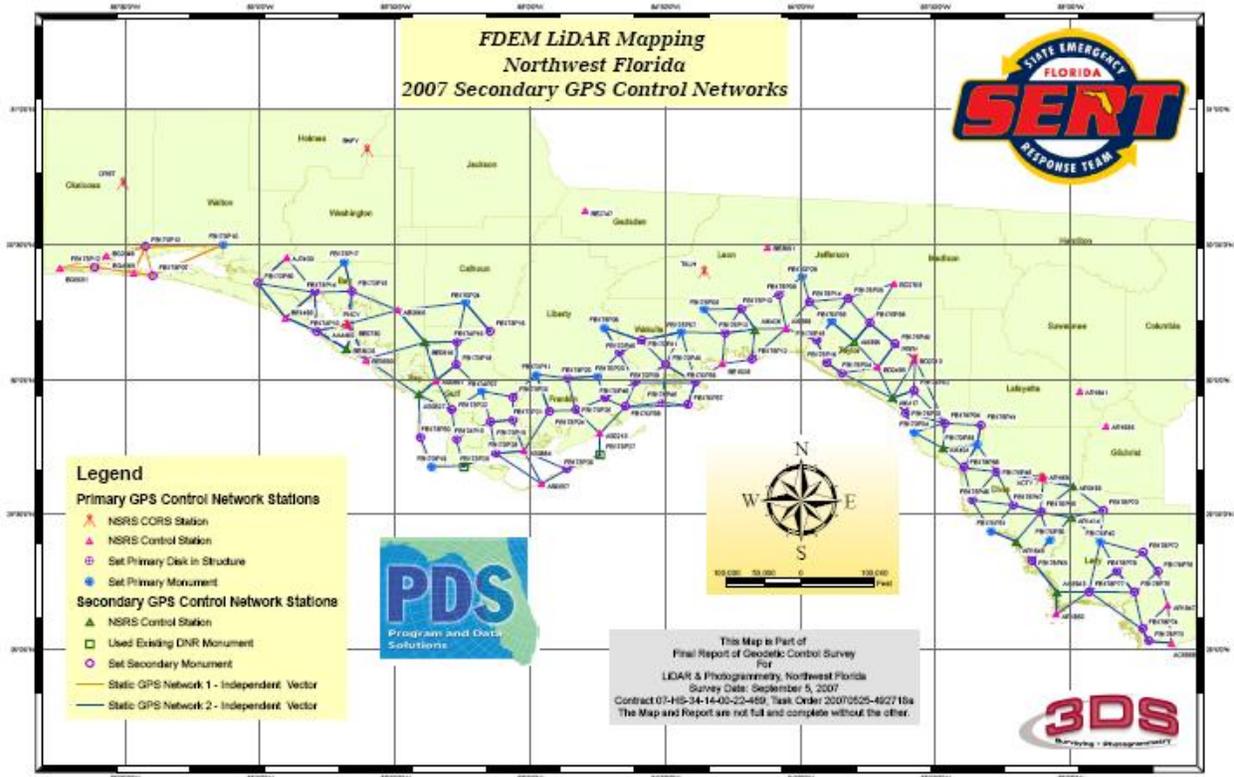


Figure 2. Secondary Control Networks

These GPS ground surveys were executed between May and September 2007. Full details are documented in 3DS's "Final Report of Geodetic Control Survey for LiDAR and Photogrammetry, Northwest Florida," dated March 13, 2008.

The QA/QC checkpoints used for this county are listed at Appendix E.

LiDAR Aerial Survey Areas and Dates

AeroMetric, Inc. and Terrapoint collected the LiDAR data for Franklin County during the summer of 2007.

LiDAR Processing Methodology

LiDAR processing reports from both AeroMetric and Terrapoint are included at Appendix D for the western and eastern portions of Franklin County, respectively.



LiDAR Vertical Accuracy Testing

URS performed the LiDAR vertical accuracy assessment for Franklin County in accordance with *ASPRS Guidelines, Vertical Accuracy Reporting for Lidar Data*, May 24, 2004, and Section 1.5 of the *Guidelines for Digital Elevation Data*, published by the National Digital Elevation Program (NDEP), May 10, 2004. These guidelines call for the mandatory determination of Fundamental Vertical Accuracy (FVA) and Consolidated Vertical Accuracy (CVA), and the optional determination of Supplemental Vertical Accuracy (SVA). NOAA’s accuracy specifications are compared with FDEM’s accuracy specifications at Table 1. NOAA’s checkpoint requirements are compared with FDEM’s checkpoint requirements at Table 4.

Table 4. Comparison of FDEM and NOAA Checkpoint Requirements

	FDEM Specifications	NOAA Specifications
Land cover categories tested by QA/QC checkpoints	Four land cover categories tested: <ol style="list-style-type: none"> 1. Open terrain; bare-earth, low grass 2. Brush lands and low trees 3. Forested areas 4. Urban, built-up areas 	Five land cover categories tested: <ol style="list-style-type: none"> 1. Open terrain; bare-earth, low grass 2. Weeds and crops 3. Scrub 4. Forested areas 5. Urban, built-up areas
Number of checkpoints per category	20 checkpoints, per category, for each 500 square mile area	20 checkpoints, per category, for each countywide dataset

The LiDAR dataset of Franklin County, redelivered in August of 2008, passed the accuracy testing by URS as documented at Appendices E and F.

Fundamental Vertical Accuracy (FVA) is determined with QA/QC checkpoints located only in open terrain (grass, dirt, sand, and rocks) where there is a high probability that the LiDAR sensor detected the bare-earth ground surface, and where errors are expected to follow a normal error distribution. With a normal error distribution, the FVA at the 95 percent confidence level is computed as the vertical root mean square error ($RMSE_z$) of the checkpoints x 1.9600. The FVA is the same as $Accuracy_z$ at the 95% confidence level (for open terrain), as specified in Appendix 3-A of the *National Standard for Spatial Data Accuracy*, FGDC-STD-007.3-1998, see <http://www.fgdc.gov/standards/projects/FGDC-standards-projects/accuracy/part3/chapter3>. For FDEM, including Franklin County, the FVA standard is .60 feet, corresponding to an $RMSE_z$ of 0.30 feet or 9.25 cm, the accuracy expected from 1-foot contours. For Franklin County, the FVA standard is 0.96 feet, corresponding to an $RMSE_z$ of 15 cm, better than the $RMSE_z$ of 18.5 cm expected from 2-foot contours. *In Franklin County, the $RMSE_z$ in open terrain equaled 0.27 ft compared with the 0.30 ft specification of FDEM; and the FVA computed using $RMSE_z \times 1.9600$ was equal to 0.53 ft, compared with the 0.60 ft specification of FDEM.*

Consolidated Vertical Accuracy (CVA) is determined with all checkpoints, representing open terrain and all other land cover categories combined. If errors follow a normal error distribution, the CVA can be computed by multiplying the consolidated $RMSE_z$ by 1.9600. However, because bare-earth elevation errors often vary based on the height and density of vegetation, a normal error distribution cannot be assumed, and $RMSE_z$ cannot necessarily be used to calculate the 95 percent confidence level. Instead, a nonparametric testing method, based on the 95th percentile, may be used to determine CVA at the 95 percent confidence level. NDEP guidelines state that errors larger than the 95th percentile should be documented in the quality control report and project metadata. For FDEM, the CVA specification for all



classes combined should be less than or equal to 1.19 feet; this same CVA specification was used by NOAA. *In Franklin County, the CVA computed using $RMSE_z \times 1.9600$ was equal to 0.74 ft, compared with the 1.19 ft specification of FDEM; and the CVA computed using the 95th percentile was equal to 0.61 ft. URS and Dewberry determined that the dataset passed the CVA standard.*

Supplemental Vertical Accuracy (SVA) is determined separately for each individual land cover category, recognizing that the LiDAR sensor and post-processing may not have mapped the bare-earth ground surface, and that errors may not follow a normal error distribution. SVA specifications are “target” values and not mandatory, recognizing that larger errors in some categories are offset by smaller errors in other land cover categories, so long as the overall mandatory CVA specification is satisfied. For each land cover category, the SVA at the 95 percent confidence level equals the 95th percentile error for all checkpoints in that particular land cover category. For FDEM’s specification, the SVA target is 1.19 feet for each category; this same SVA target specification was used by NOAA. *In Franklin County, the SVA tested as 0.53 ft in open terrain, bare earth and low grass; 0.55 ft in brush lands and low trees; 1.15 ft in forested areas; and 0.41 ft in urban, built-up areas, passing the FDEM SVA baseline target specifications in all land cover categories.*

The complete LiDAR Vertical Accuracy Report for Franklin County is at Appendix F.

LiDAR Horizontal Accuracy Testing

The LiDAR data was compiled to meet 3.8 feet horizontal accuracy at the 95% confidence level.

Whereas FDEM baseline specifications call for horizontal accuracy testing, traditional horizontal accuracy testing of LiDAR data is not cost effective for the following reasons:

- Paragraphs 3.2.2 and 3.2.3 of the National Standard for Spatial Data Accuracy (NSSDA) states: “Horizontal accuracy shall be tested by comparing the planimetric coordinates of well-defined points in the dataset with coordinates of the same points from an independent source of higher accuracy ... when a dataset, e.g., a gridded digital elevation dataset or elevation contour dataset does not contain well-defined points, label for vertical accuracy only.” Similarly, in Appendix 3-C of the NSSDA, paragraph 1 explains well-defined points as follows: “A well-defined point represents a feature for which the horizontal position is known to a high degree of accuracy and position with respect to the geodetic datum. For the purpose of accuracy testing, well-defined points must be easily visible or recoverable on the ground, on the independent source of higher accuracy, and on the product itself. Graphic contour data and digital hypsographic data may not contain well-defined points.”
- Paragraph 1.5.3.4 of the *Guidelines for Digital Elevation Data*, published in 2004 by the National Digital Elevation Program (NDEP), states: “The NDEP does not require independent testing of horizontal accuracy for elevation products. When the lack of distinct surface features makes horizontal accuracy testing of mass points, TINs, or DEMs difficult or impossible, the data producer should specify horizontal accuracy using the following statement: *Compiled to meet ___ (meters, feet) horizontal accuracy at 95 percent confidence level.*”
- Paragraph 1.2, Horizontal Accuracy, of *ASPRS Guidelines, Vertical Accuracy Reporting for Lidar Data*, published by the American Society for Photogrammetry and Remote Sensing (ASPRS) in 2004, further explains why it is difficult and impractical to test the



horizontal accuracy of LiDAR data, and explains why ASPRS does not require horizontal accuracy testing of LiDAR-derived elevation products.

- ASPRS has been actively seeking to develop cost-effective techniques to use LiDAR intensity imagery to test the horizontal accuracy of LiDAR data. As recently as May 1, 2008, at the annual conference of ASPRS, the most relevant technique for doing so was in a paper entitled “New Horizontal Accuracy Assessment Tools and Techniques for Lidar Data,” presented by the Ohio DOT. Whereas the technique had research value, it was neither practical nor affordable for use in horizontal accuracy testing of FDEM data.
- Appendix A of FDEM’s Baseline Specifications require 20 horizontal test points for every 500 square mile area of digital orthophotos to be produced, and Appendix B of FDEM’s Baseline Specifications requires 120 vertical test points for each 500 square mile area of LiDAR data to be produced. The PDS task orders included no funding for the more-expensive horizontal checkpoints that would be certain to appear on LiDAR intensity images as clearly-defined point features.
- In addition to LiDAR system factory calibration of horizontal and vertical accuracy, each of the PDS team’s LiDAR subcontractors have different techniques for field calibration checks used to determine if bore-sighting is still accurate. AeroMetric’s techniques used for Gulf and western Franklin counties, and Terrapoint’s techniques used for Wakulla and eastern Franklin counties, are explained in the LiDAR Processing Reports at Appendix D. Both reports indicated the horizontal accuracy tested well within FDEM’s 3.8 foot specification.

LiDAR Qualitative Assessments

In addition to vertical accuracy testing, URS also performed the LiDAR qualitative assessment.

An assessment of the vertical accuracy alone does not yield a complete picture with regard to the usability of LiDAR data for its intended purpose. It is very possible for a given set of LiDAR data to meet the accuracy requirements, yet still contain artifacts (non-ground points) in the bare-earth surface, or a lack of ground points in some areas that may render the data, in whole or in part, unsuitable for certain applications.

Based on the extremely large volume of elevation points generated, it is neither time efficient, cost effective, nor technically practical to produce a perfectly clean (artifact-free) bare-earth terrain surface. The purpose of the LiDAR Qualitative Assessment Report (see Appendix G) is to provide a qualitative analysis of the “cleanliness” of the bare-earth terrain surface for use in supporting riverine and coastal analysis, modeling, and mapping.

The main software programs used by URS in performing the bare-earth data cleanliness review include the following:

- *GeoCue*: a geospatial data/process management system especially suited to managing large LiDAR data sets
- *TerraModeler*: used for analysis and visualization
- *TerraScan*: runs inside of MicroStation; used for point classification and points file generation
- *GeoCue LAS EQC*: is also used for data analysis and edit



The following systematic approach was followed by URS in performing the cleanliness review and analysis:

- Uploaded data to the GeoCue data warehouse (enhanced data management)
 - LiDAR: cut the data into uniform tiles measuring 5,000 feet by 5,000 feet – using the State Plane tile index provided by FDEM
 - Imagery: Best available orthophotography was used to facilitate the data review. Additional LiDAR Orthos were created from the LiDAR intensity data and used for review purposes.
- Performed coverage/gap check to ensure proper coverage of the project area
 - Created a large post grid (~30 meters) from the bare-earth points, which was used to identify any holes or gaps in the data coverage.
- Performed tile-by-tile analyses
 - Using TerraScan and LAS EQC, checked for gross errors in profile mode (noise, high and low points)
 - Reviewed each tile for anomalies; identified problem areas with a polygon, annotated comment, and screenshot as needed for clarification and illustration. Used ortho imagery when necessary to aid in making final determinations with regards to:
 - Buildings left in the bare-earth points file
 - Vegetation left in the bare-earth points file
 - Water points left in the bare-earth points file
 - Proper definition of roads
 - Bridges and large box culverts removed from the bare-earth points file
 - Areas that may have been “shaved off” or “over-smoothed” during the auto-filtering process
- Prepared and sent the error reports to LiDAR firm for correction
- Reviewed revisions and comments from the LiDAR firm
- Prepared and submitted final reports to FDEM

Breakline Production Methodology

For western Franklin County, AeroMetric used GeoCue software to develop LiDAR stereo models so the LiDAR derived data could be viewed in 3-D stereo using DAT/EM System’s Summit Evolution softcopy photogrammetric software. Using LiDARgrammetry procedures with LiDAR intensity imagery, AeroMetric stereo-compiled the nine types of breaklines in accordance with the Data Dictionary at Appendix C. The LiDARgrammetry was performed under the direct supervision of an ASPRS Certified Photogrammetrist. The breaklines conform with data format requirements outlined by the FDEM Baseline Specifications.

For eastern Franklin County, Dewberry used GeoCue software to develop LiDAR stereo models so the LiDAR derived data could be viewed in 3-D stereo using Socet Set softcopy photogrammetric software. Using LiDARgrammetry procedures with LiDAR intensity imagery, Dewberry stereo-compiled the nine types of breaklines in accordance with the Data Dictionary at Appendix C. The LiDARgrammetry was performed under the direct supervision of an ASPRS Certified Photogrammetrist. The breaklines conform with data format requirements outlined by the FDEM Baseline Specifications.

Contour Production Methodology

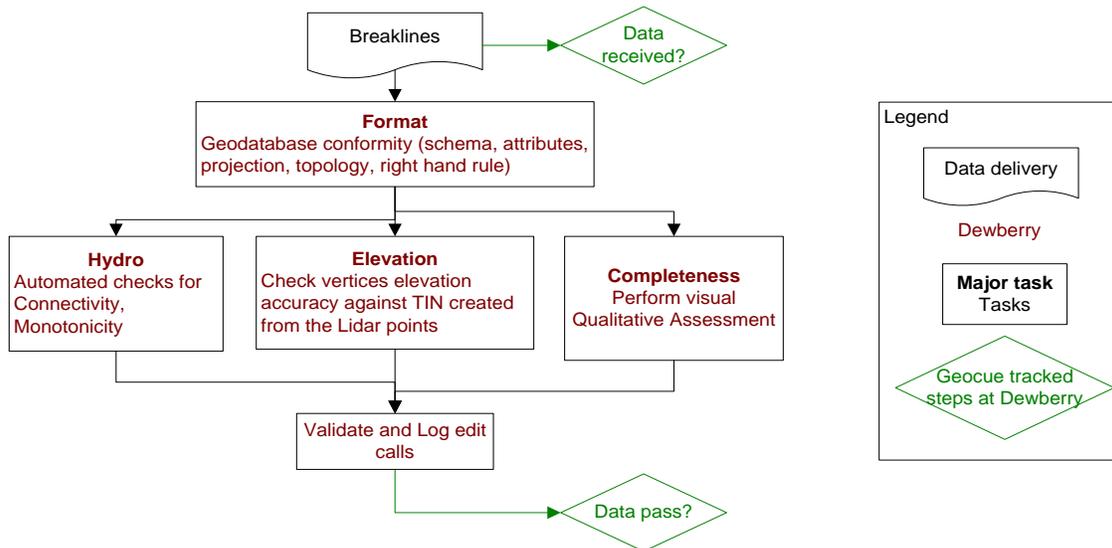


For western Franklin County, using proprietary procedures developed by AeroMetric, the 2-foot and 1-foot contours were compiled from the breaklines and LiDAR data in accordance with the Data Dictionary at Appendix C. The contours conform with data format requirements outlined by the FDEM Baseline Specifications.

For eastern Franklin County, using proprietary procedures developed by Dewberry, the 2-foot and 1-foot contours were compiled from the breaklines and LiDAR data in accordance with the Data Dictionary at Appendix C. The contours conform with data format requirements outlined by the FDEM Baseline Specifications.

Breakline Qualitative Assessments

Dewberry performed the breakline qualitative assessments. The following workflow diagram represents the steps taken by Dewberry to provide a thorough qualitative assessment of the breakline data.



In order to ensure a correct database format, Dewberry provided all subcontractors with geodatabase shells containing the required feature classes in the required format. Upon receipt of the data, Dewberry verified that the correct shell was used and validated the topology rules associated with it.

Feature Class	Rule	Feature Class
SOFTFEATURE	Must Not Intersect	
OVERPASS	Must Not Intersect	
ROADBREAKLINE	Must Not Intersect	
HYDROGRAPHIC...	Must Not Intersect	
SOFTFEATURE	Must Not Overlap With	ROADBREAKLINE
SOFTFEATURE	Must Not Overlap With	HYDROGRAPHICF
ROADBREAKLINE	Must Not Overlap With	HYDROGRAPHICF
SOFTFEATURE	Must Not Self-Intersect	
OVERPASS	Must Not Self-Intersect	
ROADBREAKLINE	Must Not Self-Intersect	
HYDROGRAPHIC...	Must Not Self-Intersect	

Figure 3. Breaklines topology rules



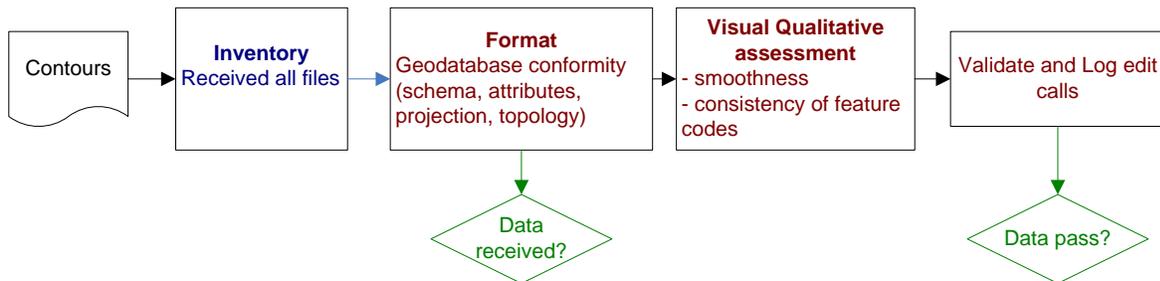
Then automated checks are applied on hydrofeatures to validate the 3D connectivity of the feature and the monotonicity of the hydrographic breaklines. Dewberry's major concern was that the hydrographic breaklines have a continuous flow downhill and that breaklines do not undulate. Error points are generated at each vertex not complying with the tested rules and these potential edit calls are then visually validated during the visual evaluation of the data. This step also helped validate that breakline vertices did not have excessive minimum or maximum elevations and that elevations are consistent with adjacent vertex elevations.

The next step is to compare the elevation of the breakline vertices against the elevation extracted from the TIN built from the LiDAR ground points, keeping in mind that a discrepancy is expected because of the hydro-enforcement applied to the breaklines and because of the interpolated imagery used to acquire the breaklines. A given tolerance is used to validate if the elevations do not differ too much from the LiDAR.

Dewberry's final check for the breaklines was to perform a full qualitative analysis of the breaklines. Dewberry compared the breaklines against LiDAR intensity images to ensure breaklines were captured in the required locations.

Contour Qualitative Assessments

Dewberry also performed the qualitative assessments of the contours using the following workflow.



Upon receipt of each delivery area, the first step performed by Dewberry was a series of data topology validations. Dewberry checked for the following instances in the data:

1. Contours must not overlap
2. Contours must not intersect
3. Contours must not have dangles (except at project boundary)
4. Contours must not self-overlap
5. Contours must not self-intersect

After the topology and geodatabase format validation was complete, Dewberry checked the elevation attribute of each contour to ensure NULL values are not included. Finally, Dewberry loaded the contour data plus the Lidar intensity images into ArcGIS and performed a full qualitative review of the contour data for smoothness and consistency of feature codes.

Appendix H summarizes Dewberry's qualitative assessments of the breaklines and contours, with graphic examples of what the breaklines and contours look like.

Deliverables



Except for the Report of Geodetic Control Survey for LiDAR and Photogrammetry, Northwest Florida, dated March 13, 2008, which was delivered separately and pertains to all deliverables in the Florida Panhandle, the deliverables listed at Table 5 are included on the external hard drive that accompanies this report.

Table 5. Summary of Deliverables

Copies	Deliverable Description	Format	Location
2	Report of Geodetic Control Survey for LiDAR and Photogrammetry, Northwest Florida, dated 3/13/2008	Hardcopy and pdf	Submitted separately
1	Data Dictionary	pdf	Appendix C
3	LiDAR Processing Report	Hardcopy and pdf	Appendix D
3	LiDAR Vertical Accuracy Report	Hardcopy and pdf	Appendix F
1	LiDAR Qualitative Assessment Report	pdf	Appendix G
1	Breakline/Contour Qualitative Assessment Report	pdf	Appendix H
1	Breaklines, Contours, Network-Adjusted Control Points, Vertical accuracy checkpoints, Tiling Footprint, Lidar ground masspoints	Geodatabase	Submitted separately

References

ASPRS, 2007, *Digital Elevation Model Technologies and Applications: The DEM Users Manual*, 2nd edition, American Society for Photogrammetry and Remote Sensing, Bethesda, MD.

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FDEM, 2006, Florida GIS, *Baseline Specifications for Orthophotography and LiDAR*, Appendix B, *Terrestrial LiDAR Specifications*, Florida Division of Emergency Management, Tallahassee, FL, October, 2006.

FEMA, 2004, Appendix A, *Guidance for Aerial Mapping and Surveying*, to “Guidelines and Specifications for Flood Hazard Mapping Partners,” Federal Emergency Management Agency, Washington, D.C.

FGCC, 1984, *Standards and Specifications for Geodetic Control Networks*, Federal Geodetic Control Committee, Silver Spring, MD, reprinted August 1993.

FGCC, 1988, *Geometric Geodetic Accuracy Standards and Specifications for Using GPS Relative Positioning Techniques*, Federal Geodetic Control Committee, Silver Spring, MD, reprinted with corrections, August, 1989.



FGDC, 1998a, *Geospatial Positioning Accuracy Standards, Part I: Reporting Methodology*, Federal Geographic Data Committee, c/o USGS, Reston, VA, http://www.fgdc.gov/standards/standards_publications/.

FGDC, 1998b, *Geospatial Positioning Accuracy Standards, Part 2, Standards for Geodetic Networks*, Federal Geographic Data Committee, c/o USGS, Reston, VA, http://www.fgdc.gov/standards/standards_publications/

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FGDC, 1998d, Content Standard for Digital Geospatial Metadata (CSDGM), Federal Geographic Data Committee, c/o USGS, Reston, VA, www.fgdc.gov/metadata/contstan.html.

NDEP, 2004, *Guidelines for Digital Elevation Data*, Version 1.0, National Digital Elevation Program, May 10, 2004, <http://www.ndep.gov/>

NOAA, 1997, *Guidelines for Establishing GPS-Derived Ellipsoid Heights (Standards: 2 cm and 5 cm)*, NOAA Technical Memorandum NOS NGS-58, November, 1997.

General Notes

This report is incomplete without the external hard drives of the LiDAR masspoints, breaklines, contours, and control. See the Geodatabase structure at Appendix I.

This digital mapping data complies with the Federal Emergency Management Agency (FEMA) "Guidelines and Specifications for Flood Hazard Mapping Partners," Appendix A: *Guidance for Aerial Mapping and Surveying*.

The LiDAR vertical accuracy report at Appendix F conforms with the National Standard for Spatial Data Accuracy (NSSDA).

The digital mapping data is certified to conform to Appendix B, *Terrestrial LiDAR Specifications*, of the "Florida Baseline Specifications for Orthophotography and LiDAR." This report is certified to conform with Chapter 61G17-6, Minimum Technical Standards, of the Florida Administrative Code, as pertains to a Specific Purpose LiDAR Survey.

THIS REPORT IS NOT VALID WITHOUT THE SIGNATURE AND RAISED SEAL OF A FLORIDA PROFESSIONAL SURVEYOR AND MAPPER IN RESPONSIBLE CHARGE.

Surveyor and Mapper in Responsible Charge:

David F. Maune, PhD, PSM, PS, GS, CP, CFM
Professional Surveyor and Mapper
License #LS6659



Signed: _____ Date: _____





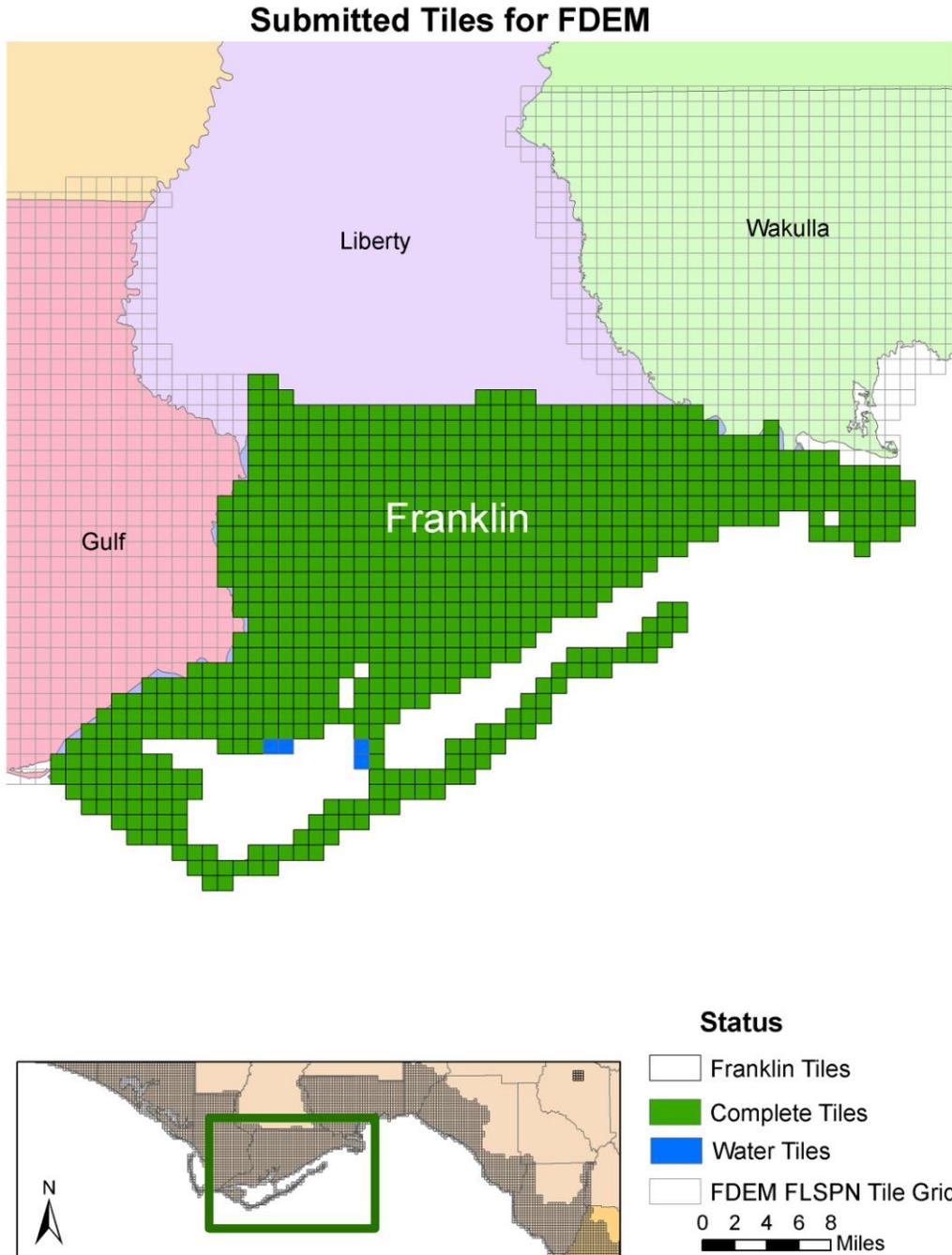
List of Appendices

- A. County Project Tiling Footprint
- B. County Geodetic Control Points
- C. Data Dictionary
- D. LiDAR Processing Report
- E. QA/QC Checkpoints and Associated Discrepancies
- F. LiDAR Vertical Accuracy Report
- G. LiDAR Qualitative Assessment Report
- H. Breakline/Contour Qualitative Assessment Report
- I. Geodatabase Structure



Appendix A: County Project Tiling Footprint: Franklin County

788 tiles were delivered for Franklin County: 784 Complete LAS tiles, 4 Water Tiles.





List of delivered complete tiles (784):

068773_N	064469_N	065016_N	066095_N	067699_N	066640_N
068774_N	064470_N	065017_N	066101_N	067700_N	066641_N
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068776_N	066078_N	065019_N	066103_N	067706_N	067165_N
068777_N	066080_N	065020_N	066104_N	067707_N	067166_N
068778_N	066081_N	065021_N	066105_N	067708_N	067167_N
068779_N	066082_N	065532_N	066626_N	067709_N	067181_N
068780_N	066083_N	065533_N	066627_N	067710_N	067182_N
068781_N	066084_N	065538_N	066628_N	067711_N	067183_N
068782_N	066085_N	065539_N	066629_N	067712_N	067184_N
068783_N	066087_N	065540_N	066630_N	067713_N	067702_N
068784_N	066094_N	065541_N	066631_N	067714_N	067703_N
068789_N	066096_N	065542_N	066632_N	067715_N	067704_N
068790_N	066097_N	065543_N	066633_N	067720_N	067705_N
068791_N	066098_N	065544_N	066634_N	065534_N	067716_N
068792_N	066615_N	064995_N	066635_N	065535_N	067717_N
068793_N	066616_N	064996_N	066636_N	065536_N	067718_N
068794_N	066617_N	064997_N	066637_N	065537_N	067719_N
068795_N	066618_N	064998_N	066642_N	064992_N	066612_N
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068811_N	067153_N	076871_N	067168_N	065560_N	068241_N
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064468_N	065015_N	066093_N	067698_N	066639_N	070950_N



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067730_N	069853_N	071487_N	071476_N	072562_N	073094_N
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068262_N	069877_N	067733_N	070951_N	075794_N	073644_N
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068270_N	070399_N	068247_N	074176_N	072014_N	073653_N
068271_N	070400_N	068248_N	074178_N	072015_N	073654_N
068272_N	070401_N	068249_N	074716_N	072016_N	074705_N
068273_N	070403_N	068263_N	074723_N	072017_N	074710_N
068274_N	070404_N	068264_N	074725_N	072018_N	074711_N
068275_N	070405_N	068265_N	074732_N	072019_N	074712_N
069310_N	070406_N	068266_N	075259_N	072020_N	073648_N
069311_N	070407_N	069317_N	072567_N	072021_N	073649_N
069312_N	070408_N	069318_N	074168_N	072022_N	074706_N
069313_N	070409_N	069319_N	074170_N	072027_N	074707_N
069314_N	070410_N	069320_N	074171_N	072028_N	074708_N
069315_N	070411_N	069333_N	074172_N	072029_N	074709_N
069316_N	070412_N	069334_N	074173_N	072030_N	072565_N
069321_N	070413_N	069335_N	074174_N	072031_N	072566_N
069322_N	070414_N	069336_N	074175_N	072032_N	074180_N
069323_N	068235_N	069857_N	074177_N	072033_N	074181_N
069324_N	068236_N	069858_N	074715_N	072039_N	074713_N
069325_N	068237_N	069859_N	074717_N	072560_N	074714_N
069326_N	068238_N	069860_N	074719_N	072561_N	074731_N
069327_N	068239_N	069873_N	074720_N	072571_N	075260_N
069328_N	069892_N	069874_N	074721_N	072579_N	075261_N
069329_N	075270_N	069875_N	074722_N	072580_N	075262_N
069330_N	075271_N	069876_N	074724_N	073091_N	075263_N
069331_N	071471_N	070394_N	075795_N	073092_N	072552_N
069332_N	071472_N	070395_N	075796_N	073097_N	072553_N



073117_N	073642_N	077948_N	076332_N	080105_N	080649_N
073118_N	073655_N	077964_N	076887_N	080106_N	080653_N
075255_N	073656_N	077966_N	076888_N	080107_N	080654_N
075256_N	073657_N	077943_N	075801_N	080115_N	080655_N
075257_N	073658_N	077944_N	075810_N	080116_N	080656_N
072023_N	075782_N	077945_N	076333_N	078481_N	076325_N
072024_N	075783_N	077946_N	076334_N	078483_N	076326_N
072025_N	075244_N	077960_N	076335_N	079021_N	076327_N
072026_N	075243_N	077961_N	076336_N	079022_N	076328_N
072040_N	075245_N	077962_N	076347_N	079023_N	076339_N
072568_N	075246_N	077963_N	076348_N	079025_N	076340_N
072569_N	075247_N	078485_N	076349_N	079027_N	077403_N
072570_N	075252_N	078486_N	076350_N	079039_N	077404_N
073101_N	075253_N	078487_N	076885_N	079041_N	077405_N
073102_N	075254_N	078488_N	077399_N	079563_N	077406_N
073103_N	075248_N	078502_N	077400_N	079564_N	077420_N
073104_N	075249_N	078503_N	077401_N	079565_N	079037_N
074184_N	075250_N	078504_N	077402_N	079566_N	079038_N
074185_N	075251_N	075809_N	077425_N	079576_N	081729_N
074186_N	077940_N	075811_N	077426_N	079577_N	081730_N
074187_N	077942_N	076321_N	077427_N	079578_N	080647_N
073638_N	077947_N	076322_N	078480_N	079579_N	080652_N
073639_N	077965_N	076323_N	078482_N	080117_N	079567_N
073640_N	077939_N	076324_N	079024_N	078484_N	076886_N
073641_N	077941_N	076329_N	079026_N	078500_N	074192_N
		076330_N	079040_N	078501_N	
		076331_N	080104_N	080648_N	

List of delivered Water Tiles (4):

- 076873_N
- 076874_N
- 076879_N
- 077419_N

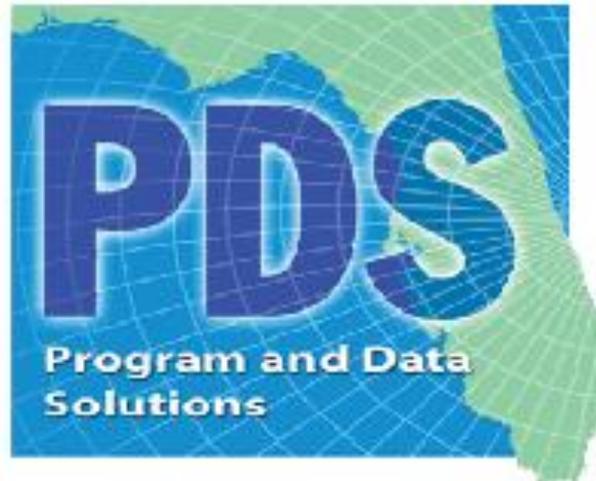


Appendix B: Franklin County Geodetic Control Points

Station	County	Longitude	Latitude	Height (meters)	Ellipsoid Height	Description
AS0213	Franklin	84 44 31.54609	29 48 1.35670	7.212	-19.936	RECOVERED NSRS STATION (SEE DATASHEET PID# AS0213)
AS0557	Franklin	84 57 26.07868	29 36 52.09268	4.231	-22.848	RECOVERED NSRS STATION (SEE DATASHEET PID# AS0557)
AS0884	Franklin	85 1 25.23954	29 44 9.74665	4.325	-22.843	RECOVERED NSRS STATION (SEE DATASHEET PID# AS0884)
AS0213	Franklin	84 44 31.54609	29 48 1.35670	7.212	-19.936	RECOVERED NSRS STATION (SEE DATASHEET PID# AS0213)
FB170P37	Franklin	84 25 5.26719	29 54 17.92362	1.063	-26.163	SET SECONDARY MONUMENT
FB170P38	Franklin	84 38 57.79874	29 53 50.88237	1.814	-25.403	SET SECONDARY MONUMENT
FB170P39	Franklin	84 36 37.19175	29 59 22.07699	5.109	-22.102	SET SECONDARY MONUMENT
FB170P46	Franklin	84 43 30.57505	29 55 51.88623	3.208	-24.076	SET SECONDARY MONUMENT
FB173P23	Franklin	84 51 41.50095	30 0 19.35428	8.852	-18.595	SET SECONDARY MONUMENT
FB173P24	Franklin	84 55 49.81956	29 53 1.17183	3.974	-23.331	SET SECONDARY MONUMENT
FB173P25	Franklin	84 49 55.61072	29 53 13.41874	3.846	-23.426	SET SECONDARY MONUMENT
FB173P26	Franklin	84 51 55.71863	29 40 4.64713	1.172	-25.909	SET SECONDARY MONUMENT
FB173P27	Franklin	84 44 32.45716	29 43 14.48330	2.14	-24.915	*RECOVERED DNR MONUMENT (DNR-R-126)
FB173P28	Franklin	85 7 38.13658	29 43 35.62574	4.676	-22.501	SET SECONDARY MONUMENT
FB170P23	Franklin	84 45 4.42239	30 0 45.68863	5.192	-22.172	SET PRIMARY MONUMENT
FB173P11	Franklin	84 58 43.31883	30 1 11.61493	8.06	-19.485	SET PRIMARY MONUMENT
FB178P45	Franklin	84 30 39.44604	29 54 55.94260	0.835	-26.343	SET PRIMARY DISK SEE ABOVE NOTE FOR FB178P45



Appendix C: Data Dictionary



LiDARgrammetry Data Dictionary & Stereo Compilation Rules

FDEM (Florida Department of Emergency Management)
January 25, 2008

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Horizontal and Vertical Datum

Horizontal datum shall be referenced to the appropriate Florida State Plane Coordinate System. The horizontal datum shall be North American Datum of 1983/HARN adjustment in US Survey Feet. The vertical datum shall be referenced to the North American Vertical Datum of 1988 (NAVD 88). Geoid03 shall be used to convert ellipsoidal heights to orthometric heights.

Coordinate System and Projection

All data shall be projected to the appropriate Florida State Plane Coordinate System Zone, Units in US Survey Feet.

Contour Topology Rules

The following contour topology rules have been incorporated into each geodatabase shell provided by PDS. The topology must be validated by each subcontractor prior to delivery to PDS. PDS shall further validate the topology before final submittal to FDEM.

Name: CONTOURS_Topology		Cluster Tolerance: 0.003			
		Maximum Generated Error Count: Undefined			
		State: Analyzed without errors			
Feature Class	Weight	XY Rank	Z Rank	Event Notification	
CONTOUR_1FT	5	1	1	No	
CONTOUR_2FT	5	1	1	No	

Topology Rules

Name	Rule Type	Trigger Event	Origin <i>(FeatureClass::Subtype)</i>	Destination <i>(FeatureClass::Subtype)</i>
Must not intersect	The rule is a line-no intersection rule	No	CONTOUR_1FT::All	CONTOUR_1FT::All
Must not intersect	The rule is a line-no intersection rule	No	CONTOUR_2FT::All	CONTOUR_2FT::All
Must not self-intersect	The rule is a line-no self intersect rule	No	CONTOUR_2FT::All	CONTOUR_2FT::All
Must not self-intersect	The rule is a line-no self intersect rule	No	CONTOUR_1FT::All	CONTOUR_1FT::All

Breakline Topology Rules

The following breakline topology rules have been incorporated into each geodatabase shell provided by PDS. The topology must be validated by each subcontractor prior to delivery to PDS. PDS shall further validate the topology before final submittal to FDEM.

Name: BREAKLINES_Topology		Cluster Tolerance: 0.003		
		Maximum Generated Error Count: Undefined		
		State: Analyzed without errors		
Feature Class	Weight	XY Rank	Z Rank	Event Notification
COASTALSHORELINE	5	1	1	No
HYDROGRAPHICFEATURE	5	1	1	No
OVERPASS	5	1	1	No
ROADBREAKLINE	5	1	1	No
SOFTFEATURE	5	1	1	No

Topology Rules

Name	Rule Type	Trigger Event	Origin <i>(FeatureClass::Subtype)</i>	Destination <i>(FeatureClass::Subtype)</i>
Must not intersect	The rule is a line-no intersection rule	No	SOFTFEATURE::All	SOFTFEATURE::All
Must not intersect	The rule is a line-no intersection rule	No	OVERPASS::All	OVERPASS::All
Must not intersect	The rule is a line-no intersection rule	No	ROADBREAKLINE::All	ROADBREAKLINE::All
Must not intersect	The rule is a line-no intersection rule	No	HYDROGRAPHICFEATURE::All	HYDROGRAPHICFEATURE::All
Must not intersect	The rule is a line-no intersection rule	No	COASTALSHORELINE::All	COASTALSHORELINE::All
Must not overlap	The rule is a line-no overlap line rule	No	SOFTFEATURE::All	ROADBREAKLINE::All
Must not overlap	The rule is a line-no overlap line rule	No	SOFTFEATURE::All	HYDROGRAPHICFEATURE::All
Must not overlap	The rule is a line-no overlap line rule	No	SOFTFEATURE::All	COASTALSHORELINE::All
Must not overlap	The rule is a line-no overlap line rule	No	ROADBREAKLINE::All	HYDROGRAPHICFEATURE::All
Must not overlap	The rule is a line-no overlap line rule	No	ROADBREAKLINE::All	COASTALSHORELINE::All
Must not overlap	The rule is a line-no overlap line rule	No	HYDROGRAPHICFEATURE::All	COASTALSHORELINE::All
Must not self-intersect	The rule is a line-no self intersect rule	No	SOFTFEATURE::All	SOFTFEATURE::All
Must not self-intersect	The rule is a line-no self intersect rule	No	OVERPASS::All	OVERPASS::All
Must not self-intersect	The rule is a line-no self intersect rule	No	ROADBREAKLINE::All	ROADBREAKLINE::All
Must not self-intersect	The rule is a line-no self intersect rule	No	HYDROGRAPHICFEATURE::All	HYDROGRAPHICFEATURE::All
Must not self-intersect	The rule is a line-no self intersect rule	No	COASTALSHORELINE::All	COASTALSHORELINE::All

Coastal Shoreline

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: COASTALSHORELINE
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Polygon
Annotation Subclass: None

Description

This polygon feature class will outline the land / water interface at the time of LiDAR acquisition.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
SHAPE_AREA	Double	Yes			0	0		Calculated by PDS
TYPE	Long Integer	No	1	Coast	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Coastal Shoreline	The coastal breakline will delineate the land water interface using LiDAR data as reference. In flight line boundary areas with tidal variation the coastal shoreline may require some feathering or edge matching to ensure a smooth transition. Orthophotography will not be use to delineate this shoreline.	<p>The feature shall be extracted at the apparent land/water interface, as determined by the LiDAR intensity data, to the extent of the tile boundaries. For the polygon closure vertices and segments, null values or a value of 0 are acceptable since this is not an actual shoreline. The digital orthophotography is not a suitable source for capturing this feature. Efforts should be taken to gradually feather the difference between tidal conditions of neighboring flights. Stair-stepping of the breakline feature will not be allowed.</p> <p>If it can be reasonably determined where the edge of water most probably falls, beneath the dock or pier, then the edge of water will be collected at the elevation of the water</p>

where it can be directly measured. If there is a clearly-indicated headwall or bulkhead adjacent to the dock or pier and it is evident that the waterline is most probably adjacent to the headwall or bulkhead, then the water line will follow the headwall or bulkhead at the elevation of the water where it can be directly measured. If there is no clear indication of the location of the water's edge beneath the dock or pier, then the edge of water will follow the outer edge of the dock or pier as it is adjacent to the water, at the measured elevation of the water.

Breaklines shall snap and merge seamlessly with linear hydrographic features.

Linear Hydrographic Features

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: HYDROGRAPHICFEATURE
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Polyline
Annotation Subclass: None

Description

This polyline feature class will depict linear hydrographic features with a length of 0.5 miles or longer as breaklines.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
TYPE	Long Integer	No	1	HydroL	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Single Line Feature	Linear hydrographic features such as streams, shorelines, canals, swales, embankments, etc. with an average width less than or equal to 8 feet. . In the case of embankments, if the feature forms a natural dual line channel, then capture it consistent with the capture rules. Other embankments fall into the soft breakline feature class	Capture linear hydro features as single breaklines. Average width shall be 8 feet or less to show as single line. Each vertex placed should maintain vertical integrity.
2	Dual Line Feature	Linear hydrographic features such as streams, shorelines, canals, swales, etc. with an average width greater than 8 feet. In the case of embankments, if the feature forms a natural dual line channel, then capture it consistent with the capture rules. Other embankments fall into the soft breakline feature class.	Capture features showing dual line (one on each side of the feature). Average width shall be great than 8 feet to show as a double line. Each vertex placed should maintain vertical integrity and data is not required to show “closed polygon”. These instructions are only for docks or piers that follow the coastline or water’s edge, not for docks or piers that

extend perpendicular from the land into the water. If it can be reasonably determined where the edge of water most probably falls, beneath the dock or pier, then the edge of water will be collected at the elevation of the water where it can be directly measured. If there is a clearly-indicated headwall or bulkhead adjacent to the dock or pier and it is evident that the waterline is most probably adjacent to the headwall or bulkhead, then the water line will follow the headwall or bulkhead at the elevation of the water where it can be directly measured. If there is no clear indication of the location of the water's edge beneath the dock or pier, then the edge of water will follow the outer edge of the dock or pier as it is adjacent to the water, at the measured elevation of the water.

Note: Carry through bridges for all linear hydrographic features.

Closed Water Body Features

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: WATERBODY
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Polygon
Annotation Subclass: None

Description

This polygon feature class will depict closed water body features and will have the associated water elevation available as an attribute.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
SHAPE_AREA	Double	Yes			0	0		Calculated by PDS
WATERBODY_ELEVATION_MS	Double	Yes			0	0		Assigned by PDS
TYPE	Long Integer	No	1	HydroP	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Water Body	<p>Land/Water boundaries of constant elevation water bodies such as lakes, reservoirs, ponds, etc. Features shall be defined as closed polygons and contain an elevation value that reflects the best estimate of the water elevation at the time of data capture. Water body features will be captured for features one-half acres in size or greater.</p> <p>“Donuts” will exist where there are islands within a closed water body feature.</p>	<p>Water bodies shall be captured as closed polygons with the water feature to the right. <u>The compiler shall take care to ensure that the z-value remains consistent for all vertices placed on the water body.</u> The field “WATERBODY_ELEVATION_MS” shall be automatically computed from the z-value of the vertices.</p> <p>An Island within a Closed Water Body Feature will also have a “donut polygon” compiled in addition to an Island polygon.</p> <p>These instructions are only for docks or piers that follow</p>

the coastline or water's edge, not for docks or piers that extend perpendicular from the land into the water. If it can be reasonably determined where the edge of water most probably falls, beneath the dock or pier, then the edge of water will be collected at the elevation of the water where it can be directly measured. If there is a clearly-indicated headwall or bulkhead adjacent to the dock or pier and it is evident that the waterline is most probably adjacent to the headwall or bulkhead, then the water line will follow the headwall or bulkhead at the elevation of the water where it can be directly measured. If there is no clear indication of the location of the water's edge beneath the dock or pier, then the edge of water will follow the outer edge of the dock or pier as it is adjacent to the water, at the measured elevation of the water.

Road Features

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: ROADBREAKLINE
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Polyline
Annotation Subclass: None

Description

This polyline feature class will depict apparent edge or road pavement as breaklines but will not include bridges or overpasses.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
TYPE	Long Integer	No	1	Road	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Edge of Pavement	Capture edge of pavement (non-paved or compact surfaces as open to compiler interpretability) on both sides of the road. Runways are not to be included.	DO NOT INCLUDE Bridges or Overpasses within this feature type. Capture apparent edge of pavement (including paved shoulders). Each vertex placed should maintain vertical integrity and data is not required to show "closed polygon". Box culverts should be continued as edge of pavement unless a clear guardrail system is in place; in that case, feature should be shown as bridge / overpass.

Bridge and Overpass Features

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: OVERPASS
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Polyline
Annotation Subclass: None

Description

This polyline feature class will depict bridges and overpasses as separate entities from the edge of pavement feature class.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
TYPE	Long Integer	No	1	Bridge	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Bridge Overpass	Feature should show edge of bridge or overpass.	Capture apparent edge of pavement on bridges or overpasses. Do not capture guard rails or non-drivable surfaces such as sidewalks. Capture edge of drivable pavement only. Each vertex placed should maintain vertical integrity and data is not required to show “closed polygon”. Box culverts should be captured in this feature class if a clear guardrail system is in place; otherwise, show as edge-of-pavement.

Soft Features

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: SOFTFEATURE
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Polyline
Annotation Subclass: None

Description

This polyline feature class will depict soft changes in the terrain to support better hydrological modeling of the LiDAR data and sub-sequent contours.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
TYPE	Long Integer	No	1	Soft	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Soft Breakline	<p>Supplemental breaklines where LiDAR mass points are not sufficient to create a hydrologically correct DTM. Soft features shall include ridges, valleys, top of banks, etc.</p> <p>Soft features may also include natural Embankments that act as small ponding areas. Top of Banks can also be included in the soft breakline class so long as it does not define the edge of a water feature.</p>	<p>Capture breaklines to depict soft changes in the elevation. If the elevation changes are easily visible, go light on the breakline capture. Each vertex placed should maintain vertical integrity.</p>

Island Features

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: ISLAND
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Polygon
Annotation Subclass: None

Description

This polygon feature class will depict natural and man-made islands as closed polygons.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
SHAPE_AREA	Double	Yes			0	0		Calculated by PDS
TYPE	Long Integer	No	1	Island	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Island	<p>Apparent boundary of natural or man-made island feature captured with a constant elevation.</p> <p>Island features will be captured for features one-half acres in size or greater.</p>	<p>Island shall take precedence over Coastal Shore Line Features. Islands shall be captured as closed polygons with the land feature to the right. The compiler shall take care to ensure that the z-value remains consistent for all vertices placed around the island.</p> <p>These instructions are only for docks or piers that follow the coastline or water's edge, not for docks or piers that extend perpendicular from the land into the water. If it can be reasonably determined where the edge of water most probably falls, beneath the dock or pier, then the edge of water will be collected at the elevation of the water where it can be directly measured. If there is a clearly-indicated</p>

headwall or bulkhead adjacent to the dock or pier and it is evident that the waterline is most probably adjacent to the headwall or bulkhead, then the water line will follow the headwall or bulkhead at the elevation of the water where it can be directly measured. If there is no clear indication of the location of the water's edge beneath the dock or pier, then the edge of water will follow the outer edge of the dock or pier as it is adjacent to the water, at the measured elevation of the water.

Low Confidence Areas

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: CONFIDENCE
Contains Z Values: No
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Polygon
Annotation Subclass: None

Description

This polygon feature class will depict areas where the ground is obscured by dense vegetation meaning that the resultant contours may not meet the required accuracy specifications.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
SHAPE_AREA	Double	Yes			0	0		Calculated by PDS
TYPE	Long Integer	No	1	Obscure	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Low Confidence Area	Apparent boundary of vegetated areas that are considered obscured to the extent that adequate vertical data cannot be clearly determined to accurately define the DTM. These features are for reference only to indicate areas where the vertical data may not meet the data accuracy requirements due to heavy vegetation.	Capture as closed polygon with the obscured area to the right of the line. Compiler does not need to worry about z-values of vertices; feature class will be 2-D only.

Note: Area must be ½ acre or larger. Only outline areas where you are not sure about vegetative penetration of the LiDAR data. This is not the same as a traditional obscured area.

Masspoints

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: MASSPOINT
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Point
Annotation Subclass: None

Description

This feature class depicts masspoints as determined by the LiDAR ground points (LAS Class 2).

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
TYPE	Long Integer	No	1	Masspoint	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Masspoint	Only the bare earth classification (Class 2) shall be loaded into the MASSPOINT feature class.	None. Data should be loaded from LAS Class 2 (Ground)

1 Foot Contours

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: CONTOUR_1FT
Contains Z Values: No
Z Resolution: N/A
Z Tolerance: N/A

Feature Type: Polyline
Annotation Subclass: None

Description

This polyline feature class will depict 1' contours modeled from the LiDAR ground points and the supplemental breaklines.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
CONTOUR_TYPE_DESC	Long Integer	No		dCONTOURTYPE	0	0	50	Assigned by PDS
CONTOUR_ELEVATION_MS	Double	No			0	0		Calculated by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Intermediate	A contour line drawn between index contours. Depending on the contour interval there are three or four intermediate contours between the index contours. Supplementary contours are used to portray important relief features that would otherwise not be shown by the index and intermediate contours (basic contours). They are normally added only in areas of low relief, but they may also be used in rugged terrain to emphasize features. Supplementary contours are shown as screened lines so that they are distinguishable from the basic contours, yet not	They are normally continuous throughout a map, but may be dropped or joined with an index contour where the slope is steep and where there is insufficient space to show all of the intermediate lines. These dotted lines are placed in areas where elevation change is minimal. If there is a lot of space between Index and Intermediate Contours (as happens where the land is relatively flat), these lines are added to indicate that there are elevation measurements, even if they are few and far between.
2	Supplementary		If the horizontal distance between two adjacent contours is

		unduly prominent on the published map.	larger than 1” at map scale (100’), then add appropriate supplemental contours from the 1FT_CONTOUR feature class. Supplemental contours do not have to be continuous but should have a minimum length of 200’.
3	Depression	Depression contours are closed contours that surround a basin or sink. They are shown by right-angle ticks placed on the contour lines, pointed inward (down slope). Fill contours are a special type of depression contours, used to indicate an area that has been filled to support a road or railway grade.	Use when appropriate.
4	Index	Index Contours are to be placed at every 5 th contour interval (1, 5, 10, etc...)	No special rules
5	Intermediate Low Confidence	Intermediate contours (Code 1) that are located in low confidence area should be cut to the low confidence boundary and should be reclassified to this code.	No special collection rules are necessary as this is a geo-processing task.
6	Supplementary Low Confidence	Supplementary contours (Code 2) that are located in low confidence area should be cut to the low confidence boundary and should be reclassified to this code.	No special collection rules are necessary as this is a geo-processing task.
7	Depression Low Confidence	Depression contours (Code 3) that are located in low confidence area should be cut to the low confidence boundary and should be reclassified to this code.	No special collection rules are necessary as this is a geo-processing task.
8	Index Low Confidence	Index contours (Code 4) that are located in low confidence area should be cut to the low confidence boundary and should be reclassified to this code.	No special collection rules are necessary as this is a geo-processing task.

2 Foot Contours

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: CONTOUR_2FT
Contains Z Values: No
Z Resolution: N/A
Z Tolerance: N/A

Feature Type: Polyline
Annotation Subclass: None

Description

This polyline feature class will depict 1' contours modeled from the LiDAR ground points and the supplemental breaklines.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
CONTOUR_TYPE_DESC	Long Integer	No		dCONTOURTYPE	0	0	50	Assigned by PDS
CONTOUR_ELEVATION_MS	Double	No			0	0		Calculated by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Intermediate	A contour line drawn between index contours. Depending on the contour interval there are three or four intermediate contours between the index contours.	They are normally continuous throughout a map, but may be dropped or joined with an index contour where the slope is steep and where there is insufficient space to show all of the intermediate lines.
2	Supplementary	Supplementary contours are used to portray important relief features that would otherwise not be shown by the index and intermediate contours (basic contours). They are normally added only in areas of low relief, but they may also be used in rugged terrain to emphasize features. Supplementary contours are shown as screened lines so that they are	These dotted lines are placed in areas where elevation change is minimal. If there is a lot of space between Index and Intermediate Contours (as happens where the land is relatively flat), these lines are added to indicate that there <i>are</i> elevation measurements, even if they are few and far between.

		distinguishable from the basic contours, yet not unduly prominent on the published map.		If the horizontal distance between two adjacent contours is larger than 1" at map scale (100'), then add appropriate supplemental contours from the 1FT_CONTOUR feature class. Supplemental contours do not have to be continuous but should have a minimum length of 200'.
3	Depression	Depression contours are closed contours that surround a basin or sink. They are shown by right-angle ticks placed on the contour lines, pointed inward (down slope). Fill contours are a special type of depression contours, used to indicate an area that has been filled to support a road or railway grade.		Use when appropriate.
4	Index	Index Contours are to be placed at every 5 th contour interval (1, 5, 10, etc...)		No special rules
5	Intermediate Low Confidence	Intermediate contours (Code 1) that are located in low confidence area should be cut to the low confidence boundary and should be reclassified to this code.		No special collection rules are necessary as this is a geo-processing task.
6	Supplementary Low Confidence	Supplementary contours (Code 2) that are located in low confidence area should be cut to the low confidence boundary and should be reclassified to this code.		No special collection rules are necessary as this is a geo-processing task.
7	Depression Low Confidence	Depression contours (Code 3) that are located in low confidence area should be cut to the low confidence boundary and should be reclassified to this code.		No special collection rules are necessary as this is a geo-processing task.
8	Index Low Confidence	Index contours (Code 4) that are located in low confidence area should be cut to the low confidence boundary and should be reclassified to this code.		No special collection rules are necessary as this is a geo-processing task.

Ground Control

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: GROUNDCONTROL
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Point
Annotation Subclass: None

Description

This feature class depicts the points used in the acquisition and calibration of the LiDAR and aerial photography collected by Aero-Metric, Sanborn and Terrapoint.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
TYPE	Long Integer	No	1	Control	0	0		Assigned by PDS
POINTID	String	Yes					12	Assigned by PDS
X_COORD	Double	Yes			0	0		Assigned by PDS
Y_COORD	Double	Yes			0	0		Assigned by PDS
Z_COORD	Double	Yes			0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Control Point	Primary or Secondary PDS control points used for either base station operations or in the calibration and adjustment of the control.	None.

Vertical Accuracy Test Points

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: VERTACCTESTPTS
Contains Z Values: Yes
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Point
Annotation Subclass: None

Description

This feature class depicts the points used by PDS to test the vertical accuracy of the data produced.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
POINTID	String	Yes					12	Assigned by PDS
X_COORD	Double	Yes			0	0		Assigned by PDS
Y_COORD	Double	Yes			0	0		Assigned by PDS
Z_COORD	Double	Yes			0	0		Assigned by PDS
LANDCOVER	Long Integer	No	1	dLANDCOVERTYPE	0	0		Assigned by PDS

Feature Definition

Code	Description	Definition	Capture Rules
1	Bare-Earth and Low Grass	None.	None.
2	Brush Lands and Low Trees	None.	None.
3	Forested Areas Fully Covered by Trees	None.	None.
4	Urban Areas	None.	None.

Footprint (Tile Boundaries)

Feature Dataset: TOPOGRAPHIC
Contains M Values: No
XY Resolution: Accept Default Setting
XY Tolerance: 0.003

Feature Class: FOOTPRINT
Contains Z Values: No
Z Resolution: Accept Default Setting
Z Tolerance: 0.001

Feature Type: Polygon
Annotation Subclass: None

Description

This polygon feature class includes the Florida 5,000' x 5,000' tiles for each countywide geodatabase produced.

Table Definition

Field Name	Data Type	Allow Null Values	Default Value	Domain	Precision	Scale	Length	Responsibility
OBJECTID	Object ID							Assigned by Software
SHAPE	Geometry							Assigned by Software
DATESTAMP_DT	Date	Yes			0	0	8	Assigned by PDS
SHAPE_LENGTH	Double	Yes			0	0		Calculated by PDS
SHAPE_AREA	Double	Yes			0	0		Calculated by PDS
CELLNUM	String	No			0	0	8	Assigned by PDS

Contact Information

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Appendix D1: AeroMetric LiDAR Processing Report

FLORIDA DIVISION OF EMERGENCY MANAGEMENT

GULF and western FRANKLIN COUNTIES, FL

LiDAR Acquisition July, 2007

LiDAR Processing Report

Prepared by:

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EXECUTIVE SUMMARY

AERO-METRIC, INC. acquired accurate Light Detection and Ranging (LiDAR) data for an area covering Gulf and western Franklin counties, Florida. Using AERO-METRIC's Optech 3100ea LiDAR system, data was collected at 1000 meters above ground level along 333 pre-planned flight lines at a pulse rate of 100,000 points per second. Airborne GPS and IMU trajectories for the LiDAR sensor were also acquired during the time of flight.

LiDAR data acquisition surveys were completed for the project site area, under a surveying and mapping contract entered into on July 11th, 2007 between Dewberry & Davis LLC and AERO-METRIC, INC.

The information maintains all standards published by the Florida Baseline Specifications for Orthophotography and LiDAR, dated October 17, 2006 and Federal Emergency Management Agency's (FEMA) Guidelines and Specifications for Flood Hazard Mapping Partners, Appendix A: Guidance for Aerial Mapping and Surveying, April 2003.

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Appendix 1 Flight Logs

Appendix 2 ABGPS Separation Graphs

Appendix 3 IMU Sensor Error Graphs

1 INTRODUCTION

This report contains a summary of the LiDAR data acquisition and processing for Gulf and western Franklin Counties, Florida.

1.1 Contact Info

Questions regarding the technical aspects of this report should be addressed to:

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1.2 Purpose

The LiDAR acquisition, bare-earth data set, breaklines, and contours were performed to develop a highly detailed ground surface dataset for use by the Florida Division of Emergency Management (FDEM).

1.3 Project Location

This project covered the entire Gulf county and the western portion of Franklin county, Florida as defined by the USGS DLG county boundary polygon.

1.4 Time Period

LiDAR data acquisition and Airborne GPS control surveys were completed between July 9th and July 22nd, 2007. A total of 22 flight missions were required to cover the project area. See page 10 for a sketch of the acquisition missions and Appendix 1 for each flight log. Ground check point GPS rapid static surveys were completed between June 21st and June 23rd, 2007.

1.5 Project Scope

AERO-METRIC, INC. acquired accurate Light Detection and Ranging (LiDAR) data for an area covering Gulf and western Franklin counties, Florida. Using AERO-METRIC's Optech 3100ea LiDAR system, data was collected at 1000 meters above ground level along 333 pre-planned flight lines at a pulse rate of 100,000 points per second. Airborne GPS and IMU trajectories for the LiDAR sensor were also acquired during the time of flight.

AERO-METRIC, Inc also collected 165 ground check points using Rapid Static GPS techniques. These check points were used to verify the processed LiDAR data.

The information maintains all standards published by the Florida Baseline Specifications for Orthophotography and LiDAR, dated October 17, 2006 and Federal Emergency Management Agency's (FEMA) Guidelines and Specifications for Flood Hazard Mapping Partners, Appendix A: Guidance for Aerial Mapping and Surveying, April 2003.

2 LIDAR CALIBRATION

2.1 Introduction

The purpose of the LiDAR system calibration is to refine the system parameters in order for the post-processing software (Optech Incorporated's DASHMap, version 1.1) to produce a “point cloud” that best fits the actual ground.

The following report outlines the calibration of the Optech 3100ea LiDAR system flown on July 8, 2007 over the Apalachicola Municipal Airport, Franklin County, Florida.

2.2 Calibration Procedures

AERO-METRIC performs two types of calibrations on its Optech 3100ea LiDAR system. The first calibration, system calibration, is performed whenever the LiDAR system is installed in the aircraft. This calibration is performed to define the system parameters affected by the physical misalignment of the system versus aircraft. The second calibration, in-situ calibration, is performed for each mission using that missions data. This calibration is performed to refine the system parameters that are affected by the on site conditions.

2.3 System Calibration

The system calibration is performed whenever the LiDAR system is installed in the aircraft. This calibration is performed to define the system parameters affected by the physical misalignment of the system versus aircraft. The main system parameters that are affected are the heading, pitch, roll, and mirror scale.

The system calibration is performed by collecting data over a known test site that incorporates a flat surface and a large, flat roofed building. A ground survey is completed to define the flat surface and the building corners. The processed LiDAR data and ground survey data is input into TerraSolid's TerraMatch software to determine the systematic errors. The system parameters are then corrected according to the determined errors and used in the processing of future LiDAR acquisition missions.

2.4 In-situ Calibration

“Bore-sighting” and “in-situ calibration” are essentially the same thing, i.e., they determine if the LiDAR sensor has maintained its factory calibration and is still sensing the correct position on the ground, both vertically and horizontally. The in-situ calibration is performed for each mission using that missions data. This calibration is performed to refine the system parameters that are affected by the on-site conditions.

For each mission, LiDAR data for at least one cross flight is acquired over the mission's acquisition site. The processed data of the cross flight is compared to the perpendicular flight lines using TerraSolid's TerraMatch software to determine if any systematic errors are present. In this calibration, the data of individual flight lines are compared against each other and their systematic errors are corrected in the final processed data.

3 GEODETIC BASE NETWORK

3.1 Network Scope

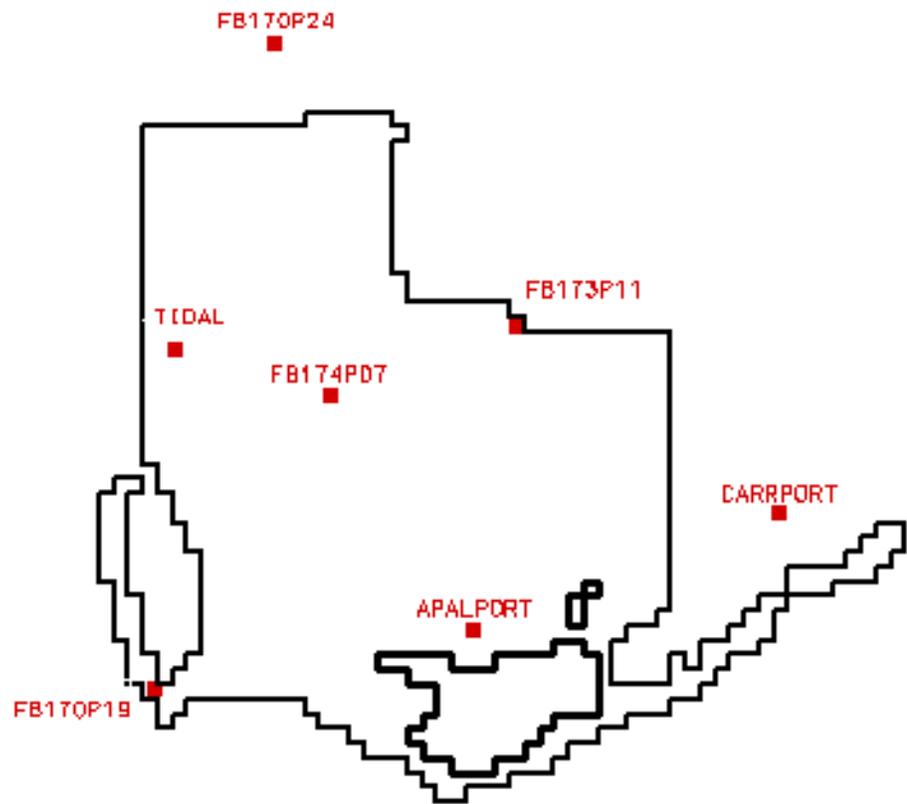
The PDS (Program and Data Solutions) team established a geodetic control network to provide accurate and consistent horizontal and vertical control for LiDAR acquisition using GPS technology.

AERO-METRIC surveyors occupied seven of the geodetic control network monuments (APALPORT, CARRPORT, FB170P19, FB170P24, FB173P11, FB174P07, TIDAL) throughout the acquisition of LiDAR data. In addition to these control stations, the National Geodetic Survey (NGS) Continuously Operating Reference Station (CORS) PNCY was also used as a base station.

3.2 Base Station Use

A minimum of two base stations were used to compute the Airborne GPS and IMU defined LiDAR trajectory per mission. These base stations were to limit the baselines lengths to the sensor to less than or equal to 20 km.

Figure 6: Base Station Location Diagram



4 LiDAR ACQUISITION & PROCEDURES

4.1 Acquisition Time Period

LiDAR data acquisition and Airborne GPS control surveys were completed between July 9th and July 22nd, 2007. A total of 22 flight missions were required to cover the project area. Apalachicola Municipal and Panama City – Bay County International airports were used as bases of operation.

4.2 LiDAR Acquisition

A total of 22 flight missions were required to cover the project area. All missions were flown at a nominal 1,000 meters above ground level. The Optech 3100ea sensor was set at a pulse rate of 100000, a scan frequency of 55, and a scan angle of 18° each side of center. See page 10 for a sketch of the acquisition missions and Appendix 1 for each flight log.

Airborne GPS and IMU trajectories for the LiDAR sensor were also acquired during the time of flight. A minimum of two base stations were used to compute the Airborne GPS and IMU defined LiDAR trajectory per mission. These base stations were to limit the baselines lengths to the sensor to less than or equal to 20 km.

Each mission was typically four to five hours long. Before take-off, the LiDAR system and the Airborne GPS and IMU system were initiated for a period of five minutes and then again after landing for another five minutes. The missions acquired data according to the planned flight lines and included a minimum of one (usually two) cross flights. The cross flights were flown perpendicular to the planned flight lines and their data used in the in-situ calibration of the sensor.

4.3 LiDAR Trajectory Processing

The airborne positioning was based on one NGS CORS station: **PANAMA CORS ARP (PNCY)** and six base stations tied to the NGS National Spatial Reference System (NSRS): **APALPORT, CARRPORT, FB170P19, FB173P11, FB174P07, and TIDAL.**

Horizontal control was based on the North American Datum of 1983/HARN. Vertical was based on the North American Vertical Datum of 1988 (NAVD88).

The ABGPS/IMU and GPS ground base station raw data were processed using the Applanix Corporation's POSpac version 4.31 software. The software was used to compute the position and attitude of the LiDAR sensor at the time of collection. The resulting data was related to the GPS ground network (see description above). At least two base stations were used to derive the solution independently and then their results were compared as a quality control measure. Graphical plots were

created to analyze and record the accuracy of the solution for each LiDAR mission. See Appendix 2.1 through 2.7.

Figure 2: Mission/Flight Line Diagram

LIDAR TRAJECTORY SKETCH
GULF and WESTERN FRANKLIN COUNTIES

MISSION

- 070907A
- 071207A
- 071307A
- 071407A
- 071507A
- 071507B
- 071607A
- 071607B
- 071607C
- 071707A
- 071707B
- 071807A
- 071807B
- 071807C
- 071907A
- 071907B
- 072007A
- 072007B
- 072107A
- 072107B
- 072207A
- 072207B



5 CHECK POINT SURVEY

The check point survey was performed between June 21st and June 23rd, 2007 using Rapid Static GPS techniques. A total of 165 check points were surveyed across the Gulf and western Franklin counties. The points were collected in varying classifications of ground cover in order to QC the LiDAR data classification process.

The following control stations from the PDS primary control network were used: AS0557 (4980 B01), AS0861 (TIDAL), AS0884 (APALPORT), FB170P19, FB173P11, FB174P07.

GPS measurement computations were done in two stages. Initial computations were done with LEICA Geo Office (LGO), version 4.0. LGO permits the conversion of raw satellite data collected by the receivers to a meaningful coordinate difference between points (baseline solutions). Once the baseline solutions were determined, they were input into the GeoSurv-GeoLab2 series of programs (Geolab version 2.4d). An adjustment was performed for analysis and quality closure. In the final adjustment all the published control values were held in the fully constrained scaled least squares base network adjustment that was used to derive the Ground Control Checkpoints.

The check points were referenced horizontally to NAD83(HARN), Florida State Plane Coordinates, North Zone. The vertical datum was NAVD88. The Units were US Survey Foot.

Table 1: Check Point Coordinates
(Units in US Survey Foot)

POINT	EASTING	NORTHING	NAVD88 HT
100	1803178.329	261143.080	11.657
101	1803160.757	261825.677	11.594
102	1804256.723	262349.813	16.857
103	1804493.061	266106.203	16.588
104	1801629.655	262576.443	15.223
105	1801899.913	262918.798	18.566
106	1802569.535	263837.793	18.215
107	1817002.445	371175.052	27.011
108	1817131.933	371505.008	27.818
109	1816602.423	371072.949	27.277
110	1816845.458	369185.692	27.395
111	1817106.950	366307.007	29.514
112	1753832.624	348503.522	20.548
113	1753794.353	348319.795	21.027
114	1753665.541	348516.806	20.712
115	1748446.362	338179.934	19.321
116	1749062.155	339504.026	18.888

POINT	EASTING	NORTHING	NAVD88 HT
117	1749550.999	340549.273	19.560
118	1750139.823	341361.161	20.102
119	1751968.422	345018.211	17.415
120	1755594.133	352180.674	24.029
121	1693161.958	364118.468	6.109
122	1693315.688	364055.584	6.631
123	1691639.606	364079.538	9.777
124	1690331.045	362474.167	5.876
125	1695806.920	363979.794	8.405
126	1700206.613	364650.626	8.661
127	1700605.765	363592.216	15.075
128	1702341.917	362668.422	12.113
129	1704762.942	361427.220	10.597
130	1694027.475	247914.189	1.102
131	1684346.389	271878.436	8.445
132	1684969.894	269266.666	5.840
133	1685713.938	266822.757	11.863
134	1686932.942	263750.280	13.222
135	1688502.017	260249.470	15.400
136	1690423.584	254948.001	11.644
137	1692525.345	250470.034	5.230
138	1694202.189	247308.603	5.030
139	1696063.219	247149.201	5.728
140	1699831.197	246569.143	5.646
141	1823149.887	224053.915	14.908
142	1823434.916	224755.072	3.993
143	1824218.225	225060.446	3.766
144	1825830.262	225373.516	4.711
145	1824801.393	225898.016	2.192
146	1826729.089	225812.009	5.476
200	1803224.258	261084.586	11.283
201	1803245.186	261771.760	11.506
202	1804195.007	262404.849	16.207
203	1804433.104	264316.325	18.287
204	1804444.885	266124.212	14.925
205	1801567.338	262537.041	13.077
206	1802609.203	263844.672	17.720
207	1816844.805	369204.688	27.487
208	1817030.168	368213.092	29.360
209	1817104.860	366278.897	30.518
210	1748383.377	338217.844	14.921
211	1749045.984	339485.548	18.504
212	1749558.932	340571.130	18.491
213	1749486.626	340594.630	18.750
214	1750220.007	341501.669	20.007
215	1750074.033	341561.994	17.989
216	1751992.654	344993.588	11.030
217	1700256.888	363837.258	14.442
218	1694588.251	364189.701	9.662

POINT	EASTING	NORTHING	NAVD88 HT
219	1690346.974	362463.803	6.617
220	1695817.750	363955.732	10.157
221	1700634.952	363643.292	16.063
222	1702394.423	362714.307	11.608
223	1704738.917	361438.821	11.161
224	1694071.881	247996.266	0.712
225	1684278.170	271853.400	7.858
226	1685712.954	266792.593	12.949
227	1686865.170	263711.520	10.486
228	1688470.521	260309.962	15.794
229	1690393.437	254981.705	12.126
230	1692551.687	250415.149	3.192
231	1694245.916	247323.472	4.124
232	1696006.319	247126.248	6.985
233	1699857.345	246518.936	5.587
234	1823409.637	224782.776	3.973
235	1824220.715	225037.670	3.415
236	1824762.968	225861.809	2.116
237	1826733.049	225775.903	5.125
300	1804239.764	262271.559	15.180
301	1804290.955	262323.960	14.314
302	1804430.174	264293.093	17.405
303	1804451.519	266124.461	15.469
304	1801552.168	262525.292	13.632
305	1802604.794	263886.073	17.900
306	1817066.166	371097.673	26.060
307	1817150.470	371434.969	27.949
308	1816596.295	371036.548	27.825
309	1816776.517	369194.642	27.306
310	1816935.165	368189.684	29.688
311	1753782.322	348391.829	20.636
312	1748367.825	338235.226	17.064
313	1749573.522	340585.533	18.793
314	1750042.428	341575.144	17.776
315	1750011.720	341393.067	18.668
316	1700155.304	363778.180	14.131
317	1694538.458	364199.475	9.314
318	1691570.344	364076.470	10.105
319	1691609.894	364146.339	9.035
320	1690339.169	362481.798	6.732
321	1695851.795	363963.084	9.770
322	1700597.439	363578.531	15.564
323	1702413.590	362758.976	11.722
324	1704706.699	361436.902	11.053
325	1705804.174	361555.894	10.371
326	1684908.910	269291.699	5.673
327	1685700.136	266813.613	12.776
328	1686951.223	263675.309	10.666
329	1688518.283	260198.089	15.702

POINT	EASTING	NORTHING	NAVD88 HT
330	1690426.878	254885.176	12.464
331	1696021.103	247123.485	7.710
332	1699878.205	246534.674	5.344
333	1823430.579	224798.120	4.058
334	1824235.843	225051.955	3.530
335	1825756.408	225417.997	3.701
336	1824774.868	225917.179	2.648
337	1826715.185	225869.017	4.724
400	1803127.821	261074.494	14.508
401	1803198.985	261840.297	13.415
402	1804255.227	262363.366	16.742
403	1804378.898	264310.682	18.835
404	1804504.278	266088.749	17.992
405	1801618.296	262559.560	15.420
406	1801896.383	262965.147	18.976
407	1802512.068	263880.978	18.812
408	1817177.087	371438.877	28.855
409	1816586.898	371056.240	28.304
410	1816878.331	369214.898	28.629
411	1817131.851	366290.075	32.070
412	1753677.743	348369.749	23.005
413	1748426.654	338219.570	20.023
414	1749104.438	339485.847	19.590
415	1751947.825	344996.603	17.917
416	1700208.601	363816.956	16.056
417	1700217.079	363845.726	15.843
418	1694521.450	364164.701	10.384
419	1691586.761	364112.251	9.997
420	1692290.936	363856.297	61.896
421	1692736.851	363891.034	72.270
422	1695810.181	364004.708	11.440
423	1700213.371	364638.926	8.937
424	1700610.667	363598.482	15.397
425	1702345.011	362648.412	13.035
426	1684347.520	271933.196	8.944
427	1684929.576	269254.570	6.690
428	1685736.576	266819.033	15.187
429	1686919.202	263731.179	13.615
430	1688496.853	260310.631	17.608
431	1690461.603	254907.824	12.874
432	1692568.616	250438.069	5.568
433	1694200.368	247293.593	5.466
434	1696085.794	247160.303	6.594
435	1699841.085	246550.718	7.238
436	1823229.506	224029.785	14.370
437	1823442.705	224770.764	4.298
438	1824213.884	225080.629	4.400
439	1825820.751	225392.643	5.118
440	1824806.892	225887.419	2.628

POINT	EASTING	NORTHING	NAVD88 HT
441	1826710.215	225834.312	4.537

6 FINAL LiDAR PROCESSING

6.1 LiDAR Processing

The ABGPS/IMU post processed data along with the LiDAR raw measurements were processed using Optech Incorporated's DASHMap version 1.1 software. This software was used to match the raw LiDAR measurements with the computed ABGPS/IMU positions and attitudes of the LiDAR sensor. The result was a "point cloud" of LiDAR measured points referenced to the ground control system. Each point was then classified into categories.

Although the data was collected using a scan width of 18° each side of centerline, the last 2° were removed during the processing of the "point cloud" in order to remove any exaggerated effects of mirror scale at the edges of the scan.

The LiDAR point cloud classification involved importing the point cloud data in TerraSolid's TerraScan software that is integrated with Bentley's MicroStation V8. The data was partitioned into 5,000ft by 5,000ft tiles to organize the massive amount of data into manageable units. TerraMatch was used to calibrate the data by removing systematic errors found between flight lines (in-situ calibration). After the fine tuning of the calibration, TerraScan was used to classify the points to identify primarily the ground (bare-earth surface) and then other classes such as trees, brush, tall grass, etc. This software computes the classifications using algorithms, with customized parameters to best fit the project area. Several areas of varying relief and planimetric features are inspected to verify the final ground surface. Once the automatic processing is completed, as a quality control measure, AERO-METRIC meticulously reviews the generated bare-earth surface data to insure that proper classification was achieved. Any further manual editing and classification is done using TerraScan.

6.2 Check Point Validation

The ground check point coordinates were input into TerraScan. TerraScan then computed the vertical differences between the surveyed elevation and the LiDAR derived elevation for each point. A report listing the differences and common statistics was created. The LiDAR data is corrected for any systematic elevation difference and TerraScan is run again to create the final report listing.

6.3 Horizontal Accuracy Check

Ten horizontal check points were surveyed on the runway surface at the Apalachicola Municipal airport. These check points were located at the corners of select painted stripes and runway numbering.

Coordinates of the check points were extracted from the LiDAR intensity data and compared to their field surveyed coordinates.

A 95% horizontal confidence level of 2.6 ft was computed from the coordinate differences. See Table 2 below.

Table 2: Horizontal Accuracy Check Point Differences
(Units in US Survey Foot)

Point ID		Field Surveyed Values		LiDAR Intensity Values		Residuals	
ID	Note	E	N	E	N	V(E)	V(N)
317	XY	1802451.102	263151.191	1802452.513	263149.277	-1.411	1.914
401	XY	1802398.568	263157.150	1802399.065	263155.983	-0.497	1.167
402	XY	1802391.779	263164.052	1802392.162	263163.083	-0.383	0.969
403	XY	1802363.673	263192.765	1802364.156	263192.666	-0.483	0.099
404	XY	1802356.774	263199.755	1802357.450	263199.372	-0.676	0.383
405	XY	1802348.901	263247.222	1802348.772	263245.326	0.129	1.896
407	XY	1802385.170	263227.977	1802385.851	263226.787	-0.681	1.189
408	XY	1802427.000	263185.369	1802426.282	263185.369	0.718	-0.001
409	XY	1802443.078	263143.125	1802443.835	263141.782	-0.757	1.343
410	XY	1802438.895	263139.115	1802440.285	263137.246	-1.390	1.869

6.4 LiDAR Breakline and Contour Production

AERO-METRIC used GeoCue software to develop LiDAR stereo models of Gulf and western Franklin Counties so the LiDAR derived data could be viewed in 3-D stereo using DAT/EM System’s Summit Evolution softcopy photogrammetric software. Using LiDARgrammetry procedures with LiDAR intensity imagery, AERO-METRIC stereo-compiled breaklines in accordance with the Data Dictionary at Appendix C. The LiDARgrammetry was performed under the direct supervision of an ASPRS Certified Photogrammetrist. The breaklines conform with data format requirements outlined by the FDEM Baseline Specifications.

Using proprietary procedures developed by AERO-METRIC, the 2-foot and 1-foot contours were compiled from the breaklines and LiDAR data in accordance with the Data Dictionary at Appendix C. The contours conform with data format requirements outlined by the FDEM Baseline Specifications.

6.5 LiDAR Data Delivery

LiDAR data was delivered to Dewberry as three major data sets. Those data sets were: 1) LiDAR classified mass points, 2) nine types of breaklines, and 3) 1ft and 2ft contours produced from the mass points and breaklines.

The mass points were delivered according to LAS 1.1 specifications and classified into the following LAS codes:

- Class 1 – Unclassified, including vegetation, buildings, bridges, piers
- Class 2 – Ground points (used for contours)

Class 7 – Noise
Class 9 – Water
Class 12 – Overlap points deliberately removed

The nine types of breaklines, produced in accordance with the Data Dictionary at Appendix C, are as follows:

1. Coastal shoreline features
2. Single-line hydrographic features
3. Dual-line hydrographic features
4. Closed water body features
5. Road edge-of-pavement features
6. Bridge and overpass features
7. Soft breakline features
8. Island features
9. Low confidence areas.

The 1ft and 2ft contours were also produced in accordance with the Data Dictionary at Appendix C.

LIDAR FLIGHT LOG

PROJECT NUMBER: 1-070414		OPERATOR: MERRY		DATE: 7/9/07 (UTC Time)		REMARKS	
MISSION	LINE NO. & Hdg	GROUND SPEED (KTS)	SCAN FREQ	SCAN ANGLE	ALT (m)	TIME START	TIME STOP
20709071						19:09	
						19:16	
230	230 359	155	55	18	2000	19:29	19:35
244	215 179	157	55	18		19:38	19:44
	229 359	157	55	18		19:48	19:54
	214 179	150	55	18		19:57	20:04
	228 359	148				20:08	20:14
	213 179	152				20:17	20:24
	227 359	147				20:28	20:34
	212 179	144				20:38	20:44
	226 359	148				20:49	20:54
	211 179	152				20:58	21:04
	225 359	150				21:08	21:14
	210 179	148				21:18	21:25
	224 359	148				21:28	21:34
	209 179	147				21:37	21:45
	223 359	150				21:48	21:54
	208 179	148				21:57	22:05
	222 359	153				22:09	22:15
STATUS	TOTAL LINES	FLOWN	LEFT	AIRCRAFT SITE	FERRY	WK:	
0	533	28	305	5.0	0.7	507/300 3300	
						vis 718 MILES	
						NOTES:	



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JUL 10 07 10:06A



LIDAR FLIGHT LOG

PROJECT NUMBER: 1-070414		OPERATOR: MERRY		DATE: 7/12/07					
MISSION	LINE NO. & HIG	GROUND SPEED (KTS)	SCAN FREQ	SCAN ANGLE	ALT (m)	TIME START	TIME STOP	TRANZPAK	REMARKS
						17:09	17:15	215	Baron Shark
						17:22			PFN → SITE
	X-51A		55	18	1000	17:42	17:43		
	202 179	152				17:49	17:57		
	188 359	148				18:01	18:09		
	201 179	153				18:13	18:21		Eye Safety Shutoff @ Beginning of Line
	187 359	149				18:24	18:31		Reply South end
	200 179	153				18:34	18:41		
	186 359	150				18:45	18:52		
	199 179	153				18:55	19:03		
	185 359	149				19:08	19:14		
	198 179	154				19:17	19:25		
	184 359	157				19:28	19:35		
	197 179	158				19:38	19:46		
	183 359	156				19:50	19:56		
	196 179	153				20:00	20:06		
	182 359	149				20:10	20:17		
	195 179	154				20:20	20:26		
	181 359	152				20:30	20:36		
STATUS	TOTAL LINES	FLOWN	LEFT	AIRCRAFT SITE	FERRY	WX: Bcwn 4000 Vis 8-9			
○	333			49	0.6	NOTES:			

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No. 7423

2007 11:00AM Courtyard

LIDAR FLIGHT LOG


RMI

PROJECT NUMBER: 1-070414		OPERATOR: MEROY		DATE: 7/13/07	
PILOT: I. Brown		MISSION		TIME	
LINE NO. & Hdg	SCAN FREQ	ANGLE	ALT (m)	START	STOP
MISSION	COND SPEED (KTS)	SCAN ANGLE	ALT (m)	TRANZPAK	REMARKS
0713071					
0 X-Flt		55	1000	01:07	01:09
0 283 304	149			01:14	01:16
0 273 124	159			01:20	01:24
0 282 304	150			01:29	01:30
0 272 124	154			01:35	01:37
0 281 304	153			01:44	01:46
0 271 124				01:51	
0 280 304					
0 271 124	154			01:07	
0 322 65	154			02:16	02:17
0 327 245	145			02:21	02:24
0 323 65	158			02:28	02:30
0 328 245	149			02:34	02:36
0 324 65	158			02:40	02:43
0 329				02:46	
0 326 65	150			02:51	02:53
STATUS	TOTAL LINES	FLOWN	LEFT	AIRCRAFT SITE	FERRY
0	333	15	2.9	2.9	0.9
NOTES:					
Wx: 7/15 7					
Brown 3000					
Eye Satchel Shut off Mid of Line					
Clouds Moving to ANOTHER AREA					
Clouds					

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LIDAR FLIGHT LOG

PROJECT NUMBER: 1070414		OPERATOR: Tom		DATE: 07/14/07		TIME		TRANZPAK		REMARKS	
MISSION	LINE NO. & Hdg	GND SPEED (KTS)	SCAN ANGLE	ALT (m)	START	STOP	START	STOP	TRANZPAK	REMARKS	
PILOT: DAVE I.					11:24	12:20	LOT			TABLE 16:46	
1070414	2 TEST	FRES								FERRY PFN → SIZE	
L071407A									218		
XFLT	172 E	150	55	18	17:07	17:11					
	172 S	155 ±			17:17	17:24					
	159 N	150			17:28	17:36					
	171 S	155 → 160			17:48						
	158 N	155 ±			17:51	17:58					
	170 S	150 → 160			18:02	18:10					
	157 N	155 ±			18:13	18:21				XTR 5:00 CLEAR FOR EXP. 12:05	
	169 S	150			18:25	18:33					
	156 N	157 ±			18:36	18:43					
	168 S	150			18:47	18:54					
	155 N	155 ±			18:58	19:05					
	167 S	150			19:08	19:16				SMOKE N. END	
	154 N	154			19:19	19:26					
	166 S	155			19:30	19:36				RAIN JUST TO W.	
	165 N	153 ±			19:44	19:51				RAIN @ 19:57 ± / EYE SAFETY @ 19:00 t	
	153 S	154 ±			19:55	20:02					
	164 N	156 ±			20:06	20:13					
	152 S	154 ±			20:18	20:24				LATE (67) + BUMP ON TEACHER PRO	
STATUS	TOTAL LINES	FLOWN	LEFT	AIRCRAFT SITE	WX	NOTES:					
1070414	333	20	3	4.5	1.7	LITTLE SUN: VERY LIT					
						VARIOUS CLOUDS					
						SOME OCC RAIN					

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0240



772

LIDAR FLIGHT LOG

PROJECT NUMBER: 1070414 OPERATOR: Tom DATE: 7/15/07

6071507A

MISSION	LINE NO. & HDG	GND SPEED (KTS)	SCAN FREQ	ANGLE	ALT (m)	DATE: 7/15/07		REMARKS
						START	STOP	
1070414	14 SE	275-313	55	18°	10000	00:08	00:14	FERRY PFN → SITE
L071507A	6 NW	155				00:17	00:21	
	15 SE	158				00:25	00:31	
	5 NW	153				00:35	00:39	
	16 SE					00:42	00:48	
	4 NW	151				00:52	00:56	
	13 SE					00:57	01:05	
	3 NW	150				01:08	01:11	
	12 SE	150-160				01:12	01:17	
	12 SE					01:20	01:25	Jumped To 13
	2 NW						01:31	
	11 SE					01:36	01:41	
	1 NW					01:46	01:48	
XFLT	1 NE					01:52	01:54	
	17 SE					02:01	02:06	
	7 NW					02:11	02:16	
	18 SE					02:21	02:26	
	8 NW					02:30	02:35	
	19 SE					02:39	02:45	
STATUS	TOTAL LINES	FLOWN	LEFT	AIRCRAFT SITE	FERRY	NOTES:		
⓪	333	32	?	5.1				

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LIDAR FLIGHT LOG

PROJECT NUMBER: 1070414		OPERATOR: Tom		DATE: 07-16-07		771	
PILOT: DAVE F.		L071609A		TRANZPAK		REMARKS	
MISSION	LINE NO. & Hdg	GROUND SPEED (KTS)	SCAN FREQ	SCAN ANGLE	ALT (m)	COT TIME START	COT TIME STOP
	TEST FERRY	±150	07:07	07:08		1:42	2:06
	30 SE	±150	55	18°	1000m	07:12	07:16
	27 NW					07:20	07:23
	29 SE					07:31	
	26 NW					07:35	07:38
	28 SE					07:43	07:47
	26 NW					07:51	07:54
	25 SW					08:00	08:02
	151 N					08:14	08:22
	145 S					08:25	08:33
	150 N					8:45	
	146 S					08:49	08:57
	149 N					09:02	09:09
	144 S					09:13	09:21
	148 N					09:25	09:33
						4:36	4:54
						5:18	5:30
	147 N	±150	55	18°	1000m	10:32	10:40
	143 S					10:44	10:51
	140					10:54	11:03
	TOTAL LINES	FLOWN	LEFT	AIRCRAFT SITE	FERRY	WX:	
	333	21	1	3.3	1.3		
STATUS	1070414					NOTES: X SHOT - ORWIN, SAVE DATA + REBOOT @ AAF	
						GAF @ 25% EX SEND BETWEEN	
						LINE# 172-173	

ALTM - NAV PROGRAM LOCKED-UP
 FERRY SITE → AAF
 23
 12

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AREA #

1070414

LIDAR FLIGHT LOG

MISSION	LINE NO. & Hgt	WIND SPEED (KTS)	SCAN FREQ	ANGLE	ALT (m)	COY TIME (GFS)		TRANZPAK	REMARKS
						START	STOP		
1070414		2 TEST	2	3:14	3:15	9:36	10:18	Z15	Thru @ 9:57 FERRY: PFN → SZFE
L071607C	231 E	150 → 155	55	18°	1000M	03:23	03:28		- TUGO
	232 W	148 → 158				03:32	03:38		
	232 E					03:42	03:47		
	239 W					03:51	03:57		
	233 E					04:01	04:06		
	240 W					04:11	04:17		
	234 E					04:26	?		
	242 W					04:34	04:42		
	235 E					04:48	04:54		
	237 W					04:57	05:04		
	236 E					?	05:15		
	241 W					05:20	05:28		
	243 E					05:33	05:40		
	248 W					05:44	05:50		
	244 E					05:54	06:01		
	249 W					06:06	06:11		
	245 E					06:22	06:22		
	250 W					06:26	06:32		
	246 E					06:36	06:43		
STATUS	TOTAL LINES	FLOWN	LEFT	AIRCRAFT SITE	FERRY	NOTES:			
⊙	333	244	?	46	1.0				



TP3

PROJECT NUMBER: 1070414

PILOT: DAVE I.

OPERATOR: Tom

DATE: 7/16/07

L071607C

10/402 11.2

10/17/2007 10:04AM Courtyard

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LIDAR FLIGHT LOG

PROJECT NUMBER: 1070414		OPERATOR: TOM		DATE: 7/17/07		772		
MISSION	LINE NO. & Hdg	GROUND SPEED (KTS)	SCAN FREQ	SCAN ANGLE	ALT (ft)	START STOP	TRANZPAK	REMARKS
1070414	127 E	2 TESTS	55	18°	10000	7:54 8:42	218	To. 0:10 FERRY: PFW → SITE
1071707B	127 S	165	55	18°	10000	01:46 01:54		XFLT
	300 NE	158±				02:12 02:20		
	299 SW					02:16 02:24		
	298 NE					02:31 02:39		
	297 SW					02:34 02:42		
	296 NE					02:49 03:00		E.S.S. AFTER TAPER BLOCK
	302 SW					03:05 03:14		POD up to 3.27
	301 NE					03:29 03:37		" 1 3.26
	303 SW					03:34 03:42		POD < 3.0 - 6.00
	308 NE					03:49 04:00		
	304 SW					04:05 04:16		
	309 NE					04:19 04:31		
	305 SW					04:34 04:36		
	310 NE					05:01 05:15		
	306 SW					05:19 05:30		
	311 NE							
	307 SW							
STATUS	TOTAL LINES	FLOWN	LEFT	AIRCRAFT SITE	FERRY	WX:		NOTES:
	1070414	18	?	4.3	1.1			9:24 2:24 EOT 01:24 z 9:06 Z end

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LIDAR FLIGHT LOG

MISSION	LINE NO. & Hdg	GND SPEED (KTS)	SCAN FREQ	SCAN ANGLE	ALT (m)	TIME		TRANZPAK	REMARKS
						START	STOP		
PROJECT NUMBER: 1070414	OPERATOR: JDM	DATE: 7/18/07							
PILOT: DAVE F.									
L071807C	3751 @	155 ±	55	18°	1000m	02:22	02:25	215	FERRY: PFN → SITE
	329 NE					02:28	02:30		2:22:39 (334) or clipped A value RED
	333 SW					02:34	02:36		
	330 NE					02:40	02:41		
	332 SW					02:46	02:47		
	331 NE					02:53			
XFLT	333 NW					02:58	03:04		BAD POOP: 3.27
	256 W					03:09	03:11		" " 3.26 or LBS
	257 E					03:19	03:21		POOP 3.04 TO GREEN
	261 W					03:25	03:27		
	258 E					03:31	03:35		
	262 W					03:47	03:49		
	259 E					03:44	03:46		
	260 W					03:50	03:52		
XFLT	262 N					03:58	04:00		
	290 SW					04:04	04:05		
	284 NE					04:09	04:11		
	291 SW					04:15	04:16		
	285 NE					04:19	04:21		
	292 SW								
STATUS	TOTAL LINES	FLOWN	LEFT	AIRCRAFT SITE	FERRY	NOTES: *Holo @ PFN on GRND by ATE			
1070414	333	24	94/89	2.9	1.4				

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19

No. 7532 P. 1

07/19/2007 2:02AM Courtyard

1635-A/121

DAF

LIDAR FLIGHT LOG

PROJECT NUMBER: 1070414		OPERATOR: LDM		DATE: 07/19/07		TIME		REMARKS	
MISSION	LINE NO. & Hdg	GND SPEED (KTS)	SCAN FREQ	SCAN ANGLE	ALT (m)	START	STOP	TRANSECT	
L071907A		TEST	Start @ 1	18°	1000m	17:00			FERRY: NO FUEL
	266	155 ±	55	18°	1000m	17:11	17:15	215	FERRY: PFN → SITE TO 11:47
	266 SE					17:19	17:23		15 mile Lead SW
	275 NW					17:26	17:30		Roll
	265 SE					17:34	17:38		
	274 NW					17:49	17:53		
	264 SE					17:57	17:58		
	273 NW					18:04	18:09		
	263 SE					18:13	18:18		
	272 NW					18:22	18:26		
	267 SE					18:31	18:36		
	276 NW					18:40	18:43		
	268 SE					18:48	18:53		
	277 NW					18:?	19:01		
	269 SE					19:05	19:10		
	278 NW					19:14	19:19		
	270 SE					19:23	19:27		
	282 NW					19:31	19:32		
STATUS	TOTAL LINES	FLOWN	LEFT	SITE	AIRCRAFT	WK:			
⊙	333	24	70	4.0	FERRY				
				1.1		NOTES:			

265

263

7

1635-A/121

DAF

LIDAR FLIGHT LOG

PROJECT NUMBER: 1070414		OPERATOR: LDM		DATE: 07/19/07		TIME		REMARKS	
MISSION	LINE NO. & Hdg	GND SPEED (KTS)	SCAN FREQ	SCAN ANGLE	ALT (m)	START	STOP	TRANSECT	
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	265 SE					17:34	17:38		
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	264 SE					17:57	17:58		
	273 NW					18:04	18:09		
	263 SE					18:13	18:18		
	272 NW					18:22	18:26		
	267 SE					18:31	18:36		
	276 NW					18:40	18:43		
	268 SE					18:48	18:53		
	277 NW					18:?	19:01		
	269 SE					19:05	19:10		
	278 NW					19:14	19:19		
	270 SE					19:23	19:27		
	282 NW					19:31	19:32		
STATUS	TOTAL LINES	FLOWN	LEFT	SITE	AIRCRAFT	WK:			
⊙	333	24	70	4.0	FERRY				
				1.1		NOTES:			

265

263

7

1635-A/121

DAF

LIDAR FLIGHT LOG

PROJECT NUMBER: 1070414		OPERATOR: LDM		DATE: 07/19/07		TIME		REMARKS	
MISSION	LINE NO. & Hdg	GND SPEED (KTS)	SCAN FREQ	SCAN ANGLE	ALT (m)	START	STOP	TRANSECT	
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	272 NW					18:22	18:26		
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	276 NW					18:40	18:43		
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	277 NW					18:?	19:01		
	269 SE					19:05	19:10		
	278 NW					19:14	19:19		
	270 SE					19:23	19:27		
	282 NW					19:31	19:32		
STATUS	TOTAL LINES	FLOWN	LEFT	SITE	AIRCRAFT	WK:			
⊙	333	24	70	4.0	FERRY				
				1.1		NOTES:			

265

263

7

1635-A/121

DAF

LIDAR FLIGHT LOG

PROJECT NUMBER: 1070414		OPERATOR: LDM		DATE: 07/19/07		TIME		REMARKS	
MISSION	LINE NO. & Hdg	GND SPEED (KTS)	SCAN FREQ	SCAN ANGLE	ALT (m)	START	STOP	TRANSECT	
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	269 SE					19:05	19:10		
	278 NW					19:14	19:19		
	270 SE					19:23	19:27		
	282 NW					19:31	19:32		
STATUS	TOTAL LINES	FLOWN	LEFT	SITE	AIRCRAFT	WK:			
⊙	333	24	70	4.0	FERRY				
				1.1		NOTES:			

265

263

7

1635-A/121

DAF

LIDAR FLIGHT LOG

PROJECT NUMBER: 1070414		OPERATOR: LDM		DATE: 07/19/07		TIME		REMARKS	
MISSION	LINE NO. & Hdg	GND SPEED (KTS)	SCAN FREQ	SCAN ANGLE	ALT (m)	START	STOP	TRANSECT	
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	264 SE					17:57	17:58		
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	269 SE					19:05	19:10		
	278 NW					19:14	19:19		
	270 SE					19:23	19:27		
	282 NW					19:31	19:32		
STATUS	TOTAL LINES	FLOWN	LEFT	SITE	AIRCRAFT	WK:			
⊙	333	24	70	4.0	FERRY				
				1.1		NOTES:			

265

263

7

1635-A/121

DAF

LIDAR FLIGHT LOG

PROJECT NUMBER: 1070414		OPERATOR: LDM		DATE: 07/19/07		TIME		REMARKS	
MISSION	LINE NO. & Hdg	GND SPEED (KTS)	SCAN FREQ	SCAN ANGLE	ALT (m)	START	STOP	TRANSECT	
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	264 SE					17:57	17:58		
	273 NW					18:04	18:09		
	263 SE					18:13	18:18		
	272 NW					18:22	18:26		
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	276 NW					18:40	18:43		
	268 SE					18:48	18:53		
	277 NW					18:?	19:01		
	269 SE					19:05	19:10		
	278 NW					19:14	19:19		
	270 SE					19:23	19:27		
	282 NW					19:31	19:32		
STATUS	TOTAL LINES	FLOWN	LEFT	SITE	AIRCRAFT	WK:			
⊙	333	24	70	4.0	FERRY				
				1.1		NOTES:			

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7

1635-A/121

DAF

LIDAR FLIGHT LOG

18:38 - 23:12
1/21

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LIDAR FLIGHT LOG

PROJECT NUMBER: 109044N		OPERATOR: Tom		DATE: 7/21/07					
MISSION	LINE NO. & Hdg	GROUND SPEED (KTS)	SCAN FREQ	ANGLE	ALT (m)	TIME START	TIME STOP	TRANZPAK	REMARKS
L072107B	218	155	180	35	1000m	1:30	2:00	218	FERRY: PFN → SITE
	62 S					19:02	19:14		Just under car stands - Tomod 7:40
	65 N					19:19	19:31		
	61 S					19:36	19:48		
	64 N					19:52	20:05		
	60 S					20:08	20:20		
	62 N					20:25	20:35		NEED AN ENTER BUILTIN DEPRESSION TO MAKE LINE CORRECT - GETTING LINE
	59 S					20:32	20:43		
	69 N					20:48	21:00		TIDE AREAS ARE COMPLETE
	66 S					21:05	21:17		
	73 N					21:21	21:33		
	67 S					21:37	21:49		PROP 3.1
	74 N					21:53	22:05		DR 25:59, 30:05, 30:11
	68 S					22:08	22:16		PROP 3.37
	75 W					22:20	22:26		PROP 2.44 OFF 03:10
	48 N					22:31	22:33		SIGHT - DOWN DUE TO PREPARE AREA
	40 N					22:35	22:40		30:00
	40 N					22:47	22:47		SHORT EMASIS
	40 E					22:50	22:51		
XFLT	TOTAL LINES	FLOWN	LEFT	AIRCRAFT SITE	FERRY	WX:			
	333	12.38		3.9	.9	NOTES:			
1070414	24 VOLTS ON LANDING								
	ALTM								

AERO-METRIC, INC. N.6216 Resource Drive Sheboygan Falls, WI. 53085 PHONE: 920-467-2655 E-Mail: aemphoto@aerometric.com

LIDAR FLIGHT LOG

218



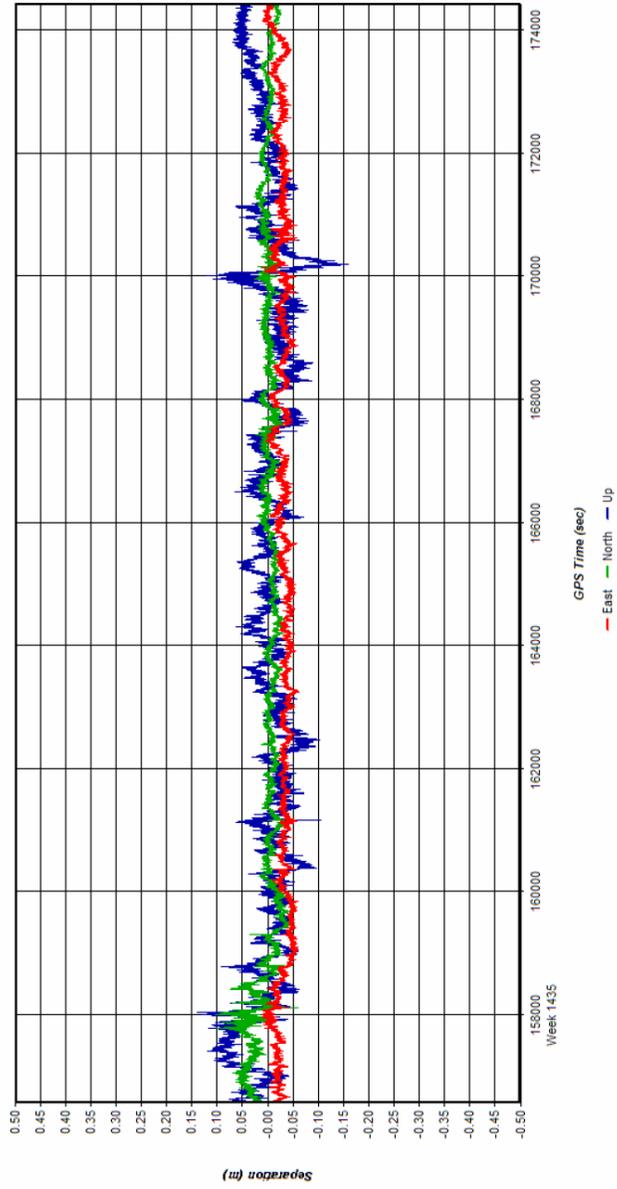
PROJECT NUMBER: 1070414 OPERATOR: DM DATE: 7/22/07 TP2

PILOT: CAM MISSION: L072207B ALT (mi) TRANZPRAK

LINE NO. & IMG	GROUND SPEED (KTS)	SCAN FREQ	ANGLE	START TIME	STOP TIME	REMARKS
58 S	155 ±	55	18°	16:47	17:48	LOWER CLOUDS JUST TO WEST
57 N				17:01	17:10	
54 S				17:14	17:23	
55 N				17:27	17:35	
54 S				17:40	17:48	
53 N				17:53	18:01	
52 S				18:05	18:13	
51 N				18:17	18:25	
50 S				18:29	18:36	LOW S. END LOW. 5000' VERT CLOUD BELOW FLT HT
49 N				18:41	18:49	
50 S				19:02	19:04	
50 W				19:08	19:10	RAIN S. END (-E.S.)
50 N				19:16	19:20	REFLY FOR LESS RAIN
49 E				2:18	2:48	FERRY SITE → PFN
TOTAL LINES	FLOWN	LEFT	AIRCRAFT SITE	WX: CU JUST ABOVE		
333	10/333	2.5	FERRY	FLT ALT		NOTES:
1070414						LOW VOLTAGE and Roll-out
						7/21 2:57

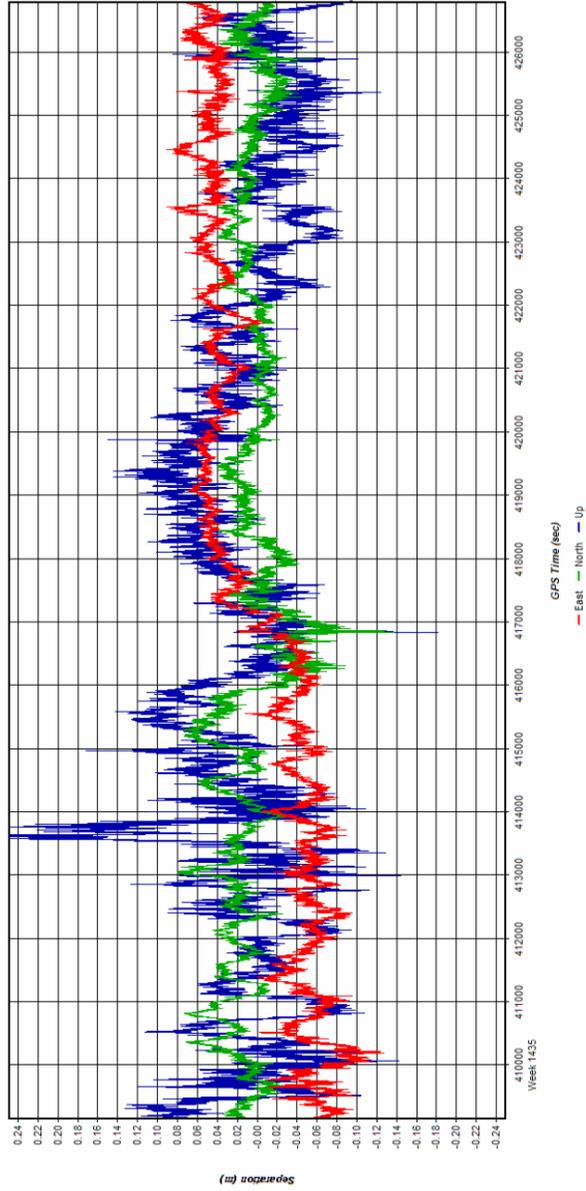
AERO-METRIC, INC. N 6216 Resource Drive Sheboygan Falls, WI 53085 PHONE: 920-467-2555 E-Mail: amphoto@aerometric.com

Separation Plot
APALPORT, CARRPORT, FBI70P19, and FBI73P11
L0709071



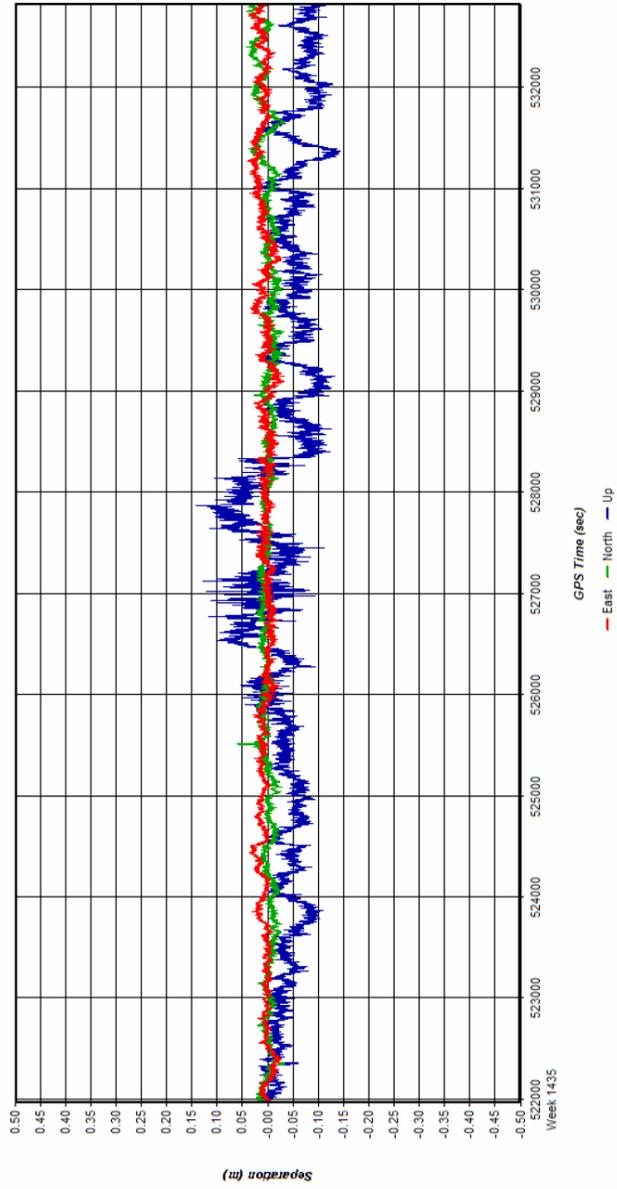
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Separation Plot
APALPORT, FBI73P11, FBI74P07, PNCY, and TIDAL
L0712071



N280MB_71206_Sep_APALPORT_FBI73P11_FBI74P07_PNCY_TIDAL-Cmb.doc

Separation Plot
APALPORT, CARRPORT, and FB174P07
L0713071



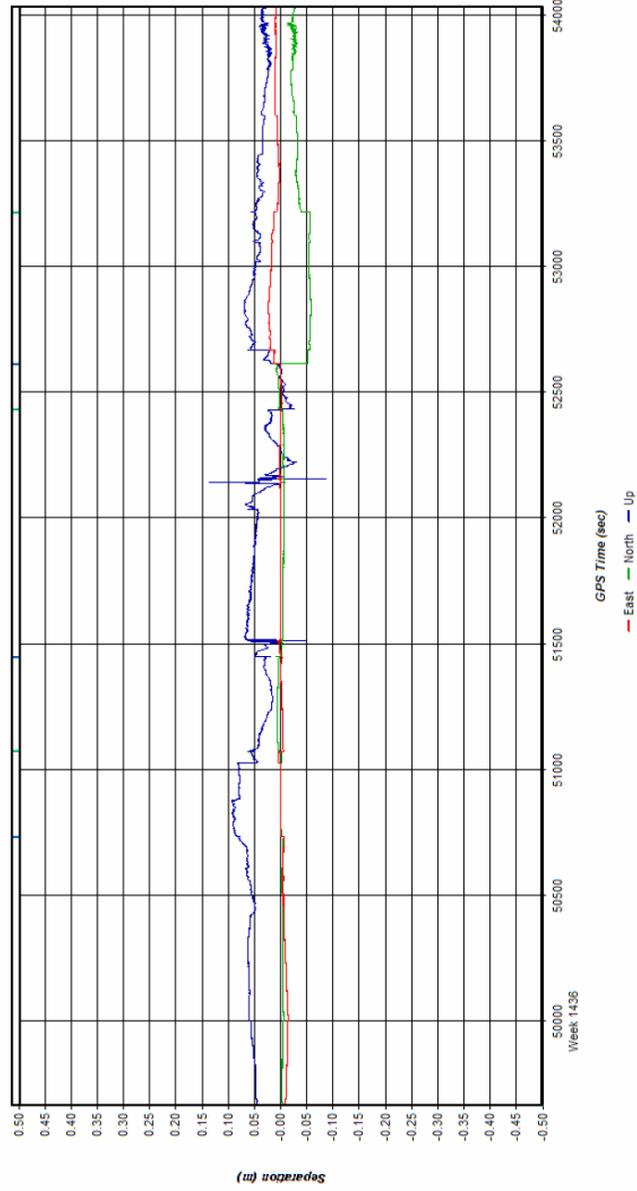
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Separation Plot
APALPORT and FBI174P07
L071407A



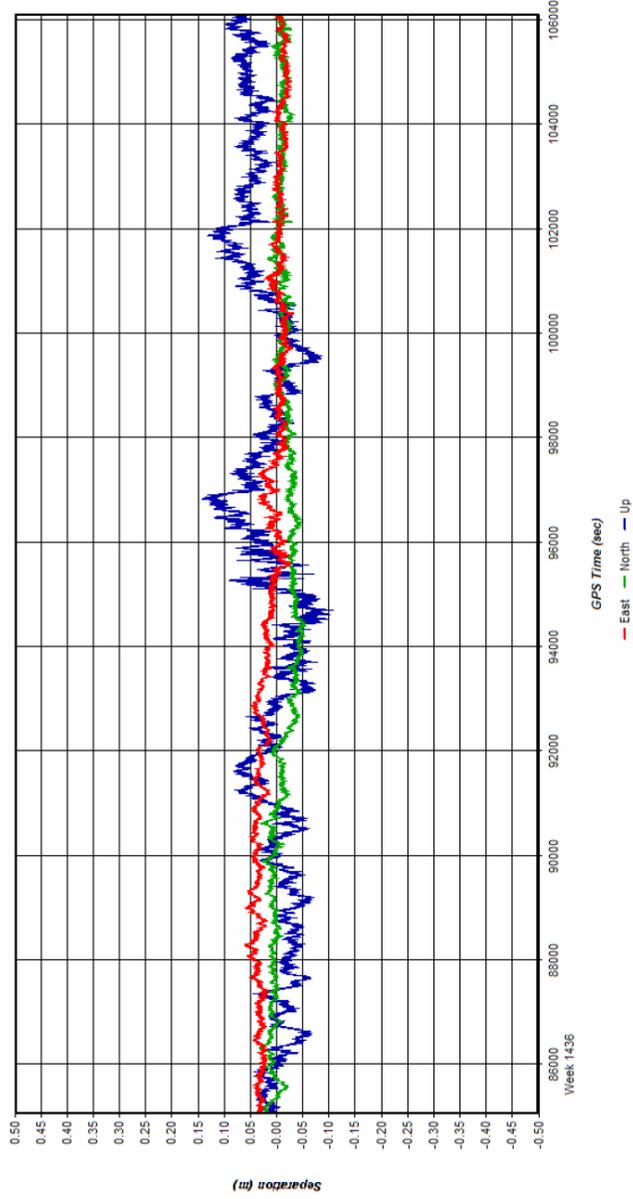
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Separation Plot
FB170P19, FB174P07, and PNCY
L071507A



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Separation Plot
FBI70P19-Cmb, FBI74P07-Rev, and PNCY-Rev
L071507B



N280MB_L071507B_SEP_FBI70P19-Cmb_FBI74P07-Rev_PNCY-Rev.doc

Separation Plot

L071607A



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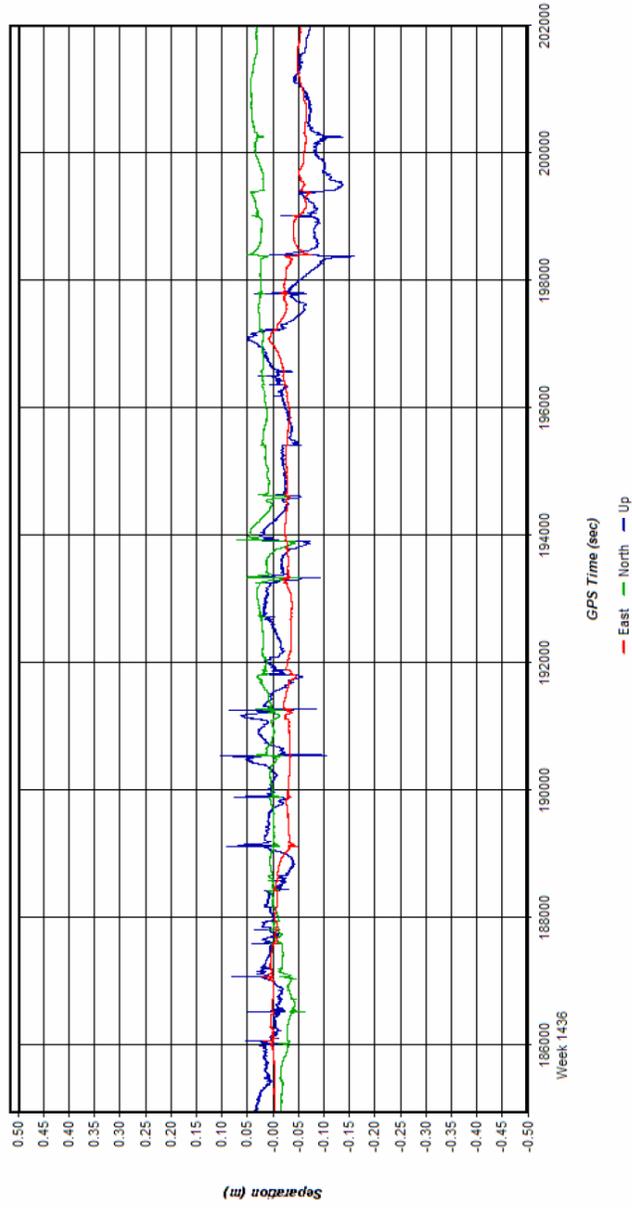
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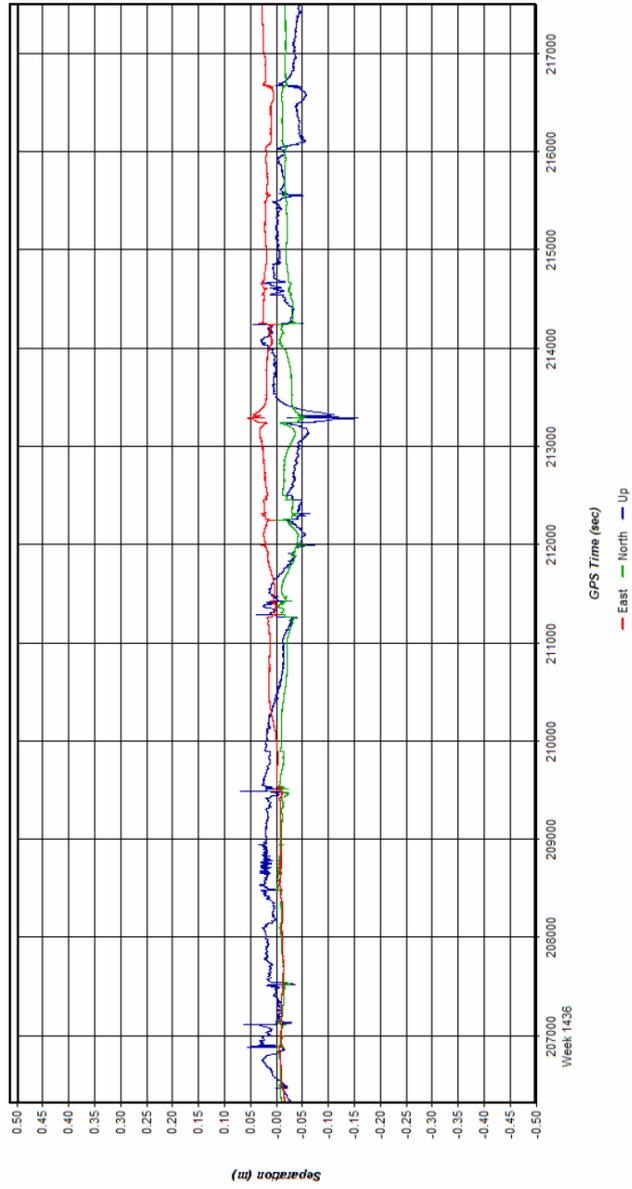
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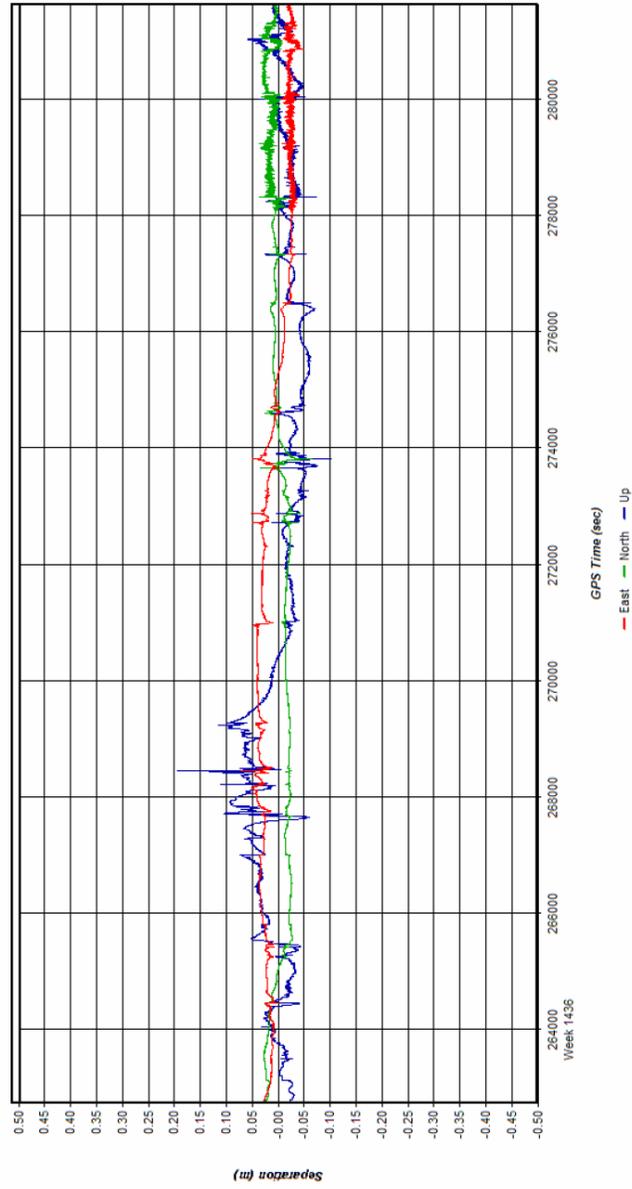
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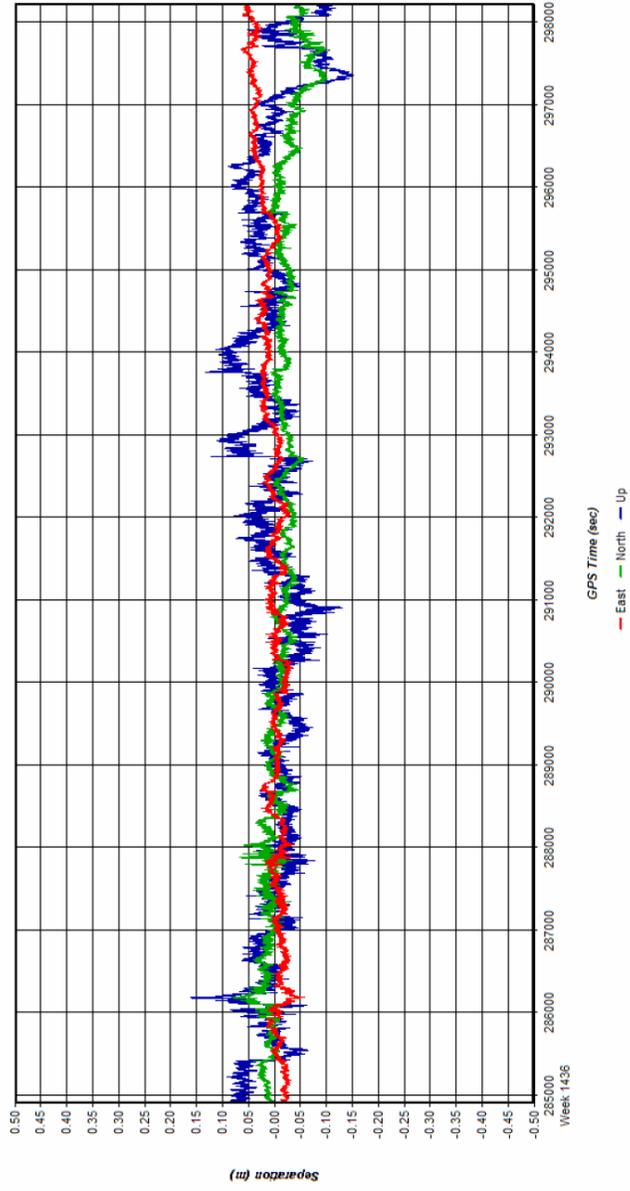
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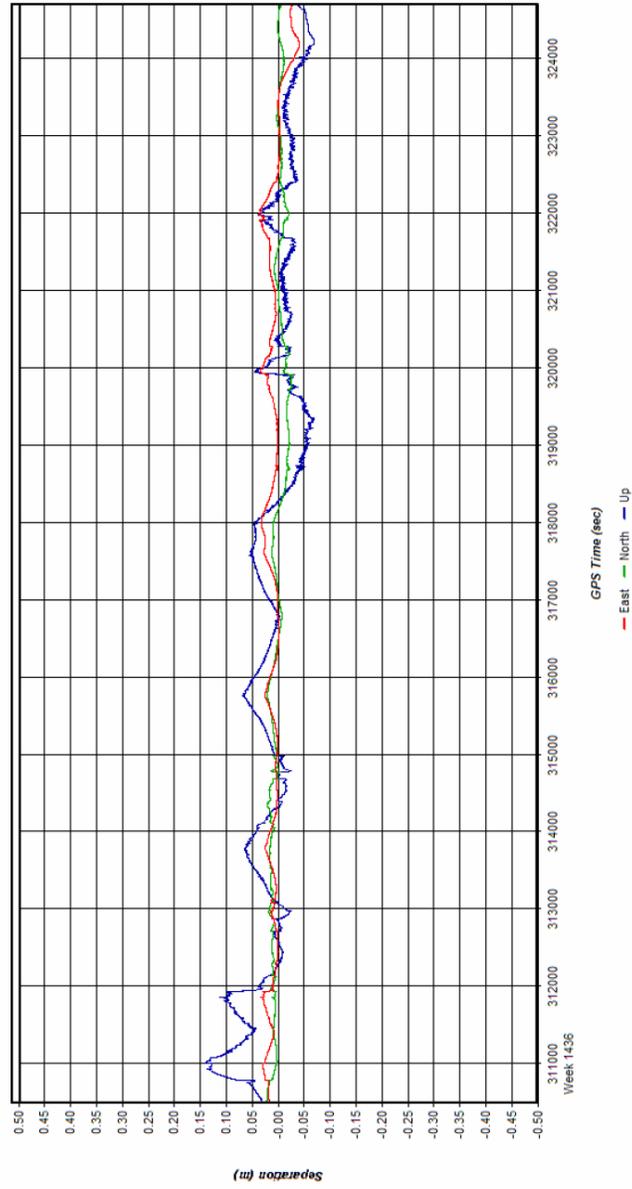
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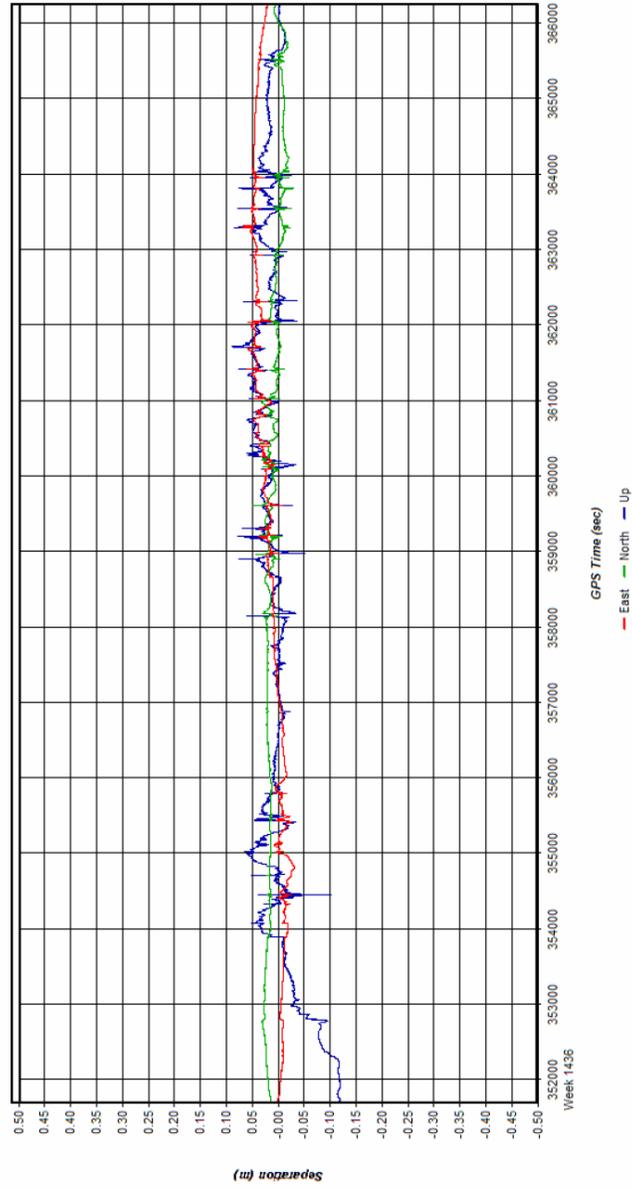
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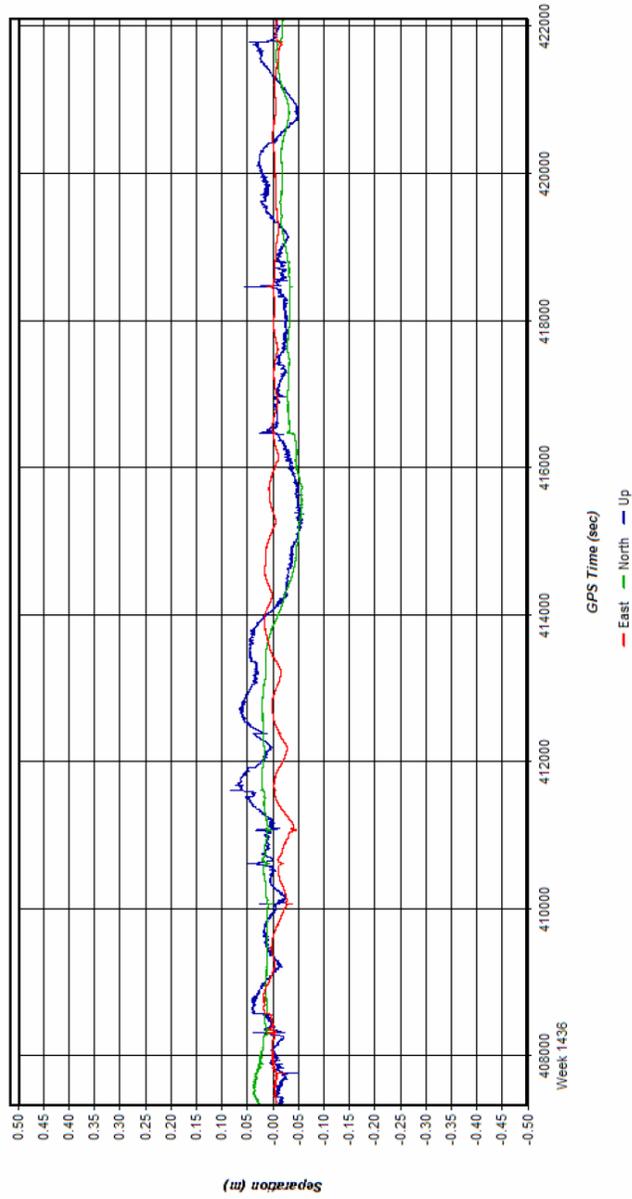
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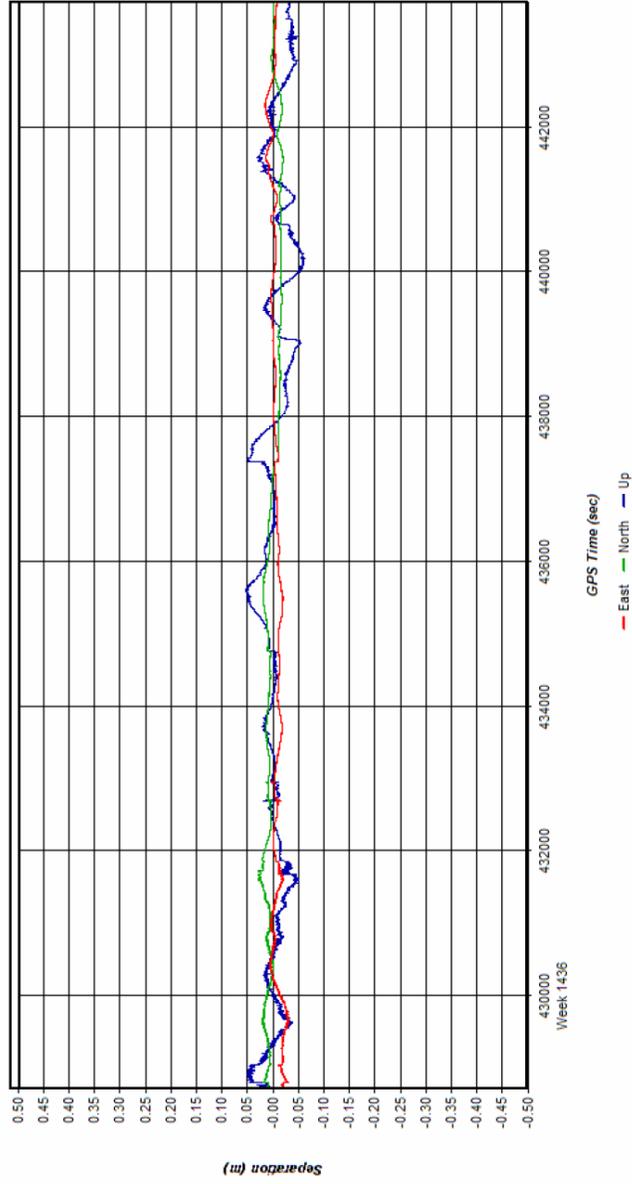
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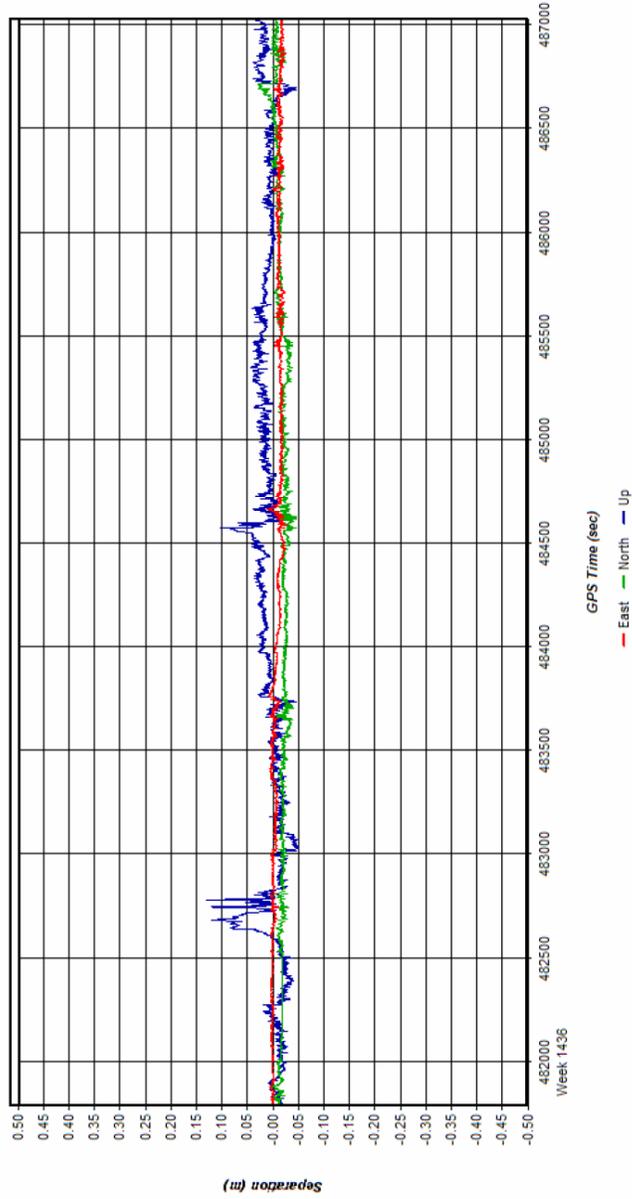
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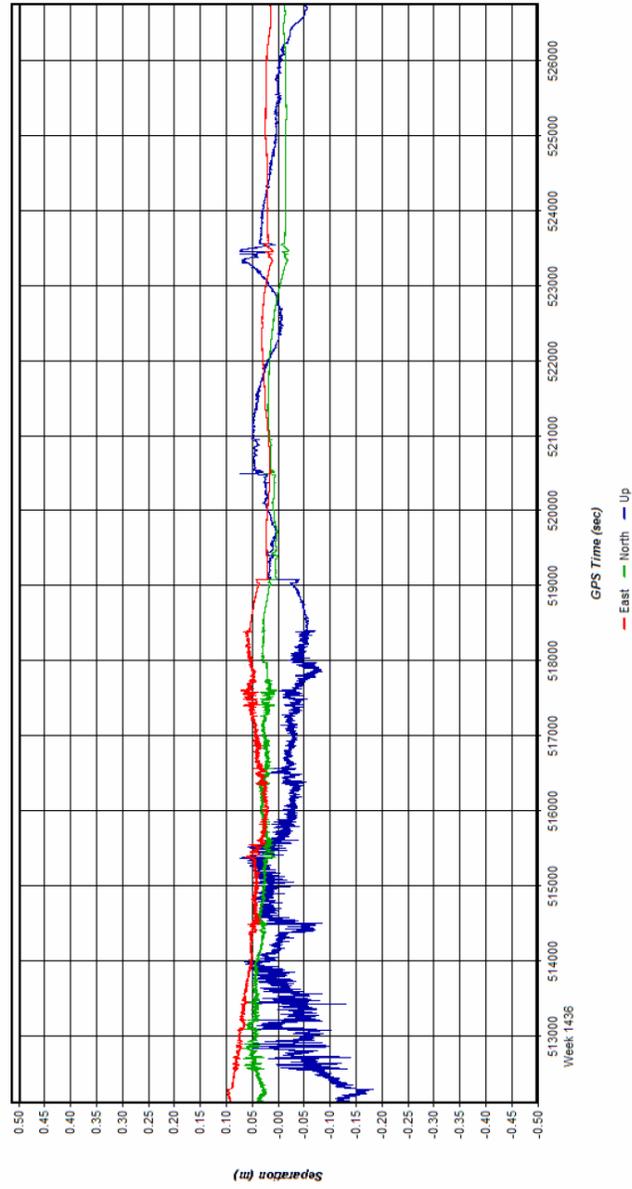
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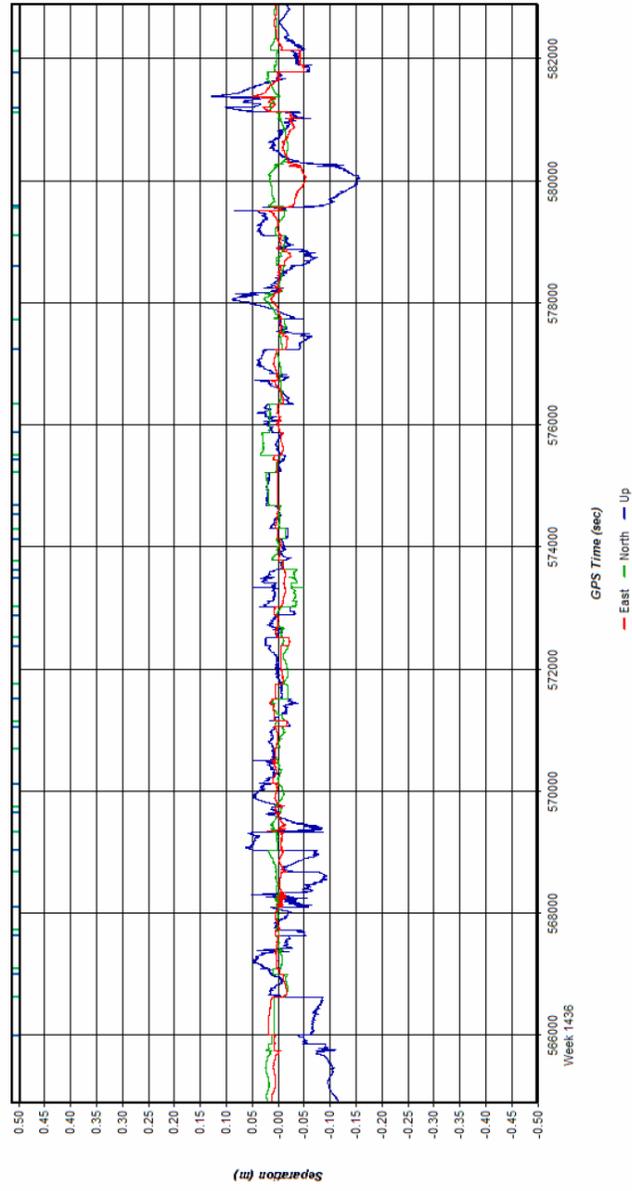
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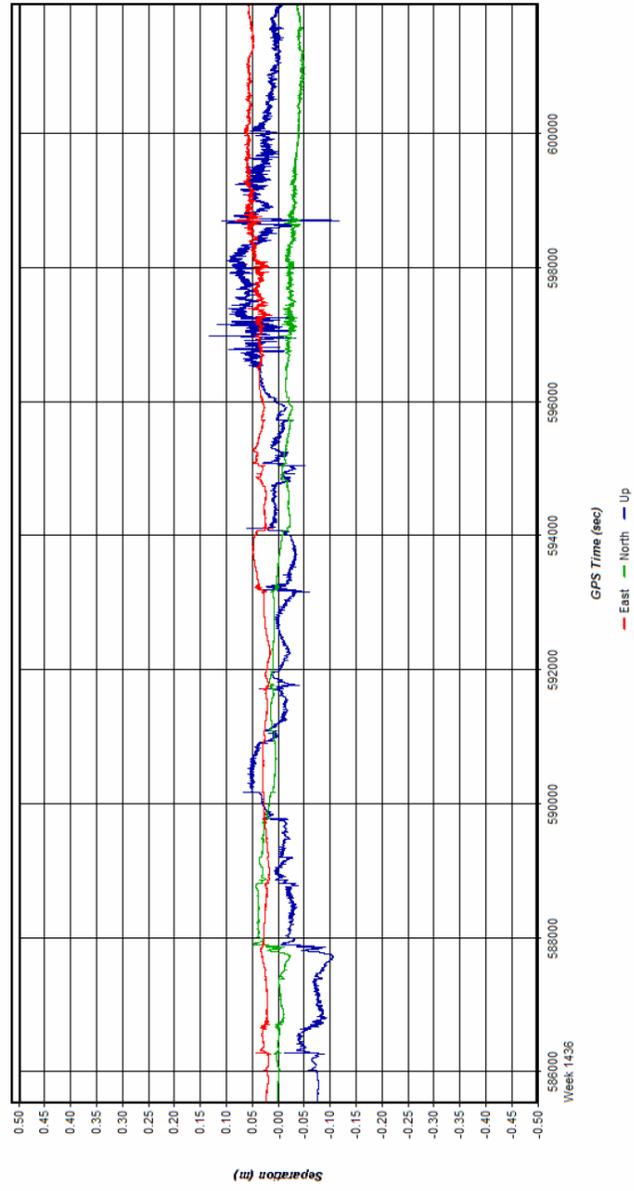
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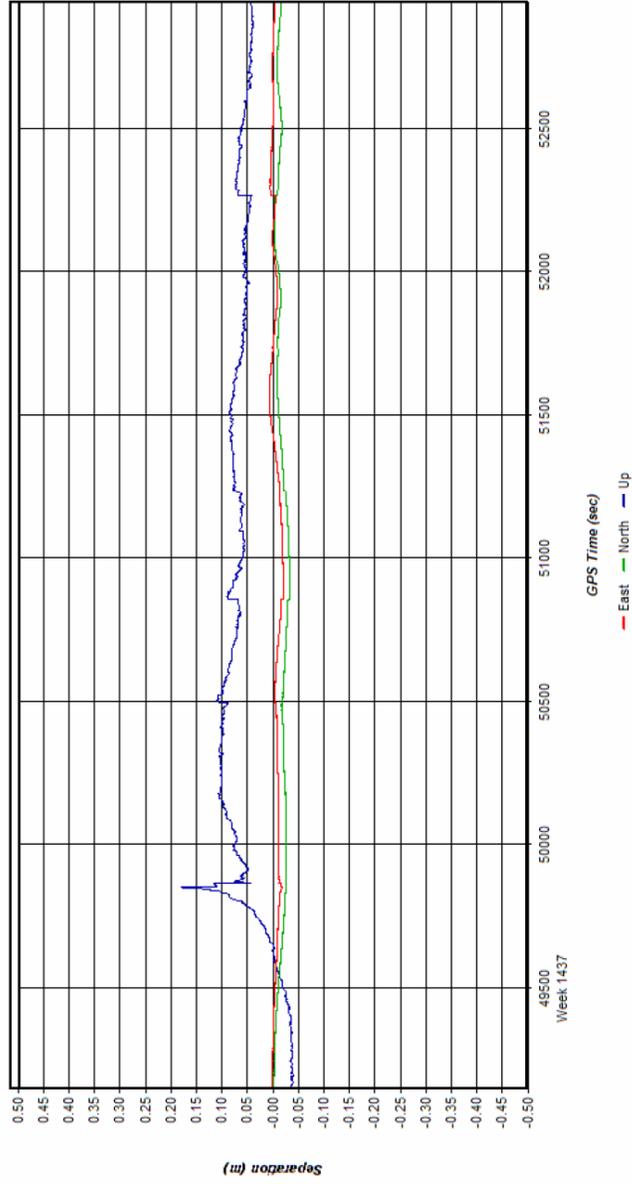
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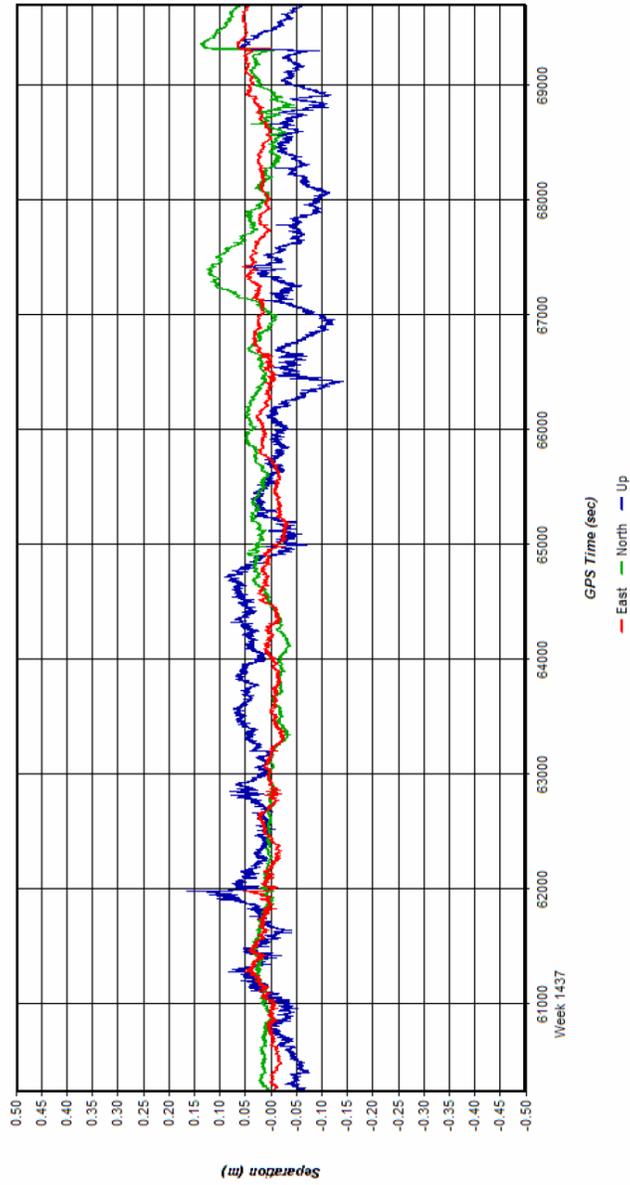
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Separation Plot

L072207B

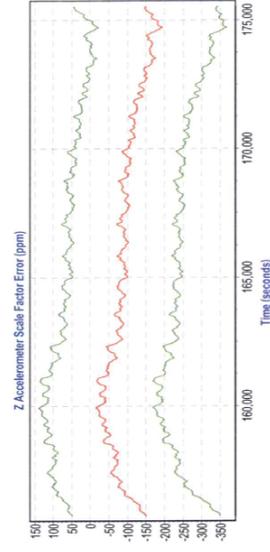
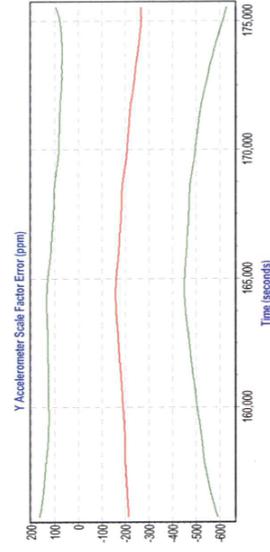
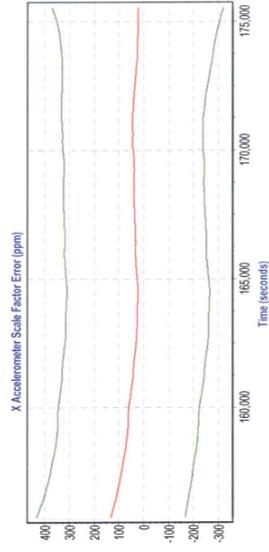
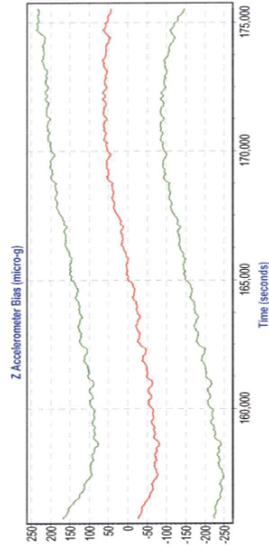
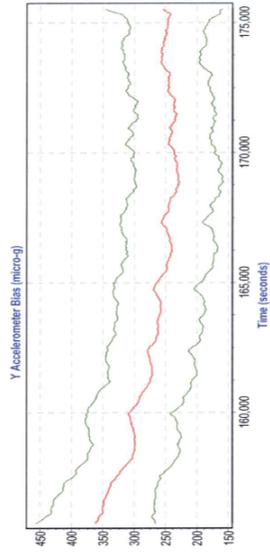
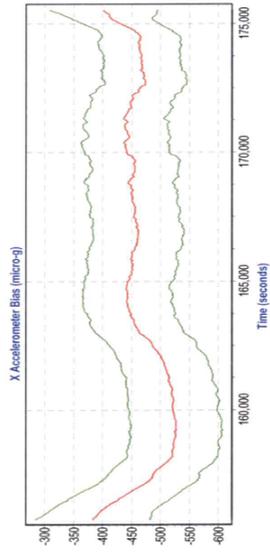


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Sensor Errors
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POSPac Version 4.3

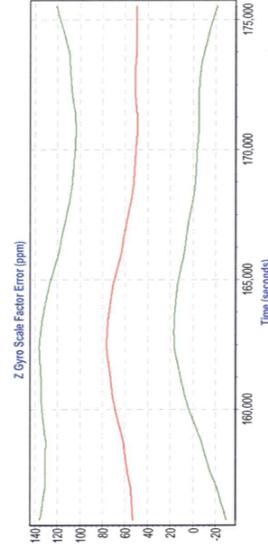
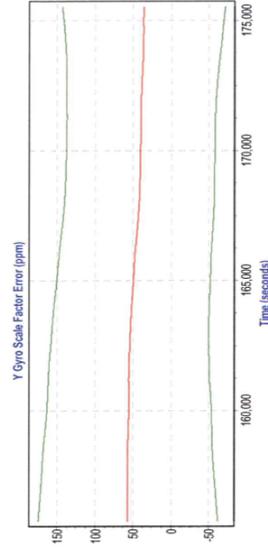
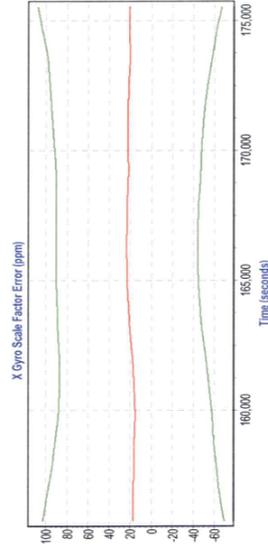
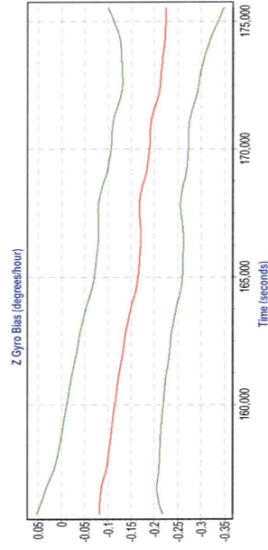
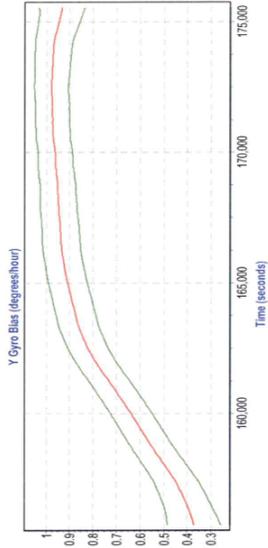
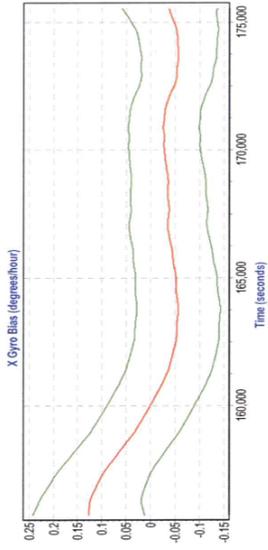
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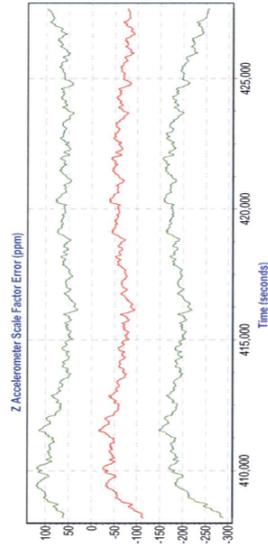
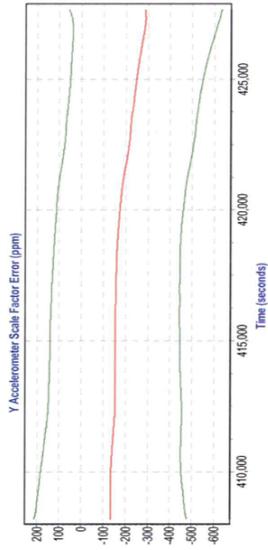
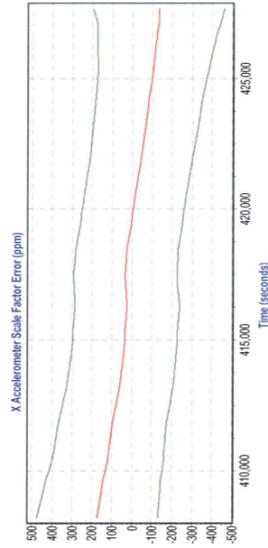
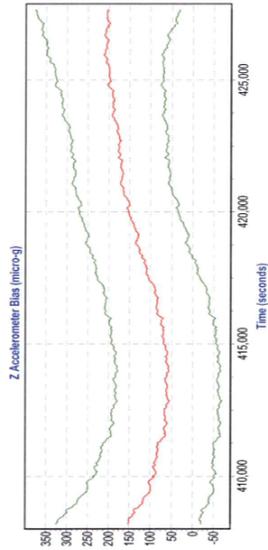
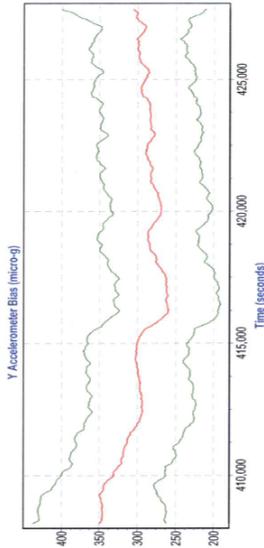
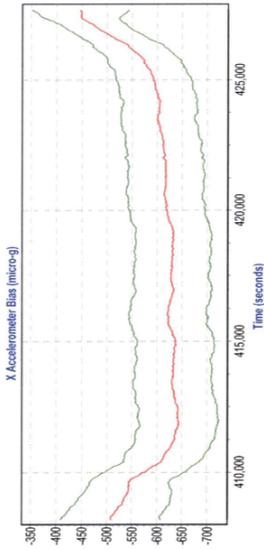
POSPac Version 4.3



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- 1 -

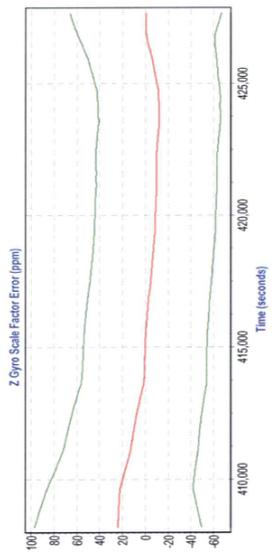
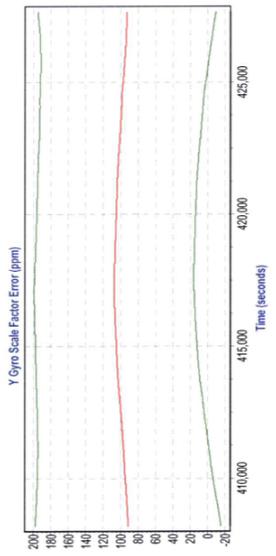
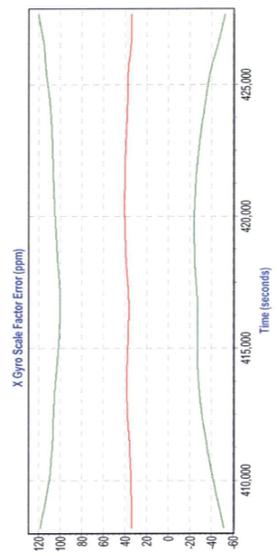
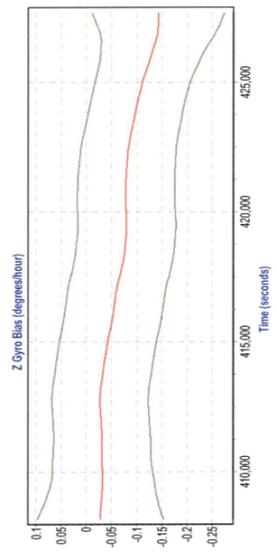
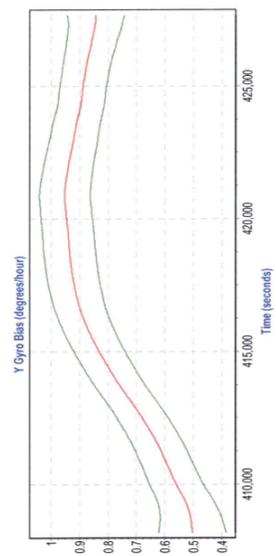
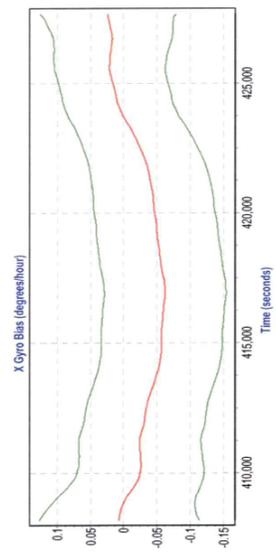
POSPac Version 4.3



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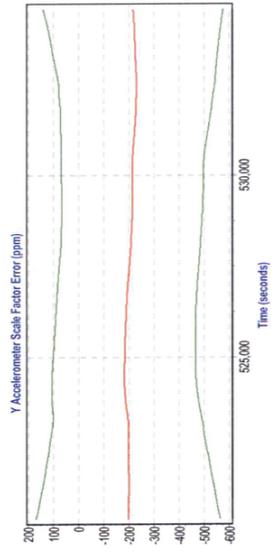
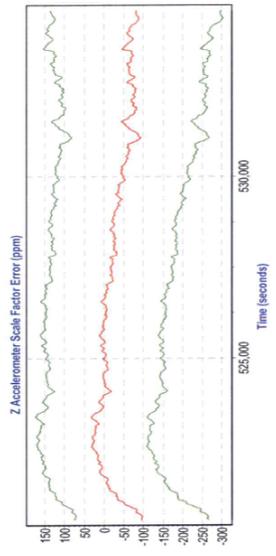
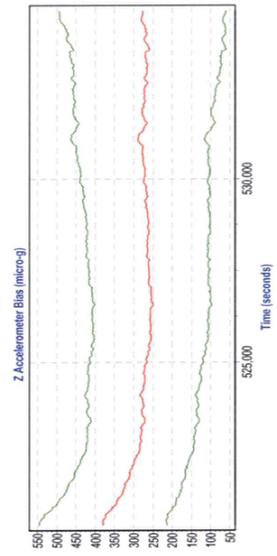
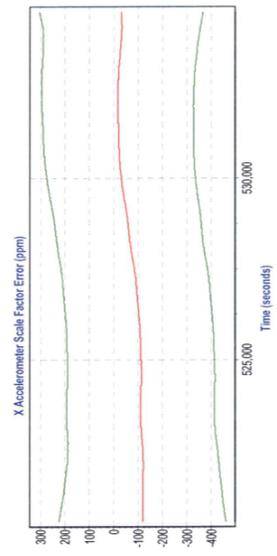
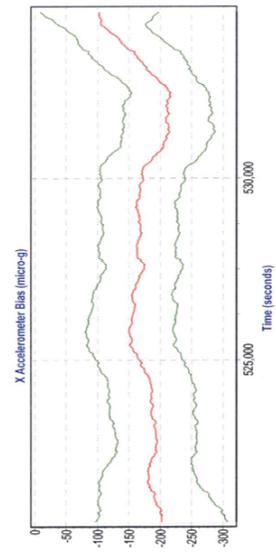
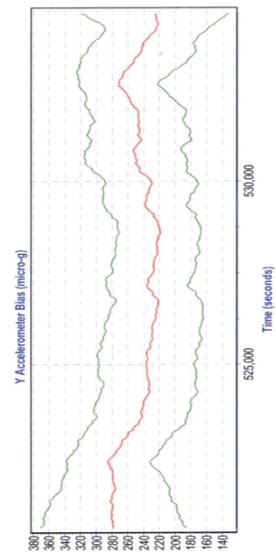
POSPac Version 4.3



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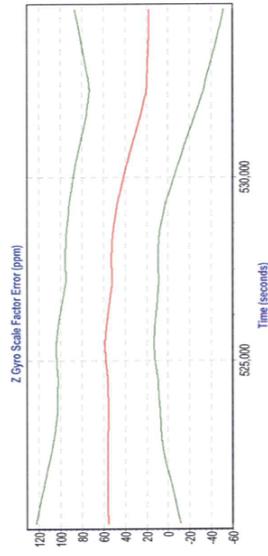
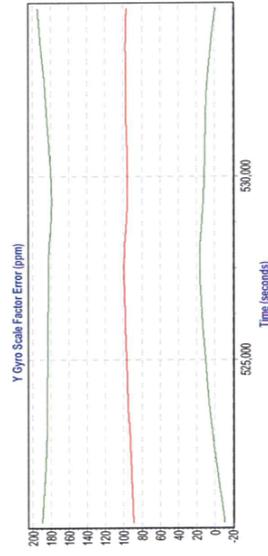
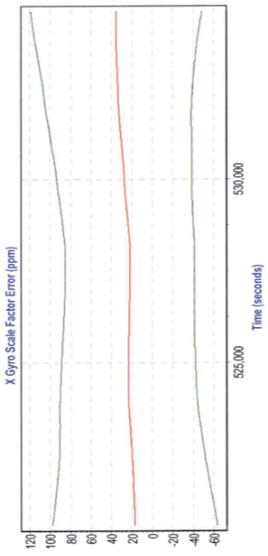
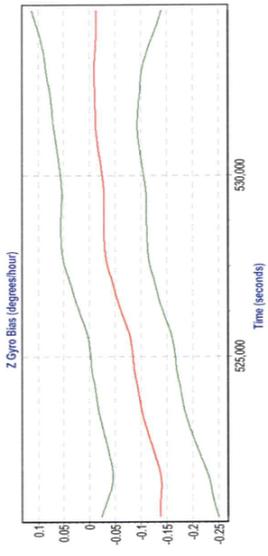
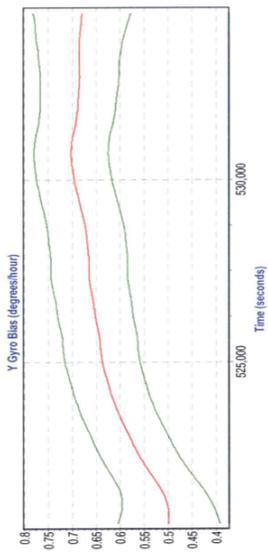
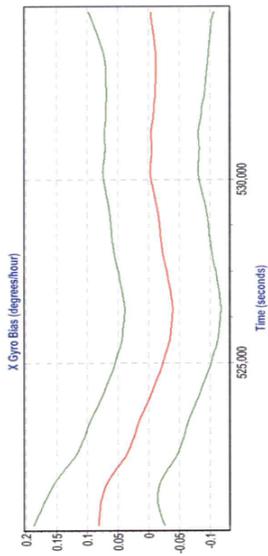
POSPac Version 4.3



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- 2 -

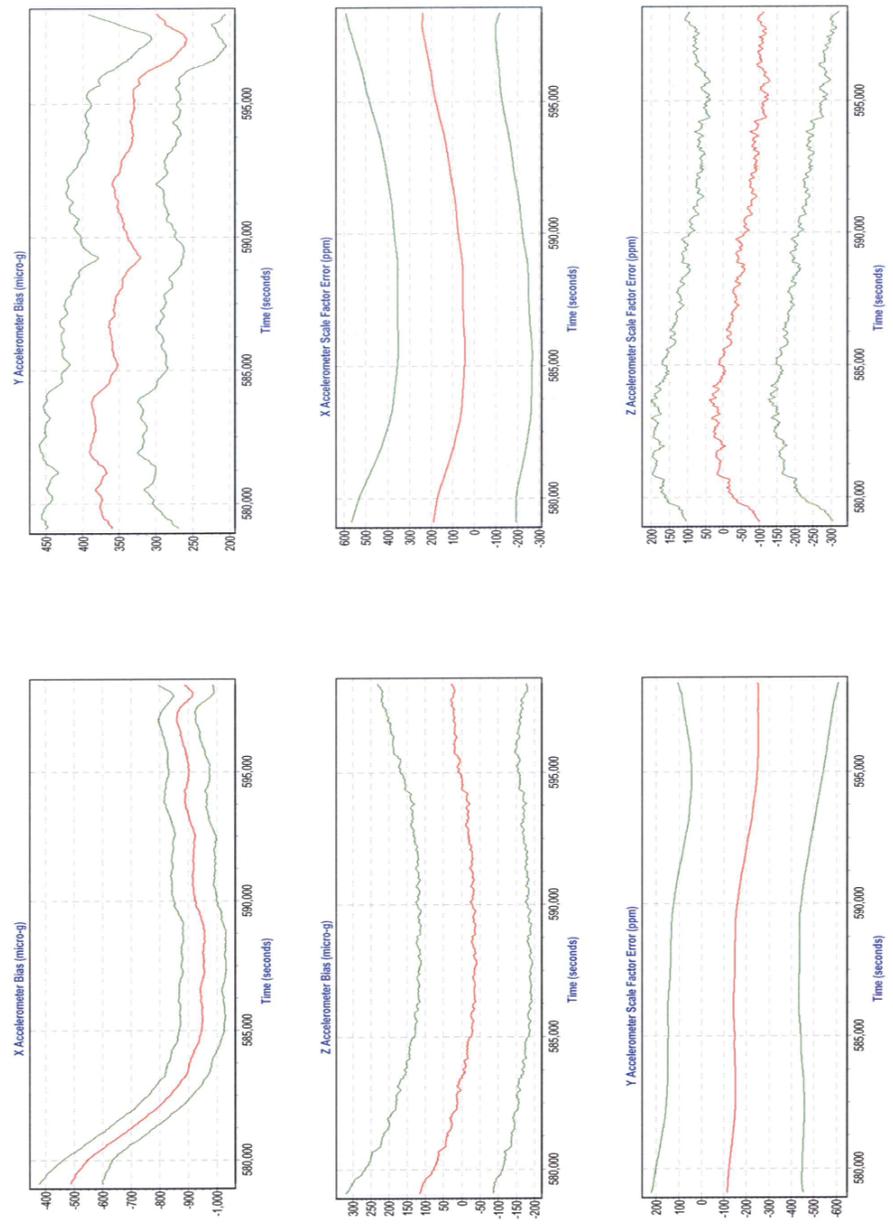
POSPac Version 4.3



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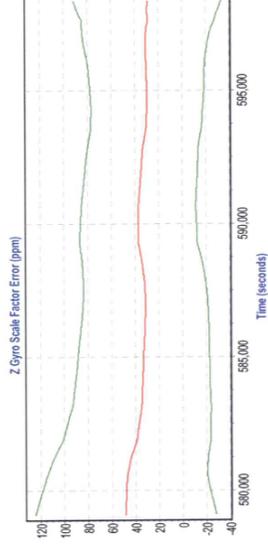
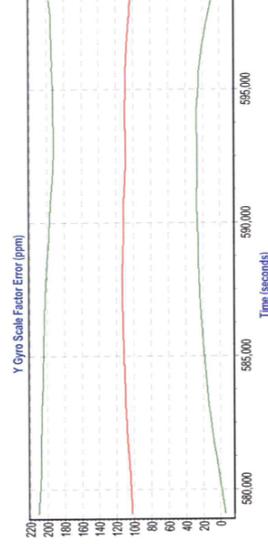
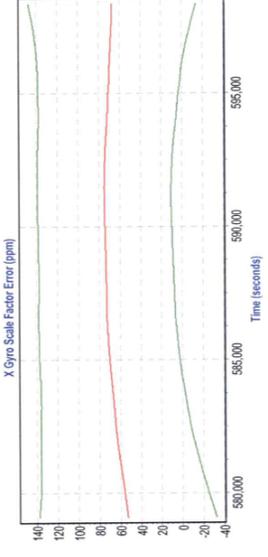
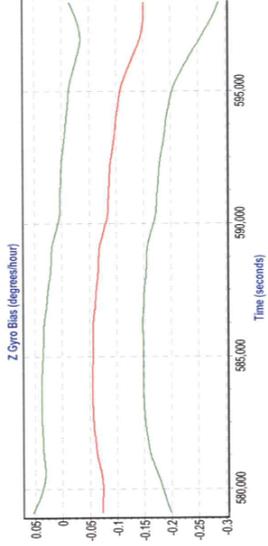
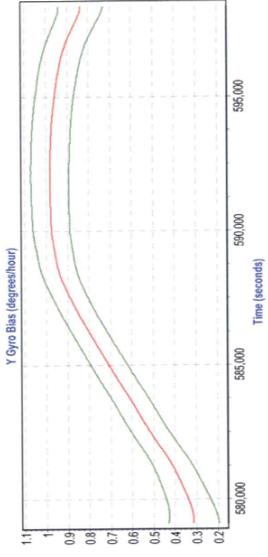
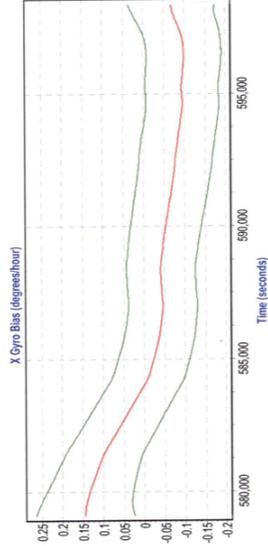
POSPac Version 4.3



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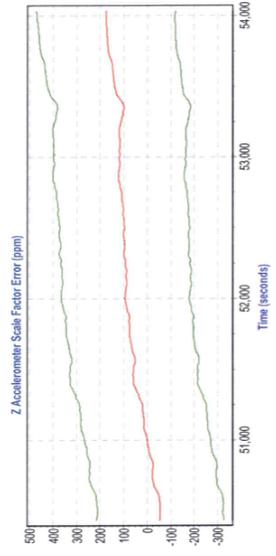
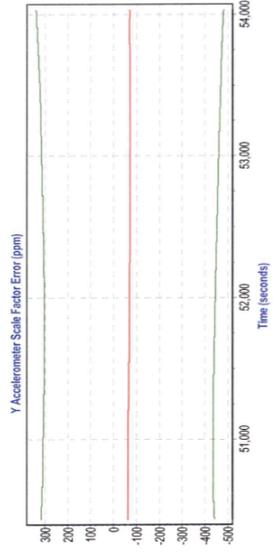
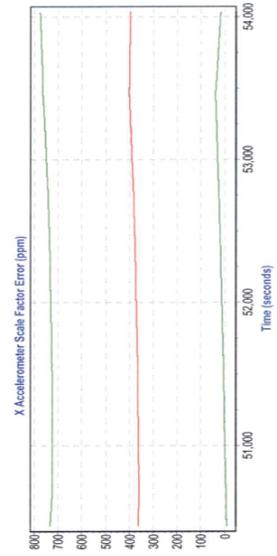
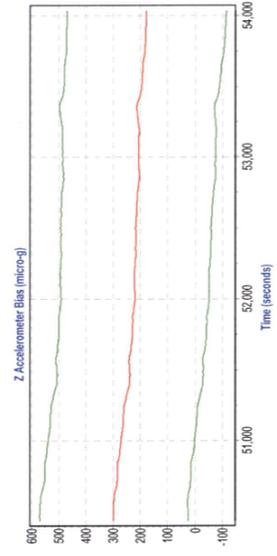
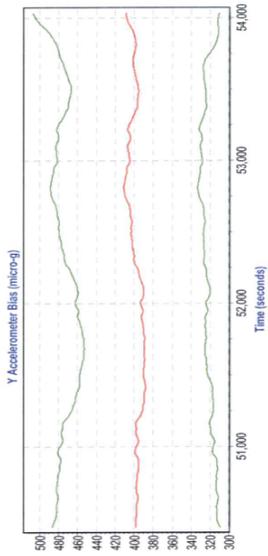
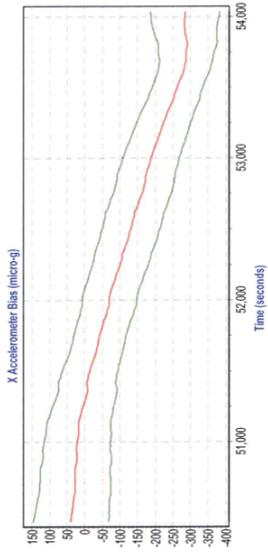
Sensor Errors
- 2 -

POSPac Version 4.3



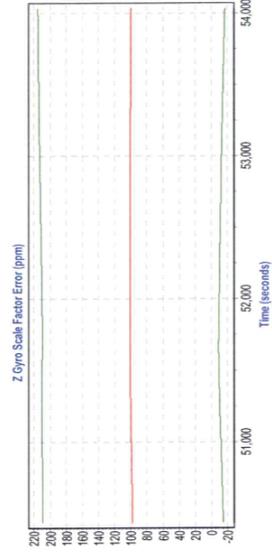
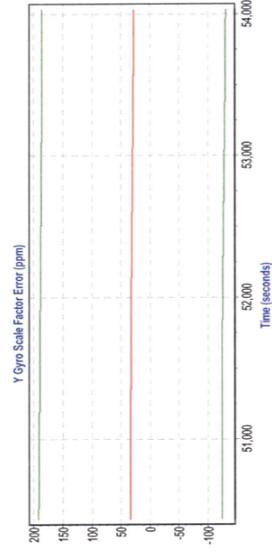
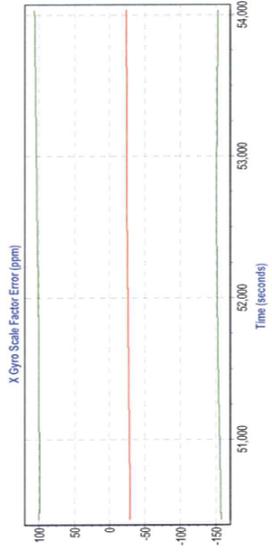
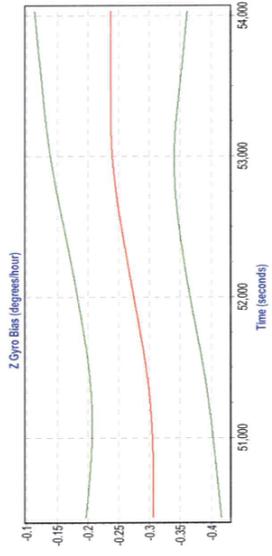
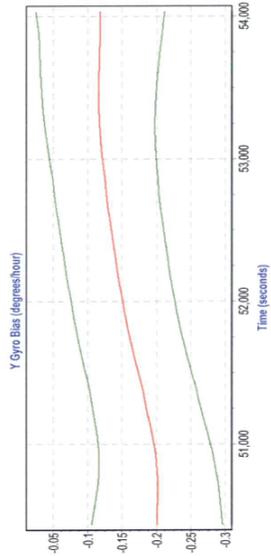
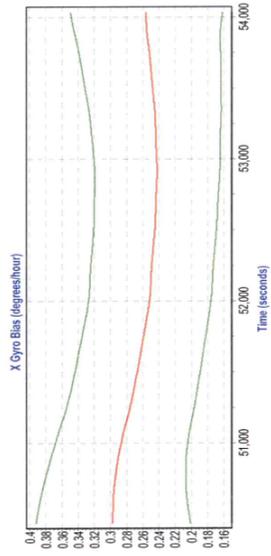
Sensor Errors
- 1 -

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Sensor Errors
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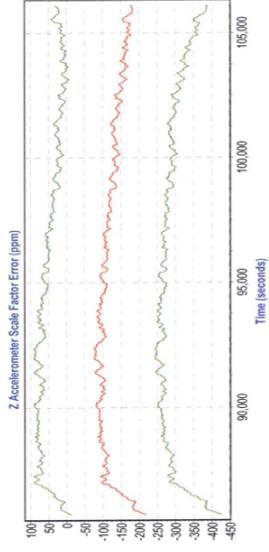
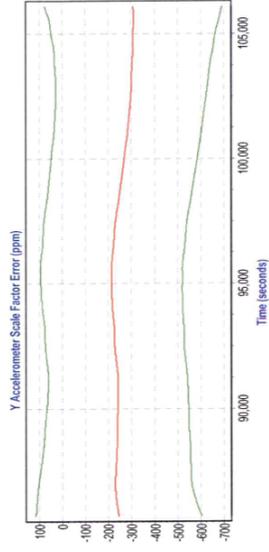
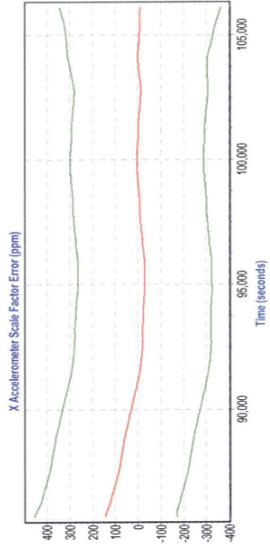
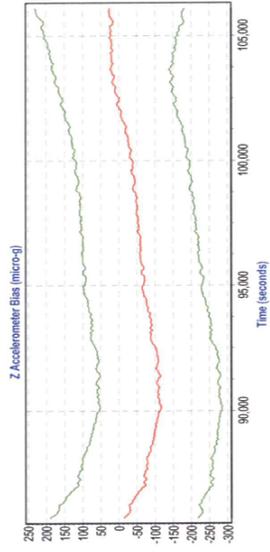
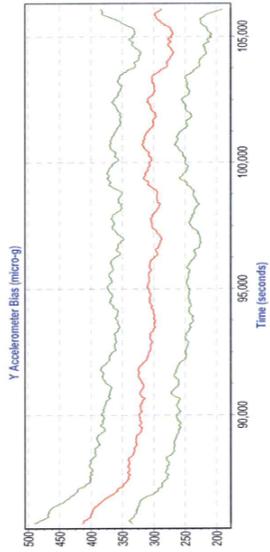
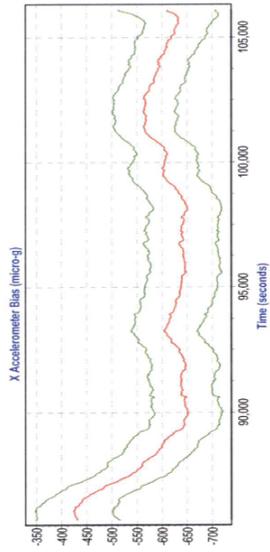
POSPac Version 4.3

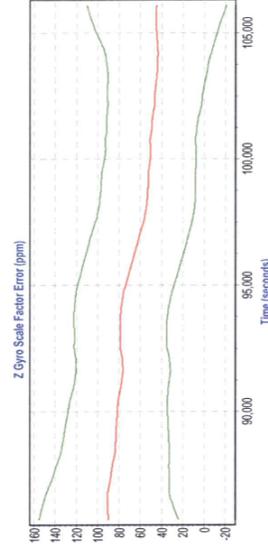
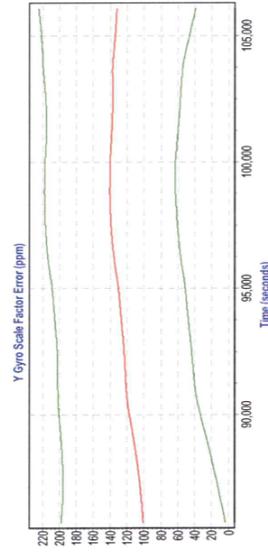
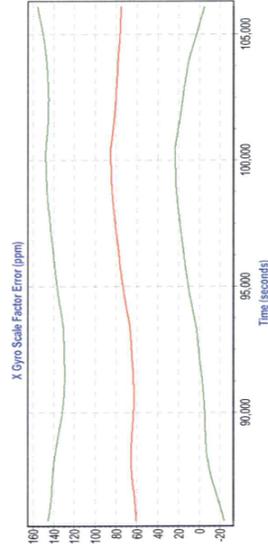
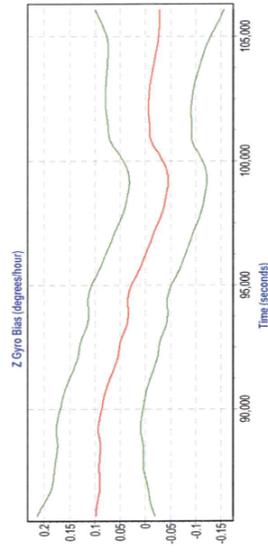
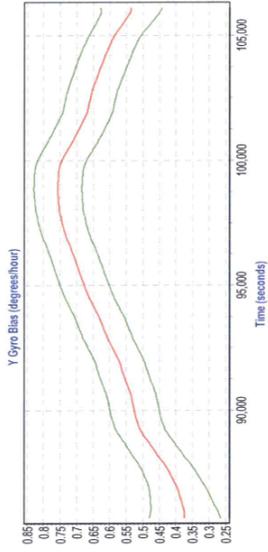
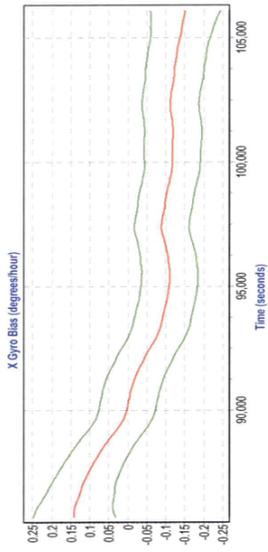


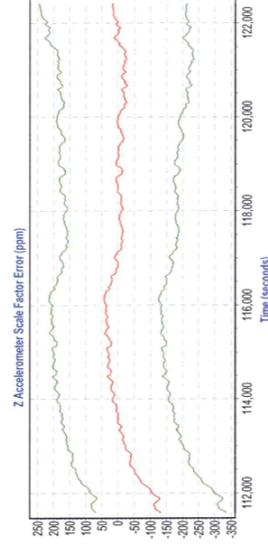
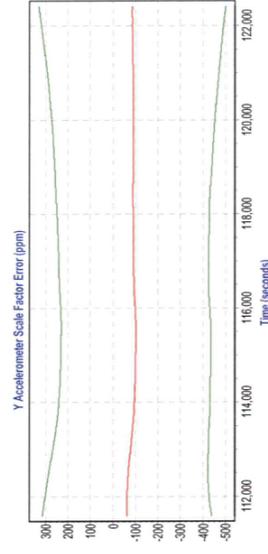
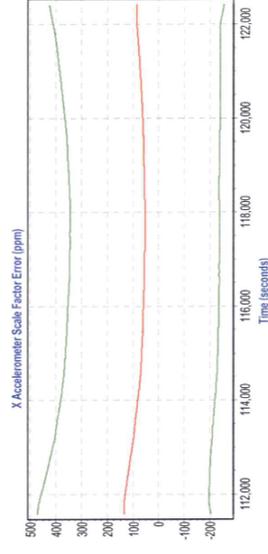
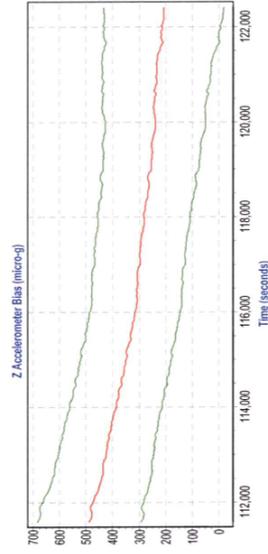
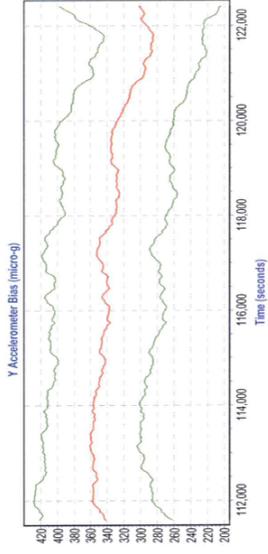
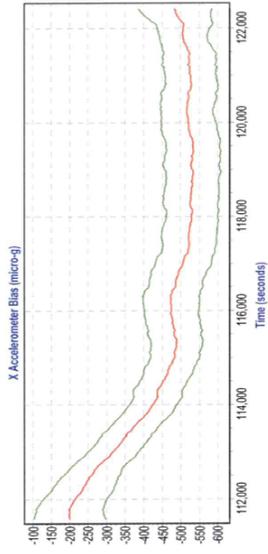
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Sensor Errors
- 1 -

POSPac Version 4.3

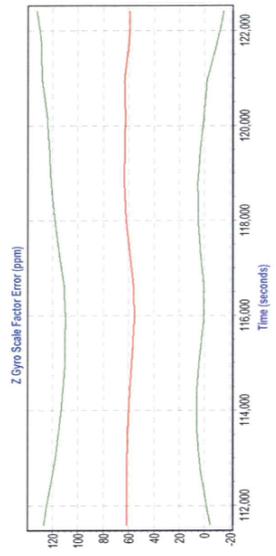
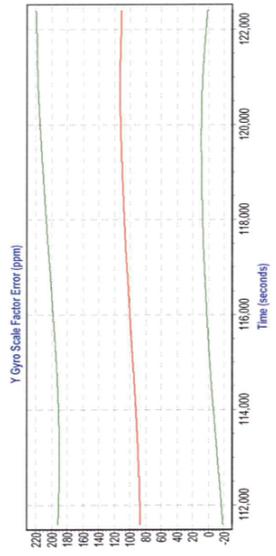
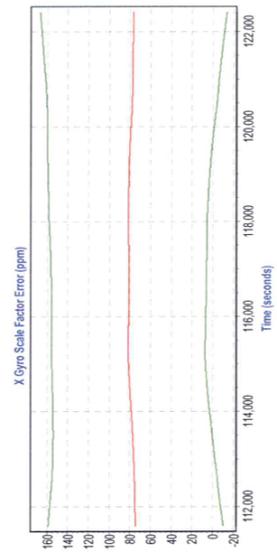
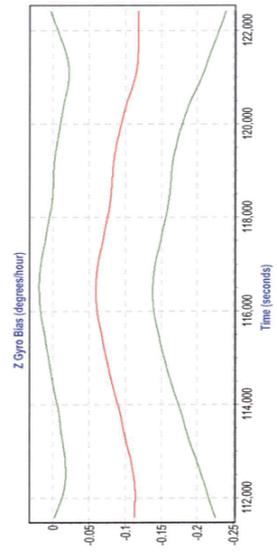
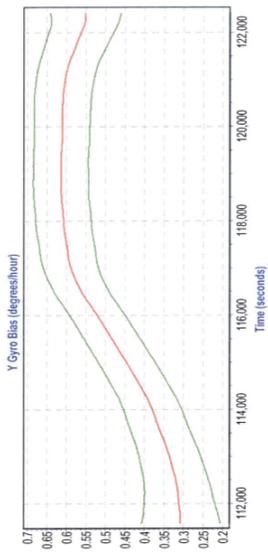
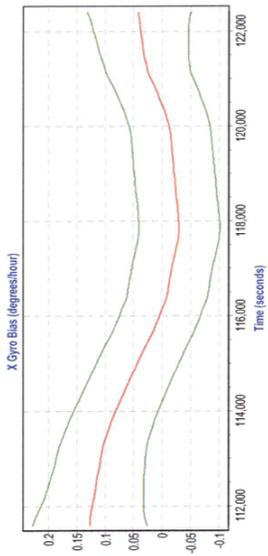






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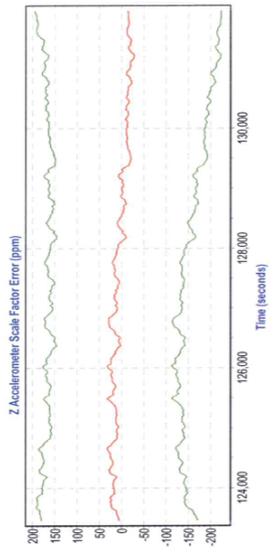
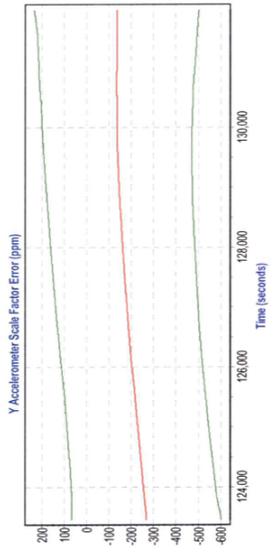
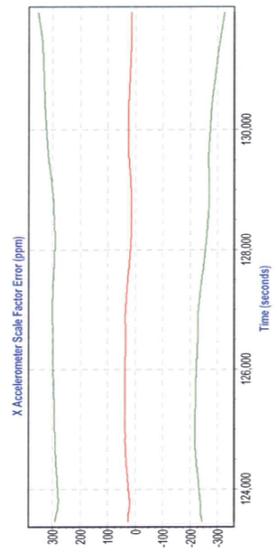
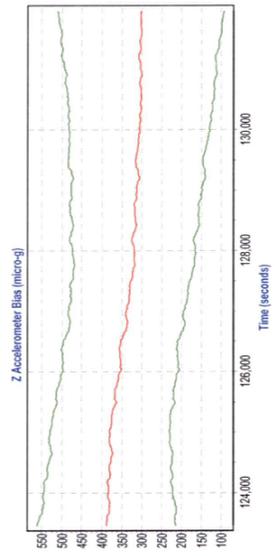
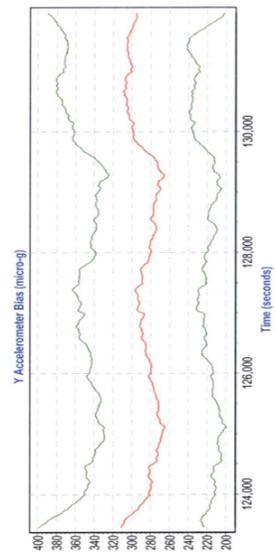
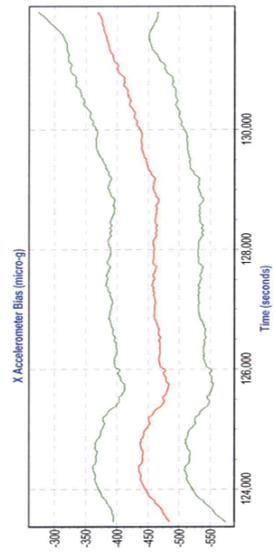
POSPac Version 4.3



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- 1 -

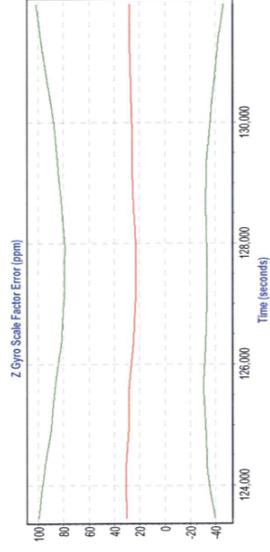
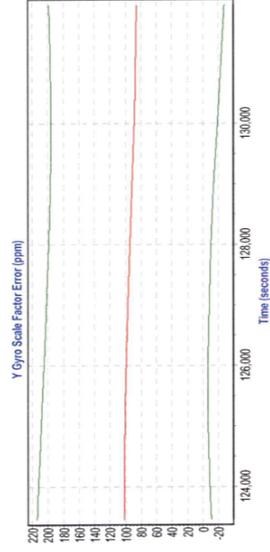
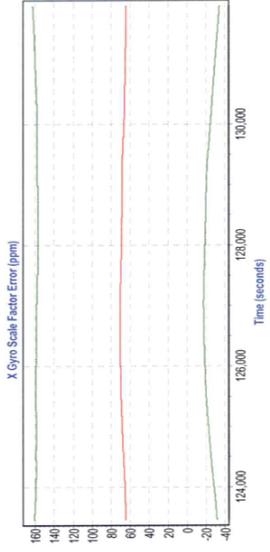
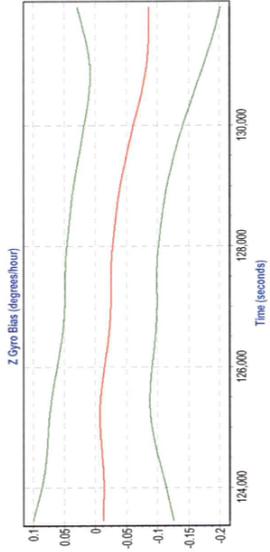
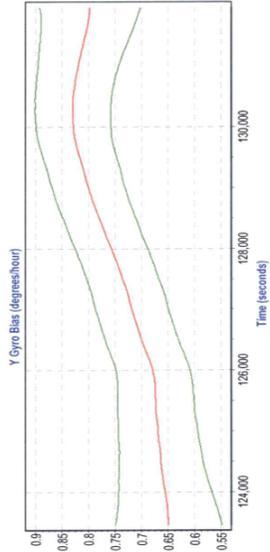
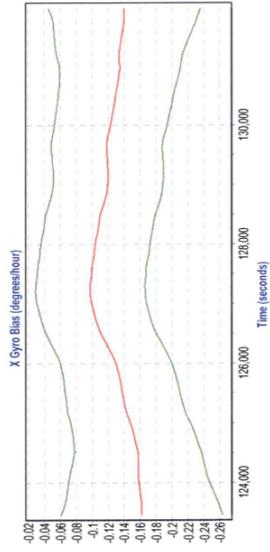
POSPac Version 4.3



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- 2 -

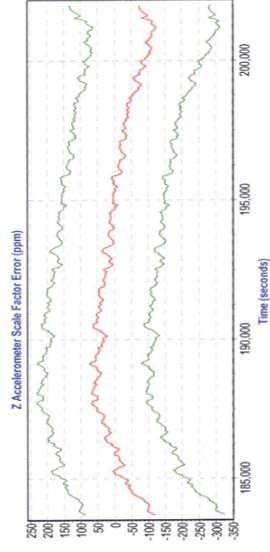
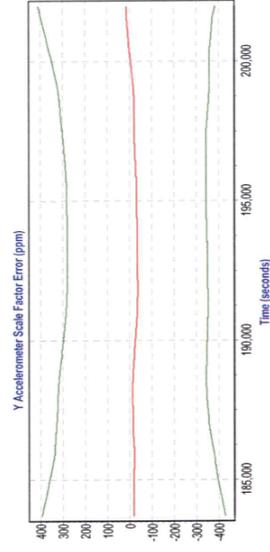
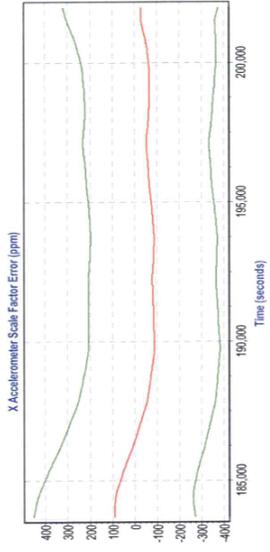
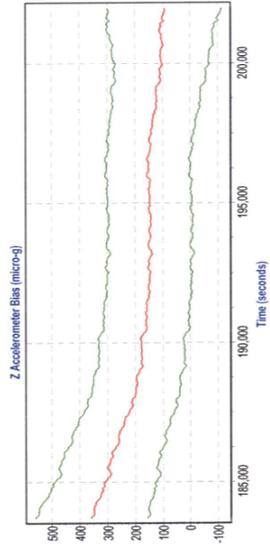
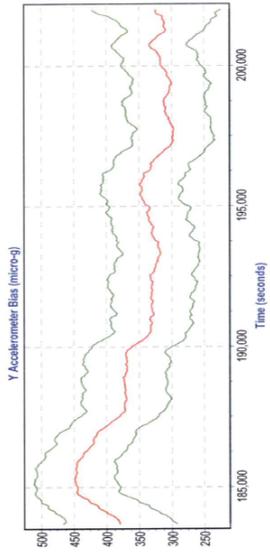
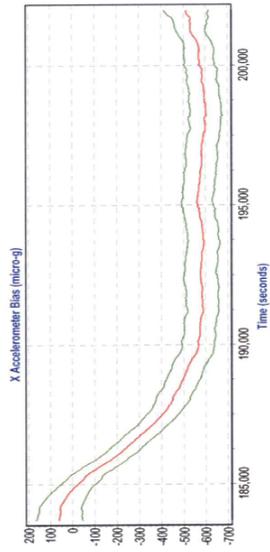
POSPac Version 4.3



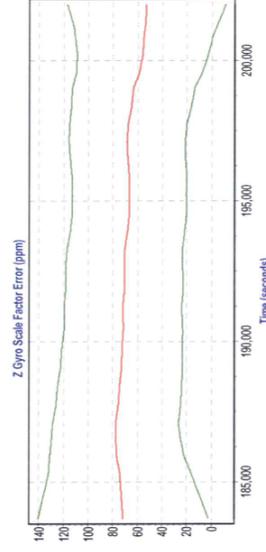
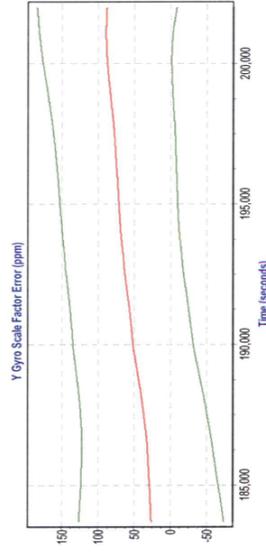
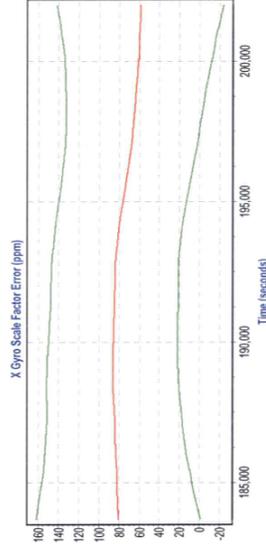
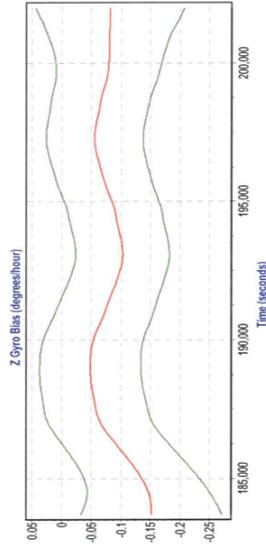
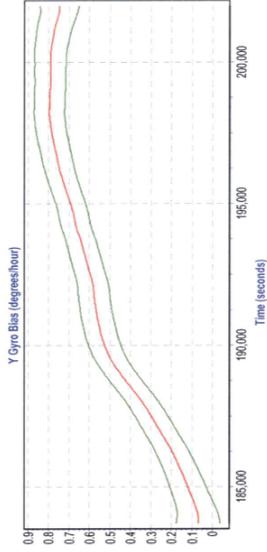
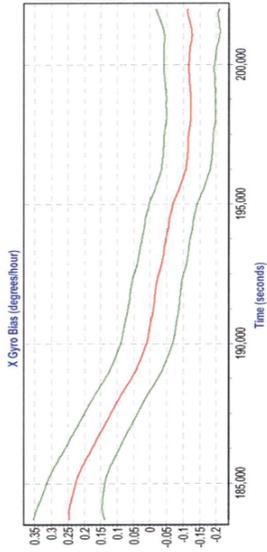
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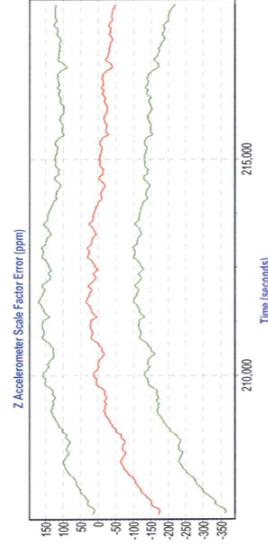
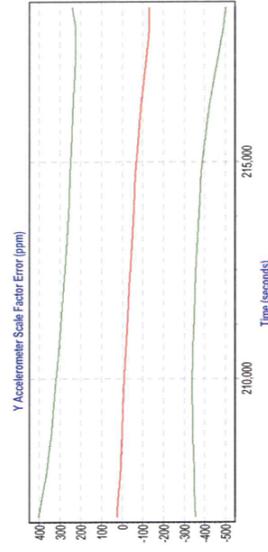
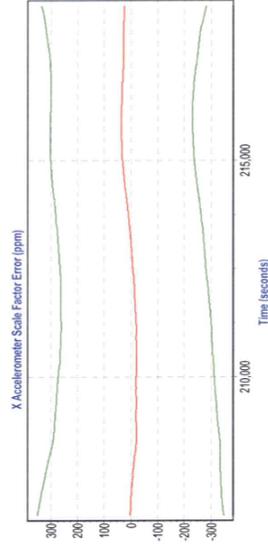
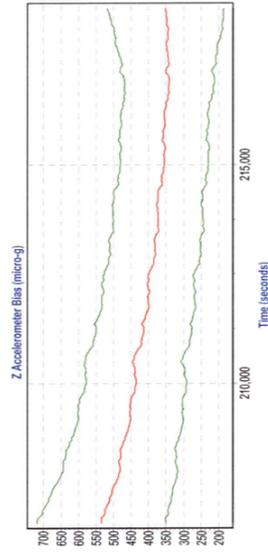
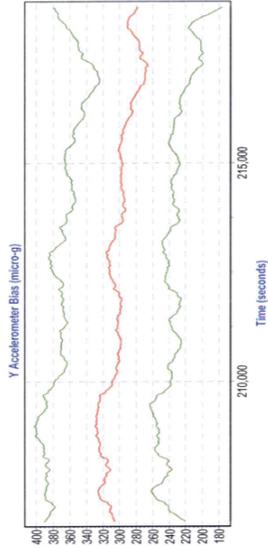
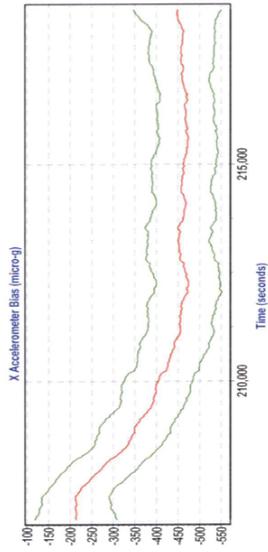
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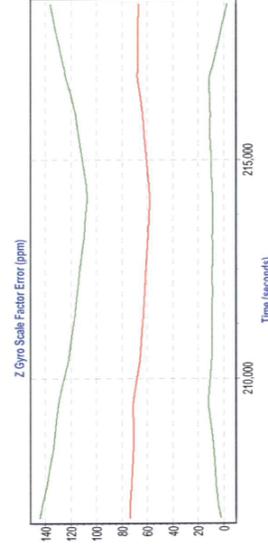
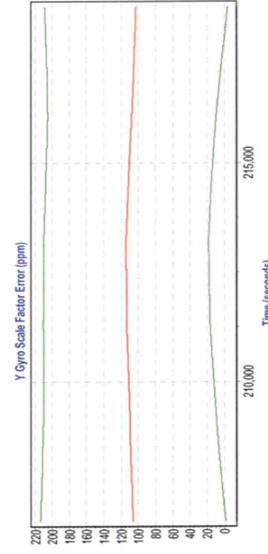
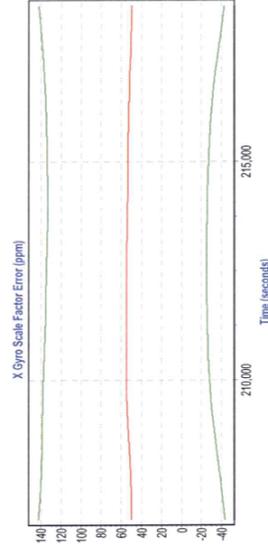
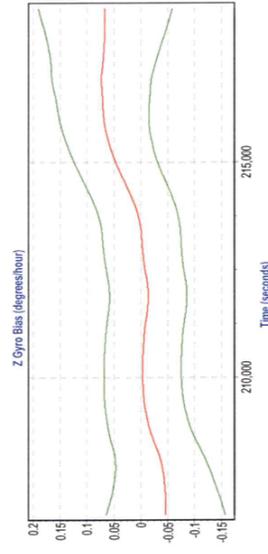
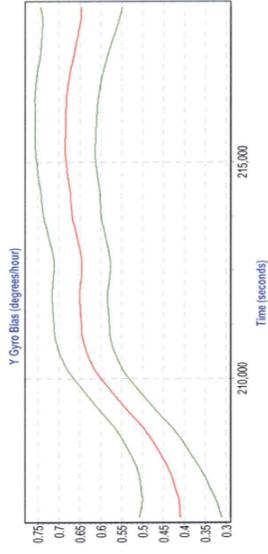
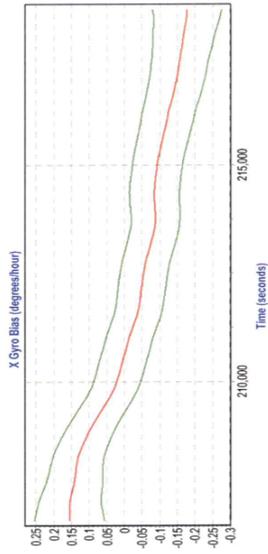
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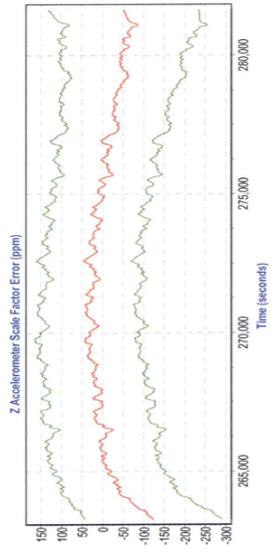
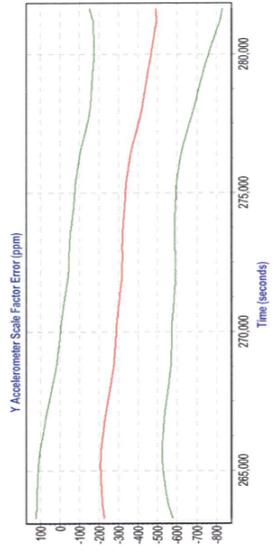
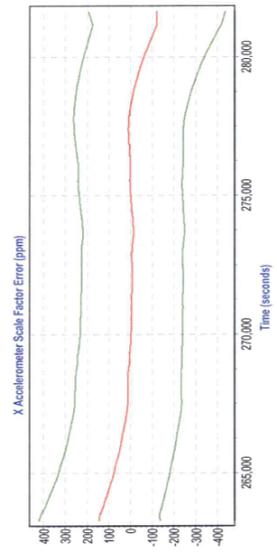
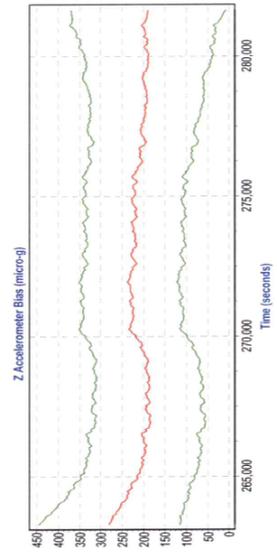
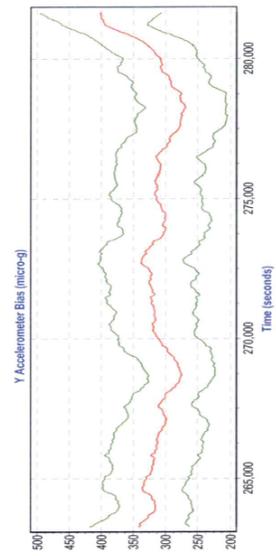
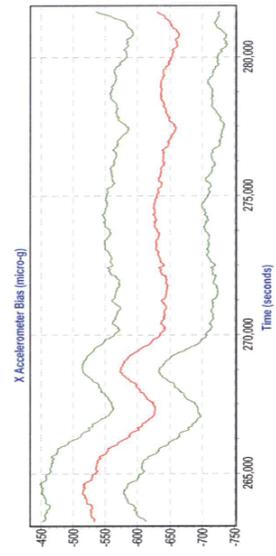






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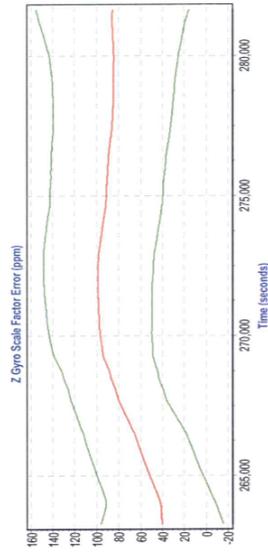
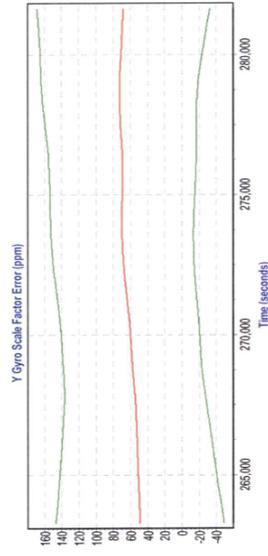
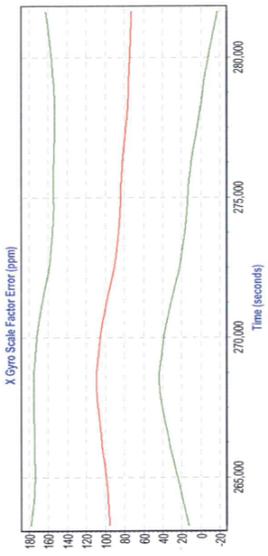
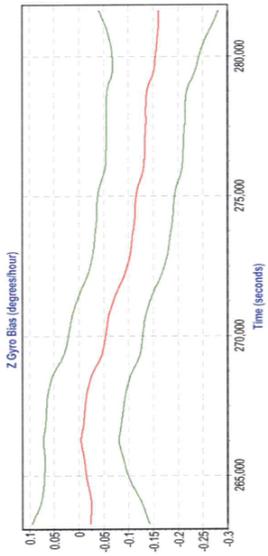
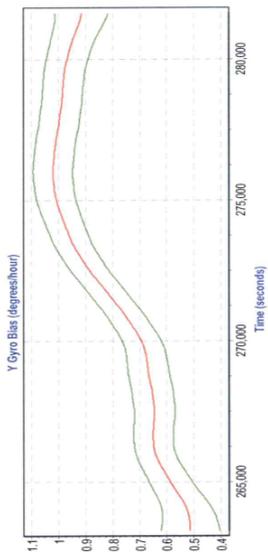
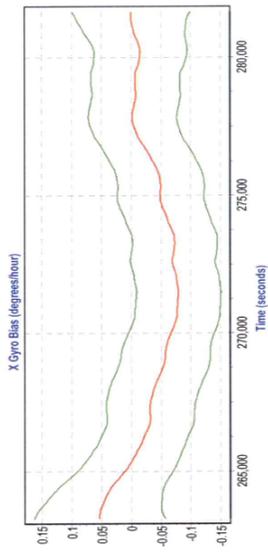
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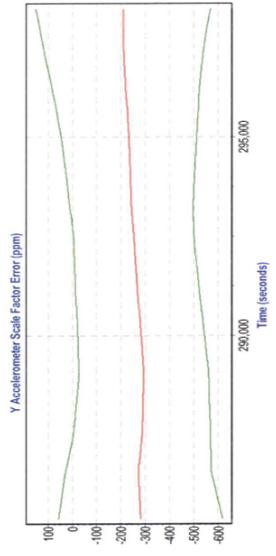
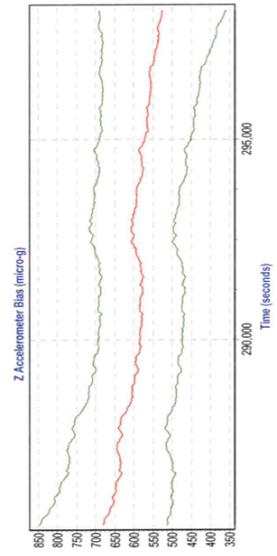
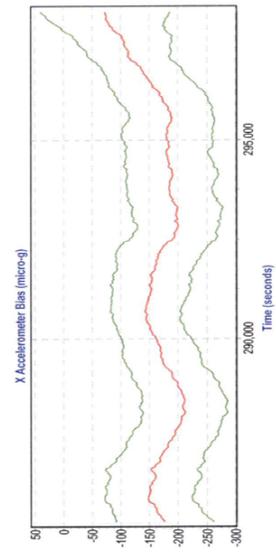
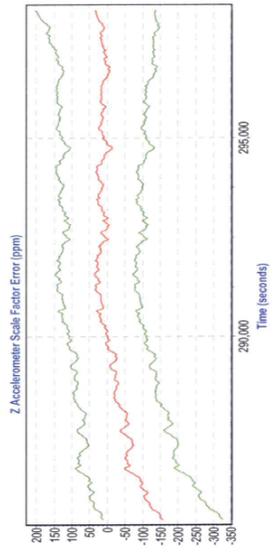
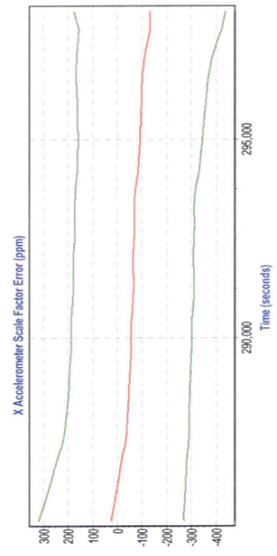
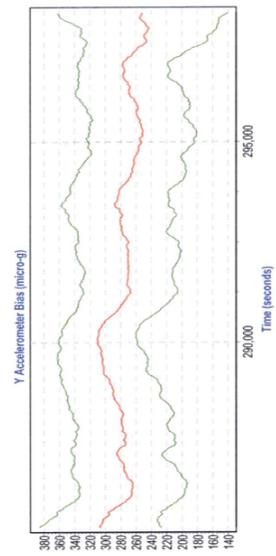
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- 2 -

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Sensor Errors
- 1 -

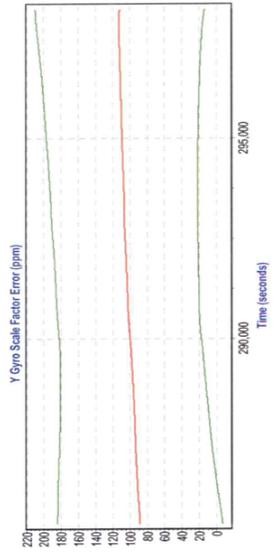
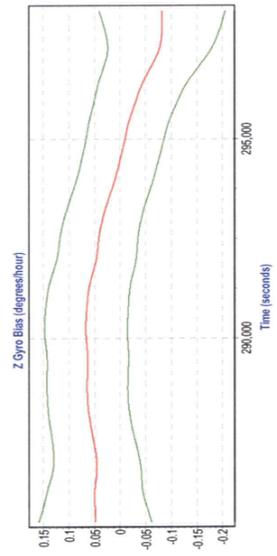
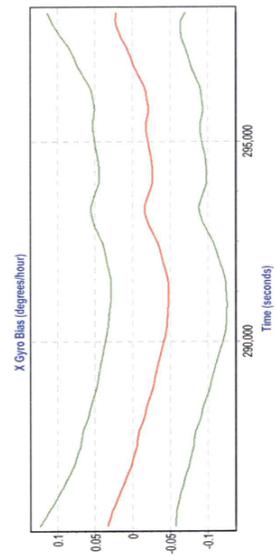
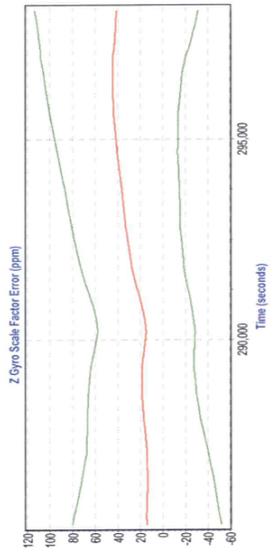
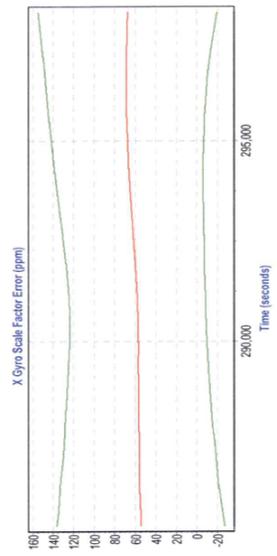
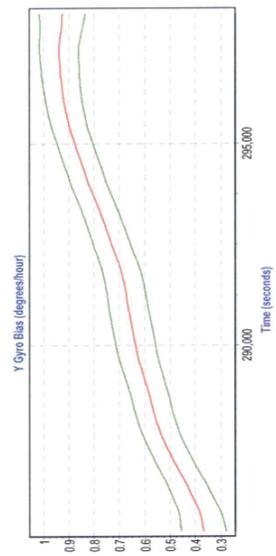
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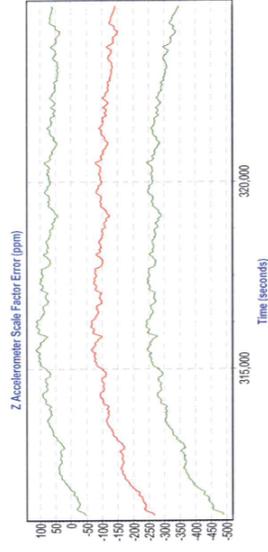
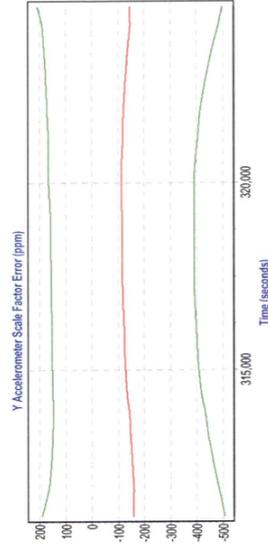
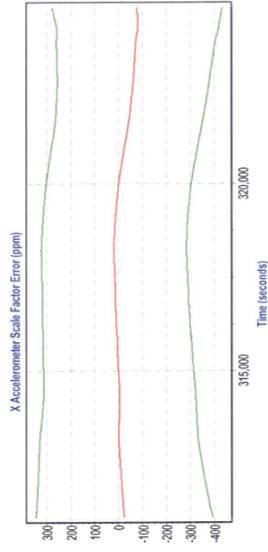
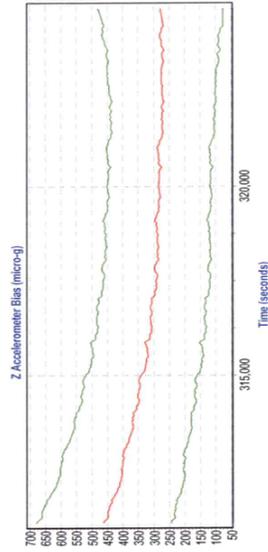
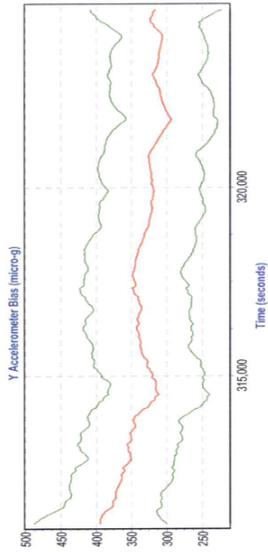
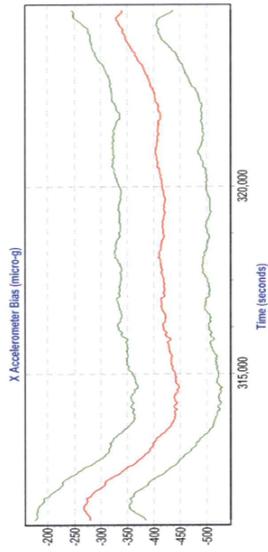
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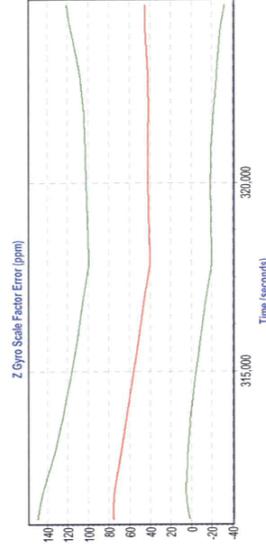
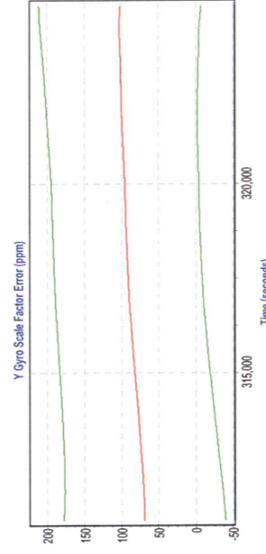
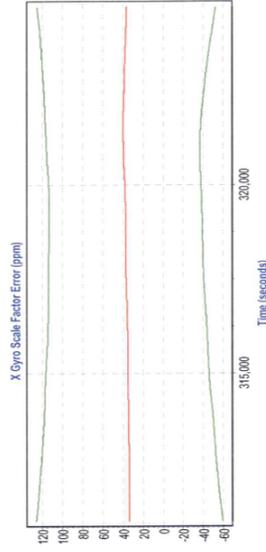
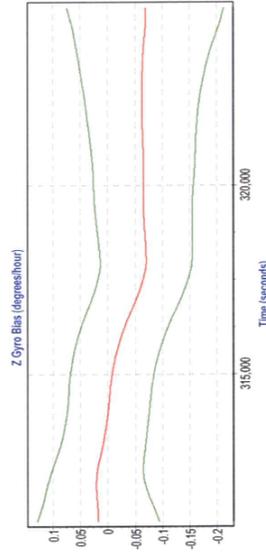
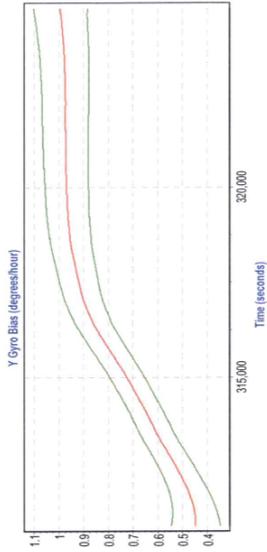
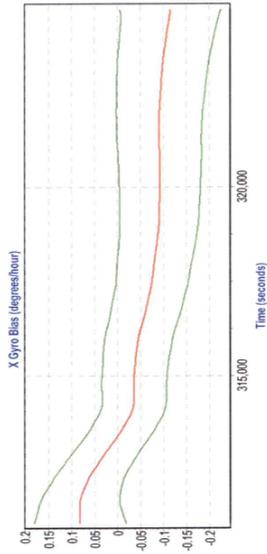
Sensor Errors
- 2 -

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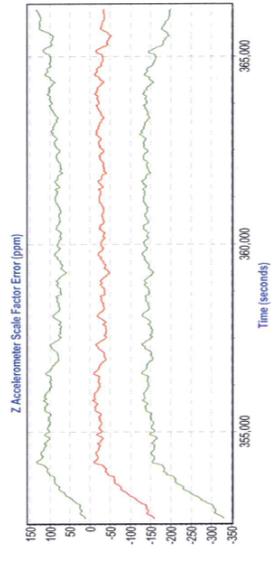
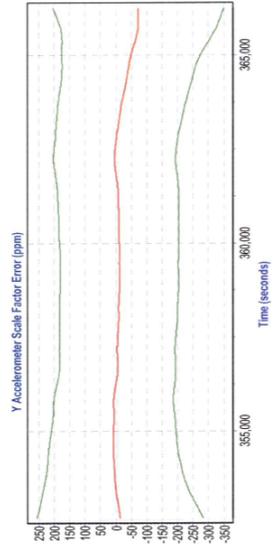
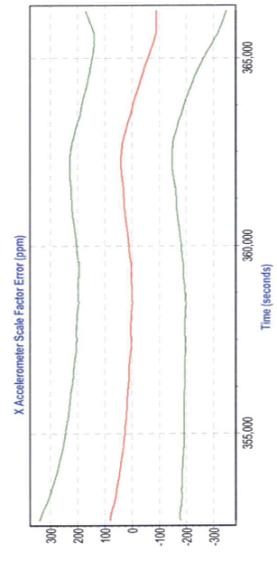
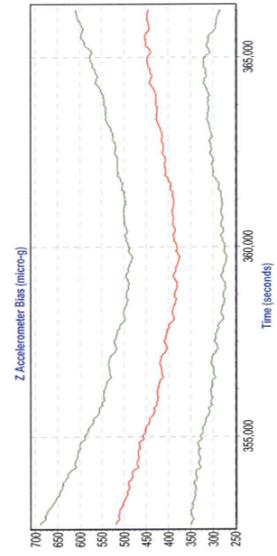
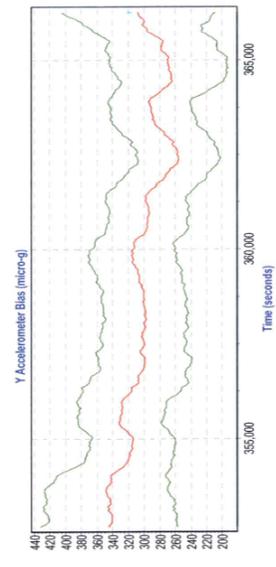
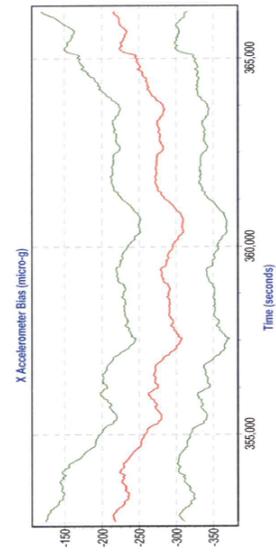
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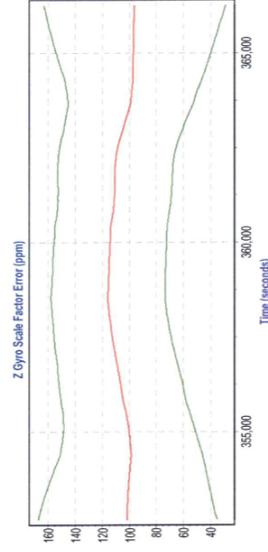
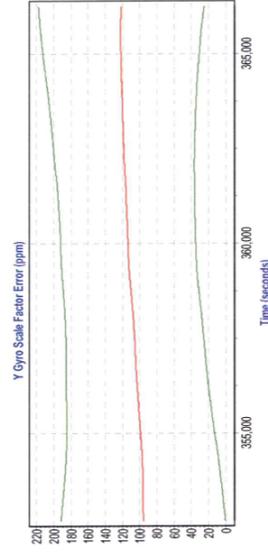
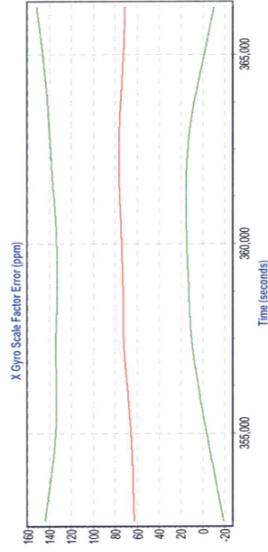
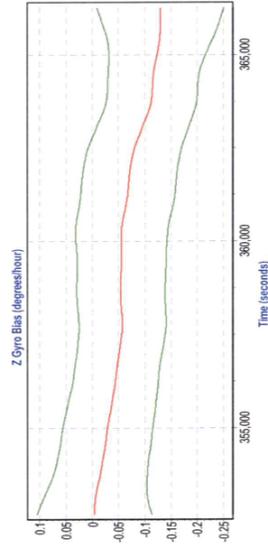
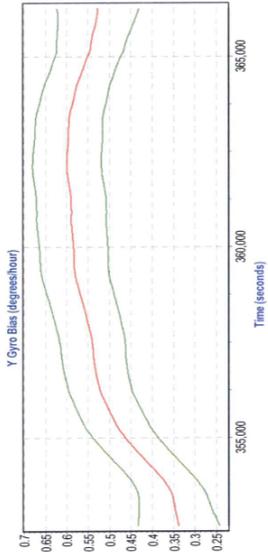
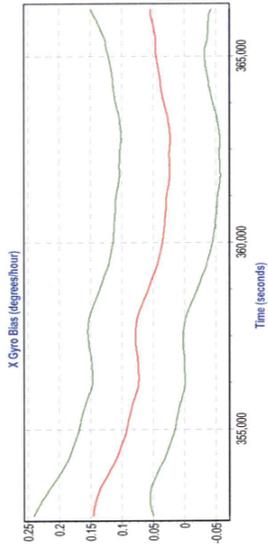




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- 1 -

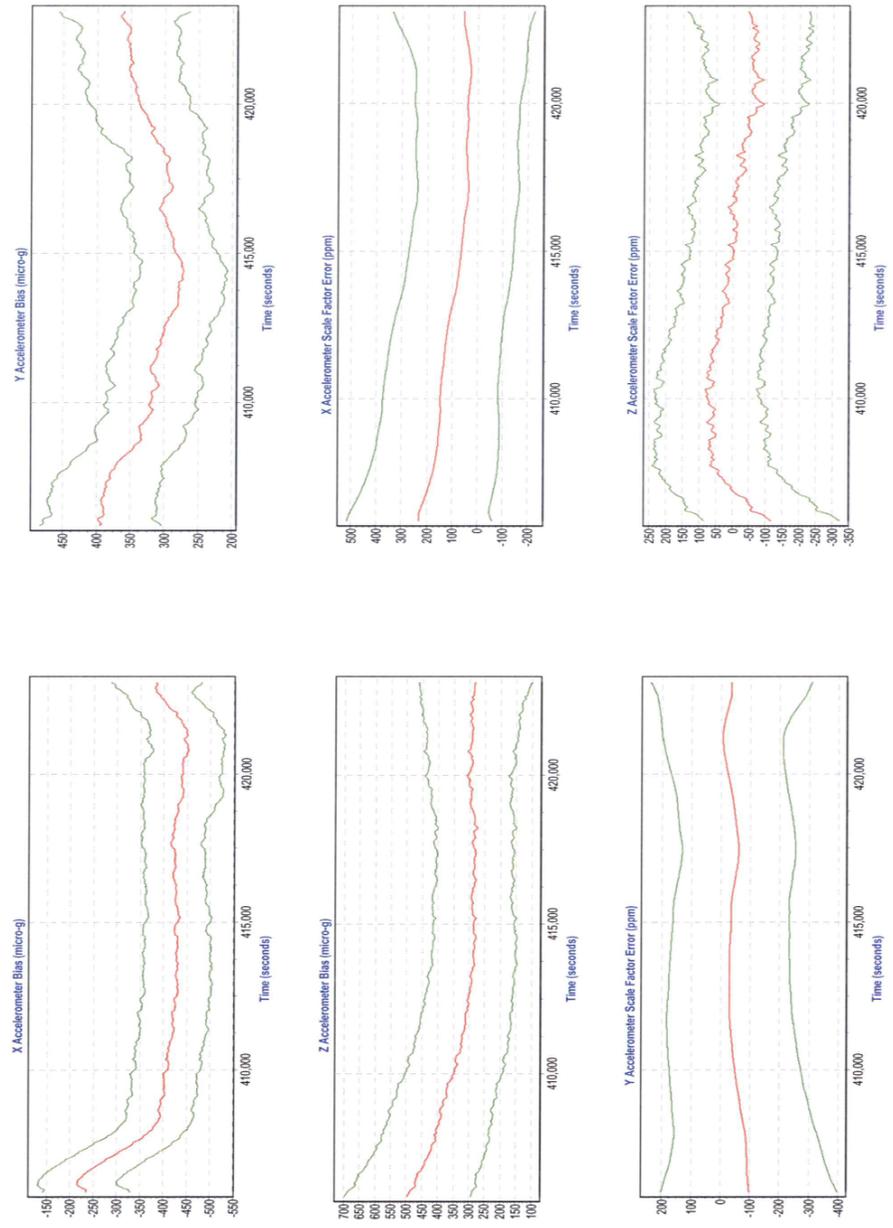
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Sensor Errors
- 1 -

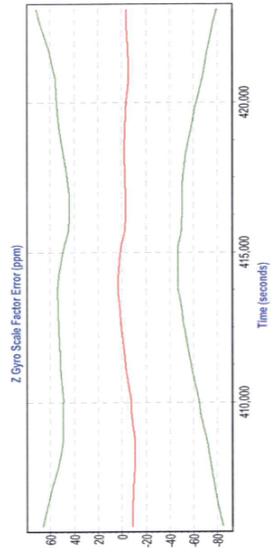
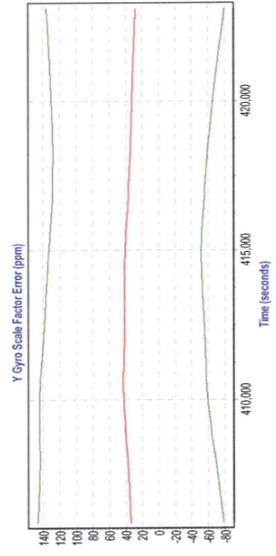
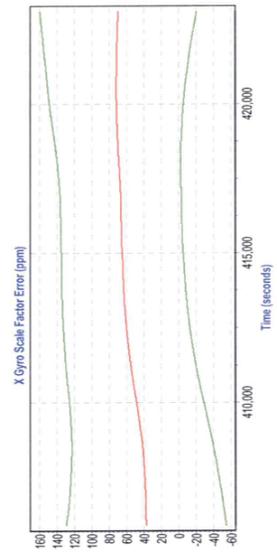
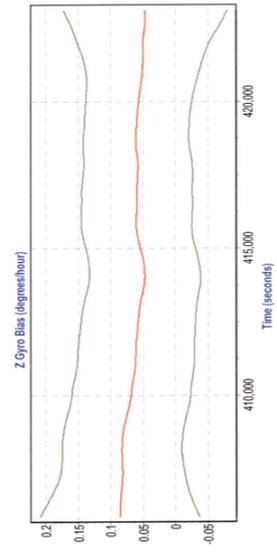
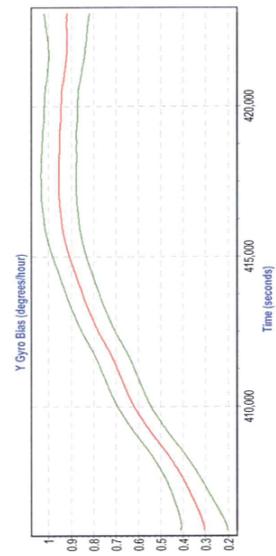
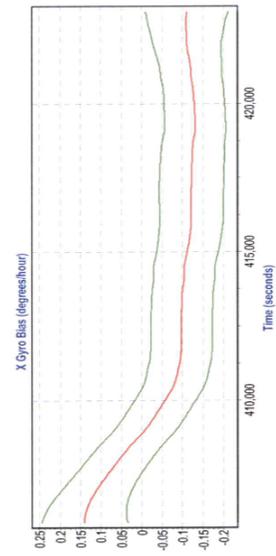
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- 2 -

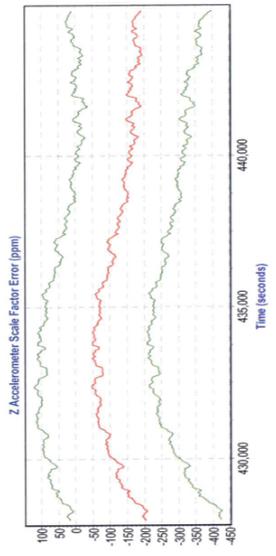
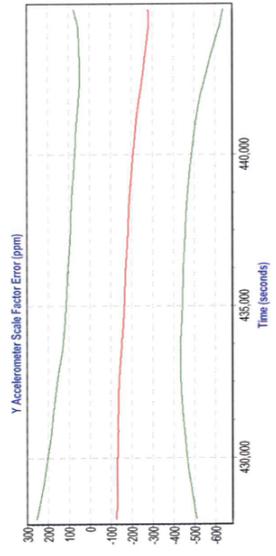
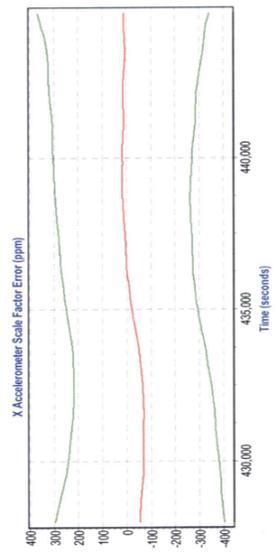
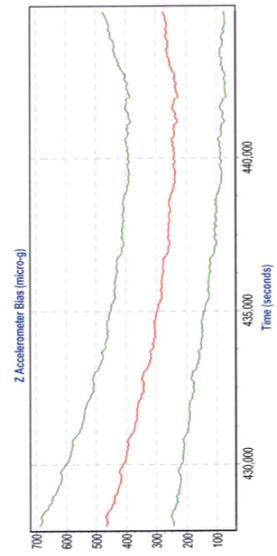
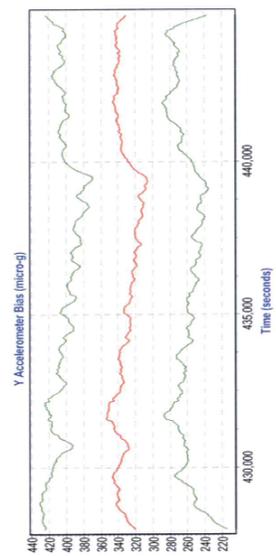
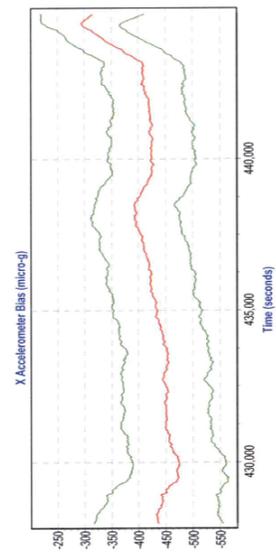
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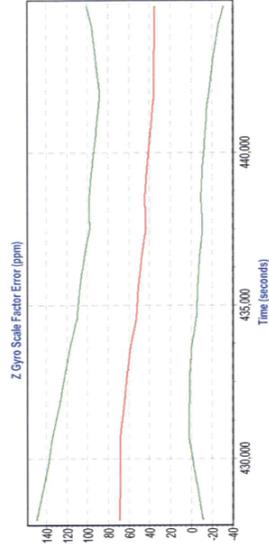
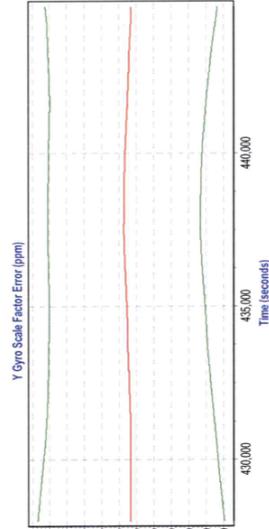
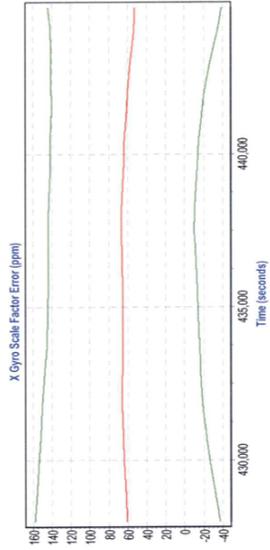
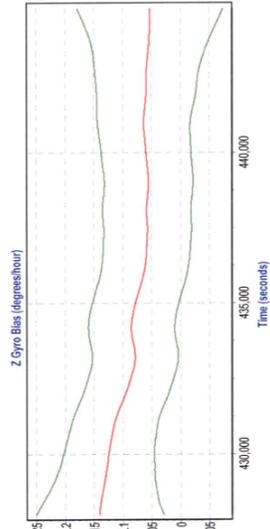
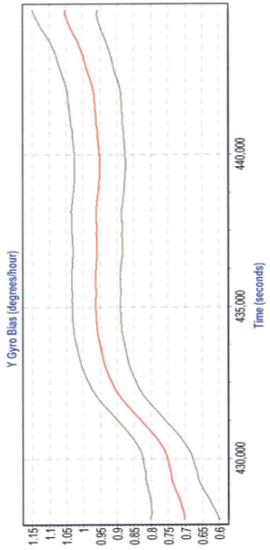
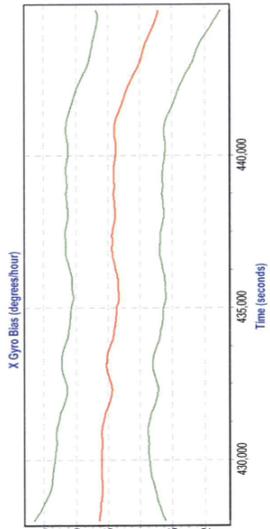
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Sensor Errors
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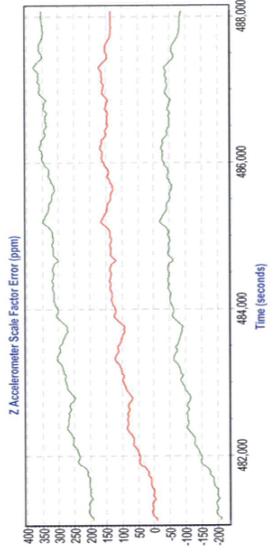
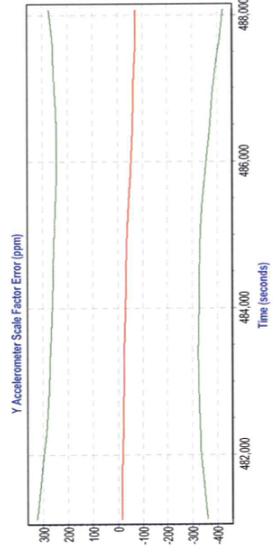
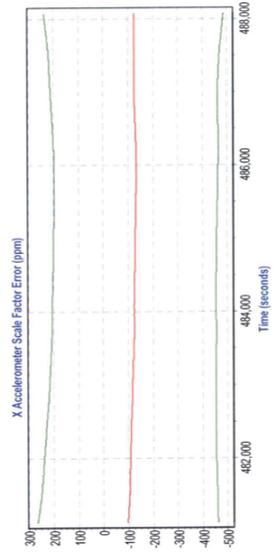
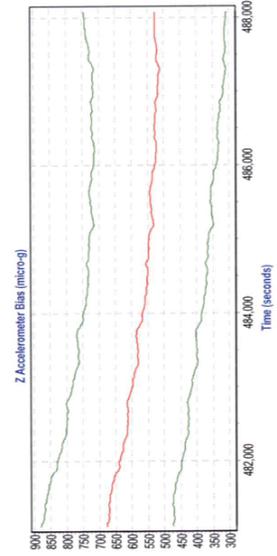
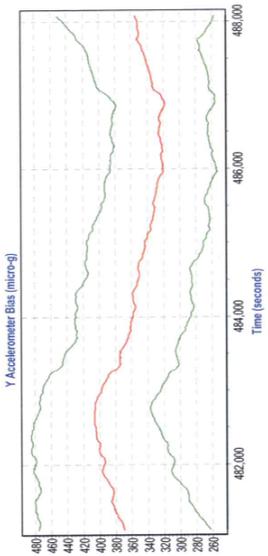
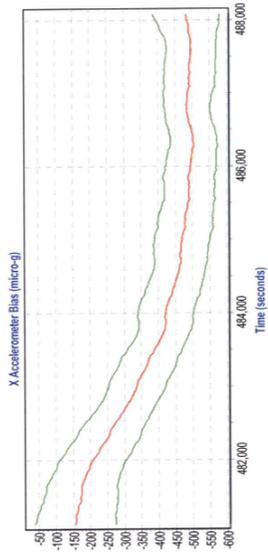


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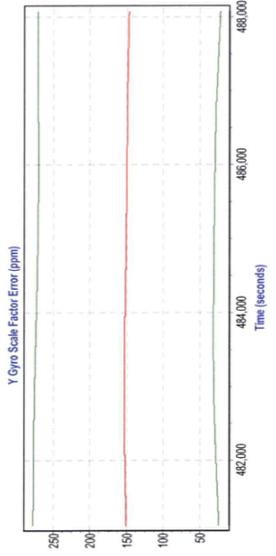
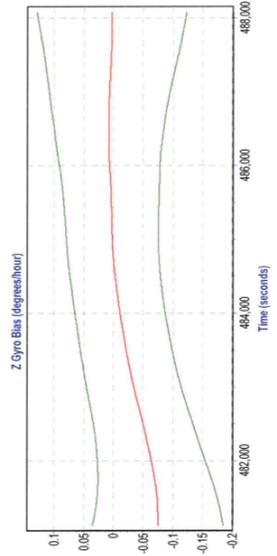
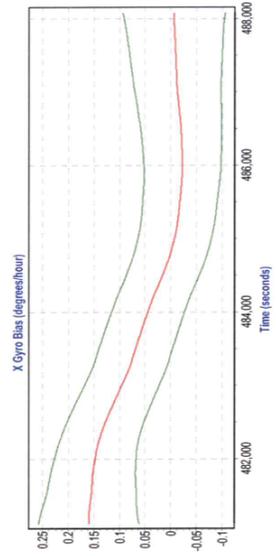
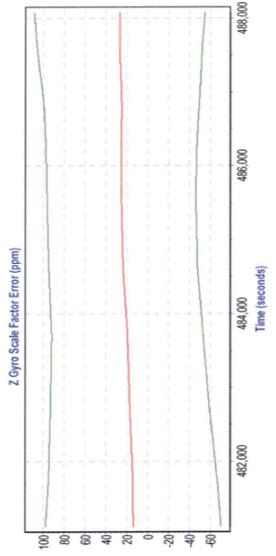
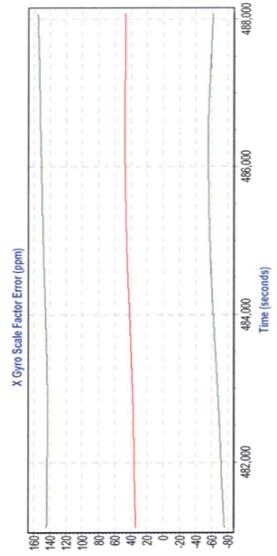
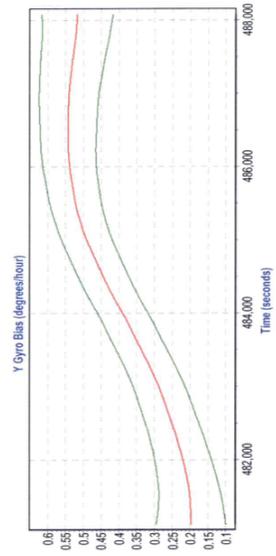


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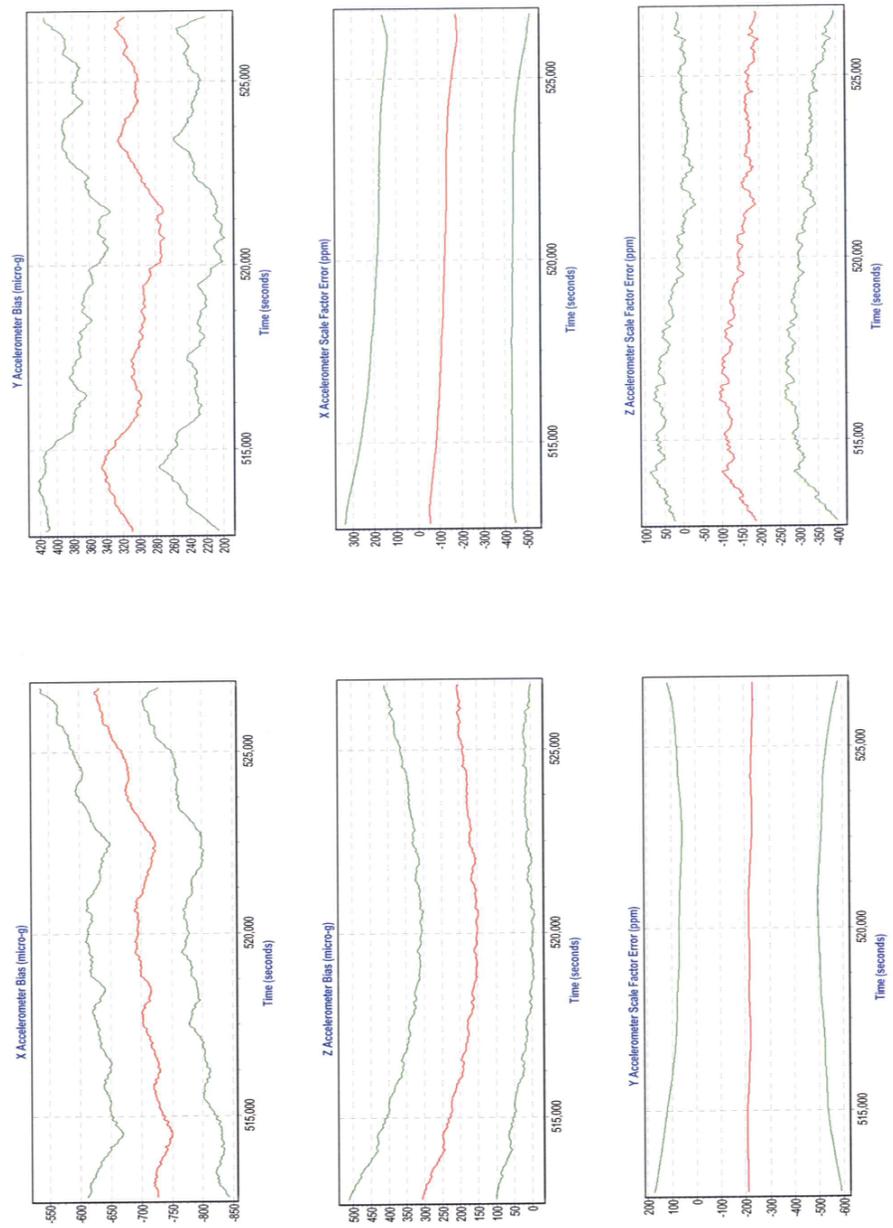
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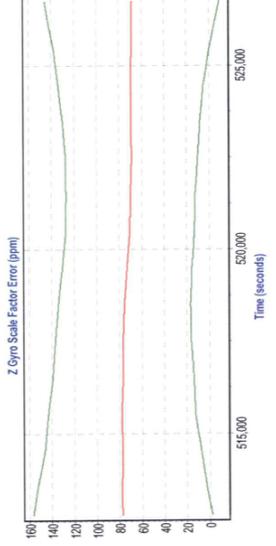
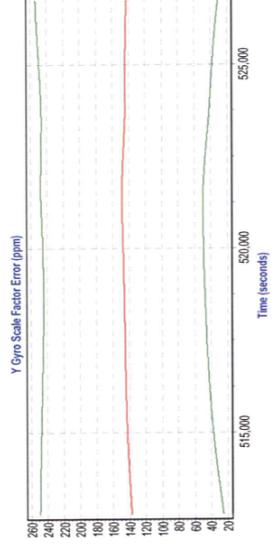
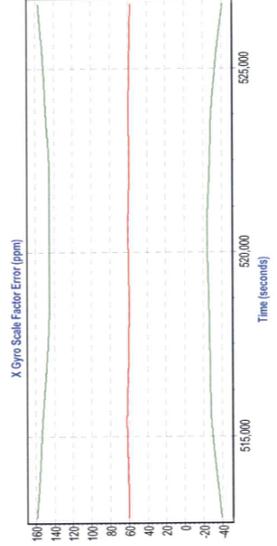
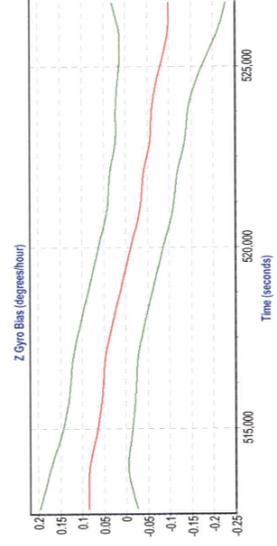
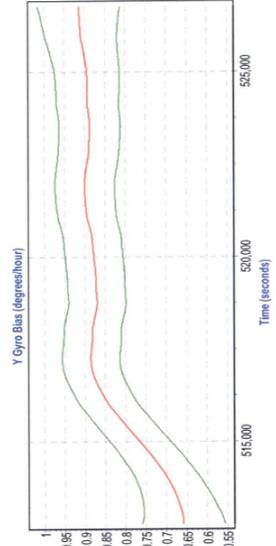
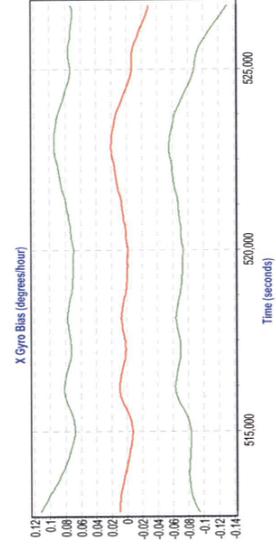
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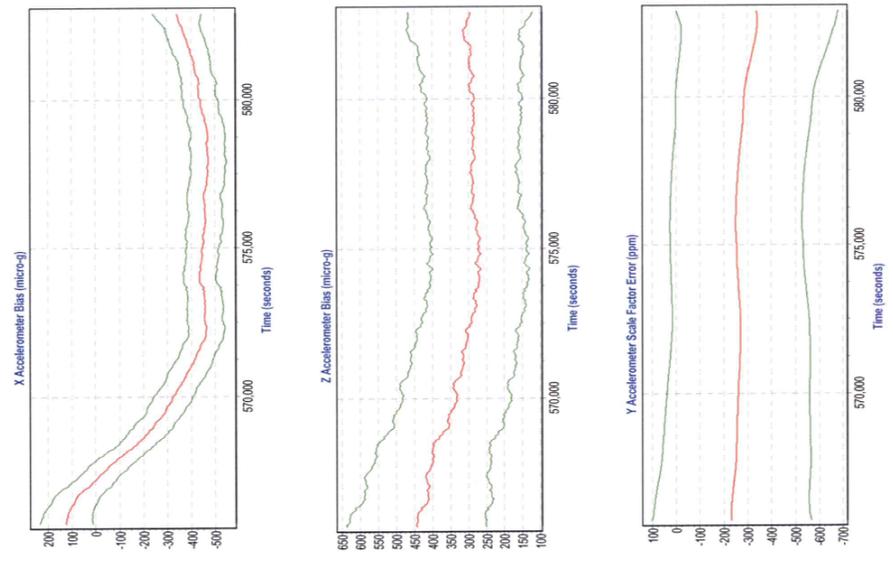
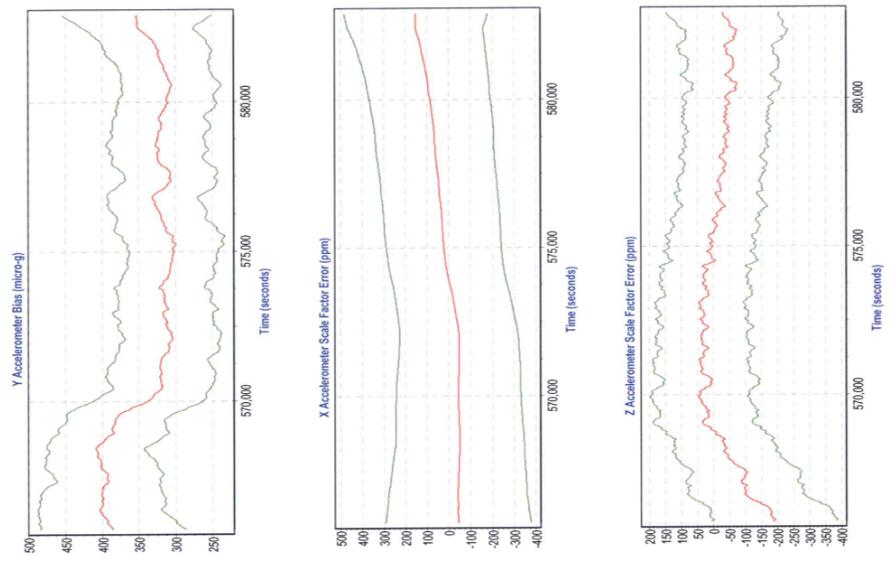


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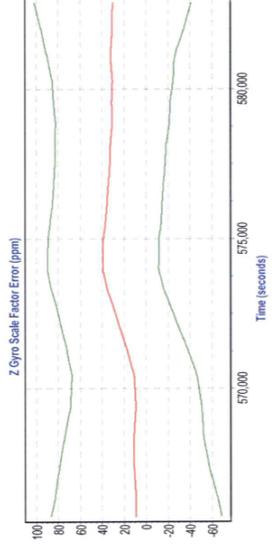
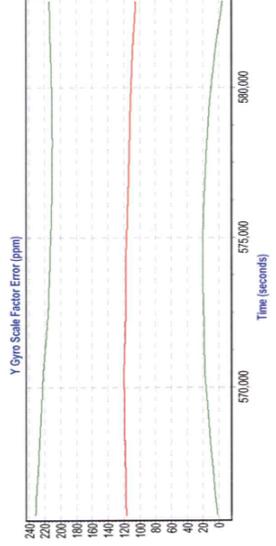
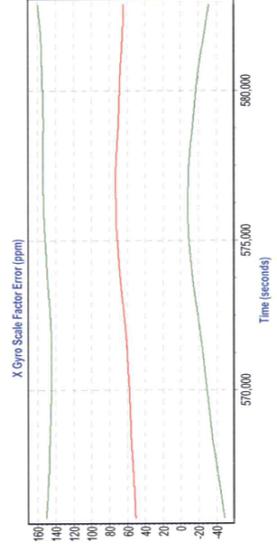
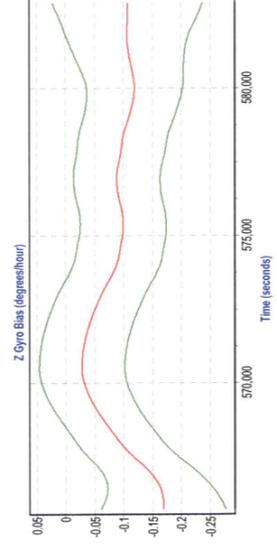
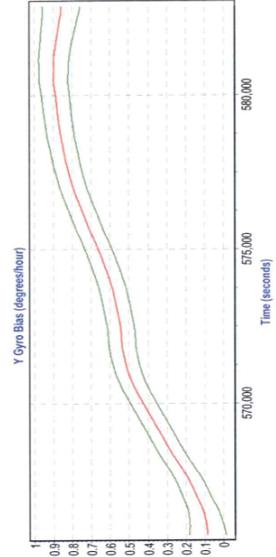
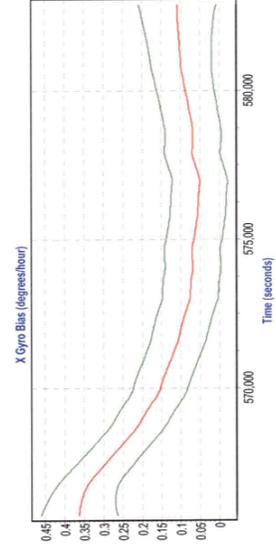


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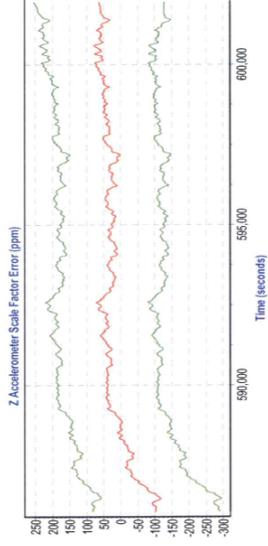
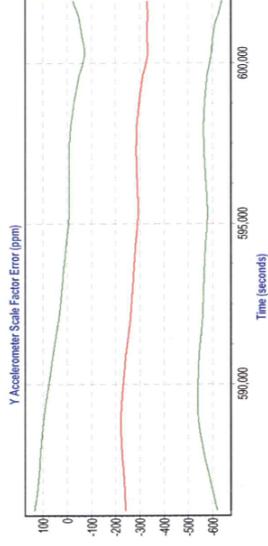
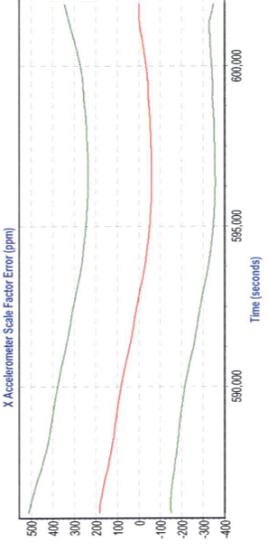
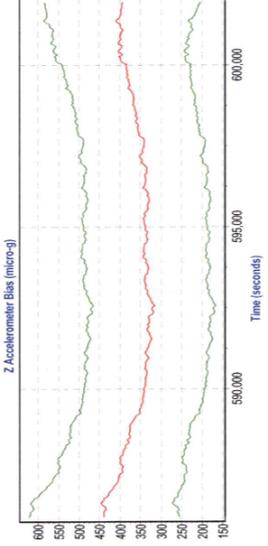
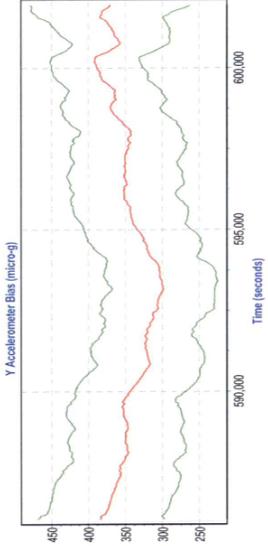
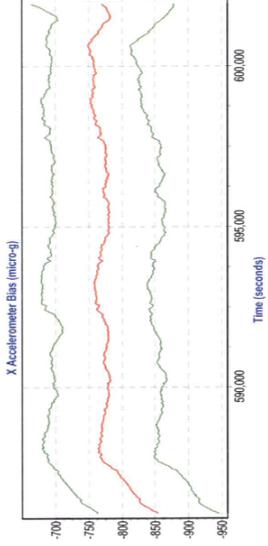
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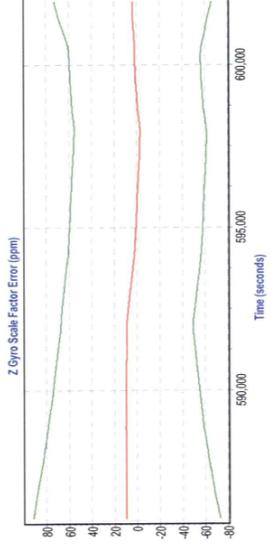
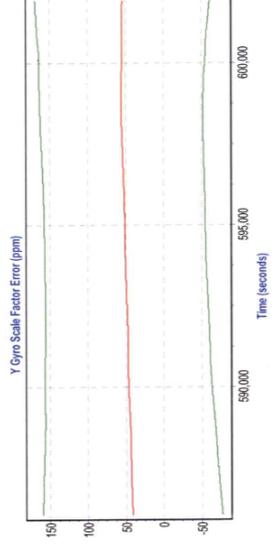
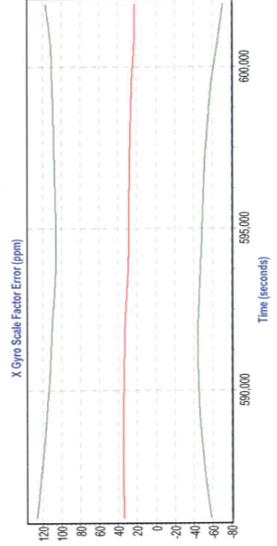
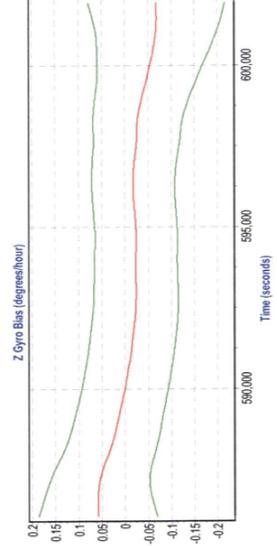
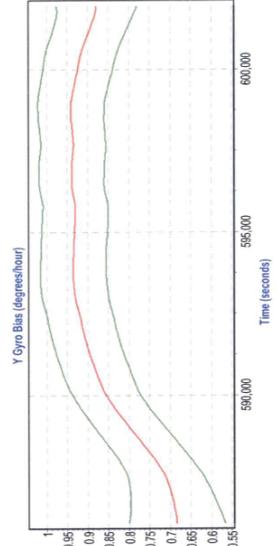
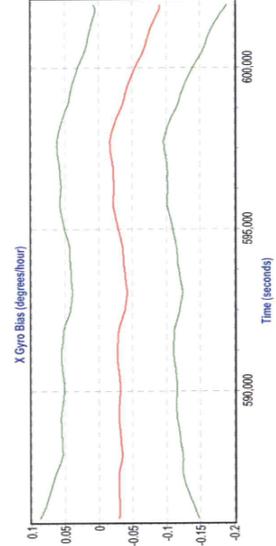
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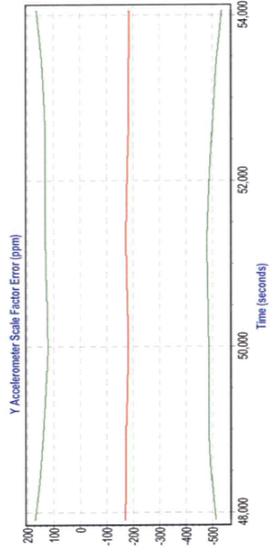
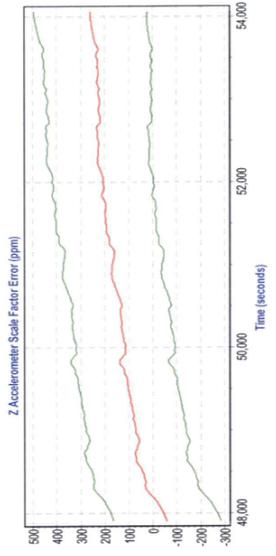
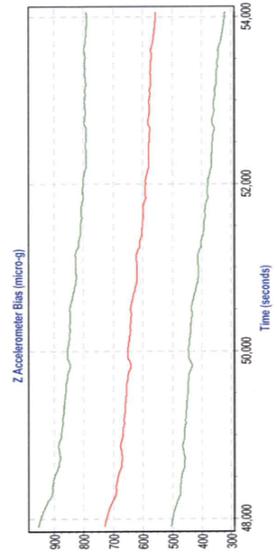
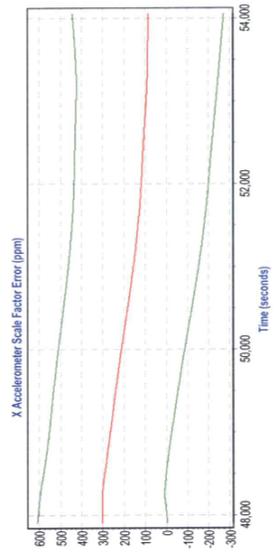
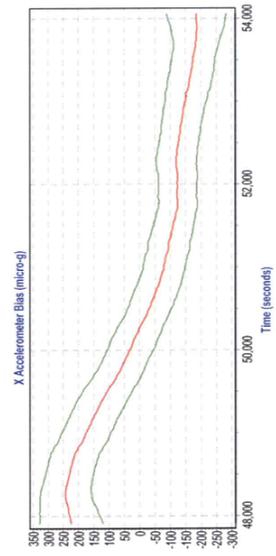
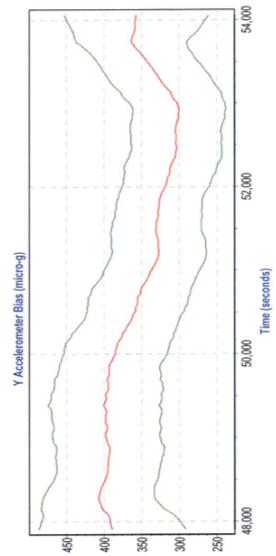


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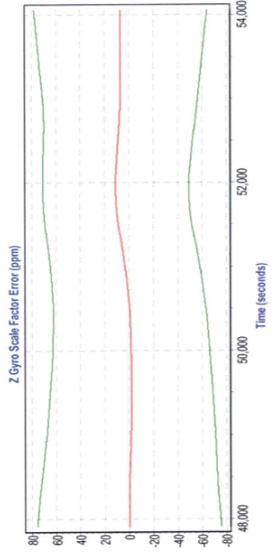
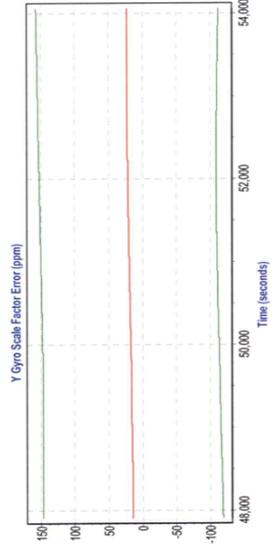
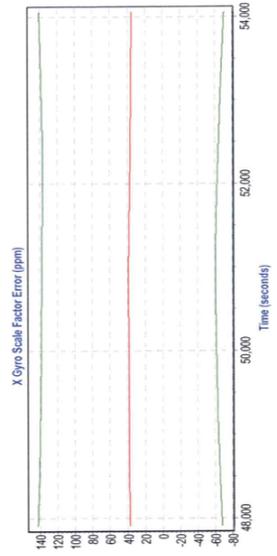
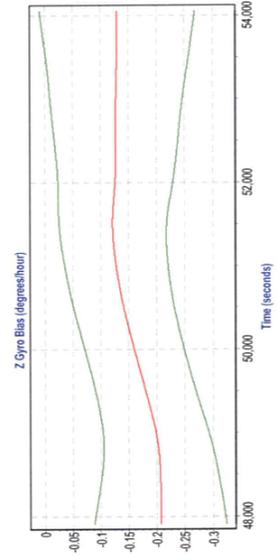
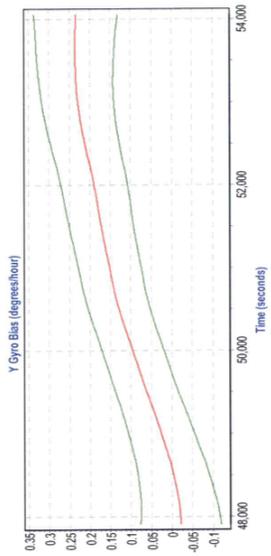
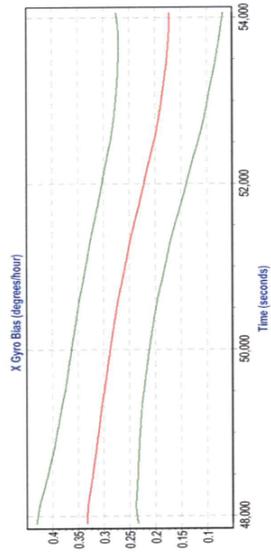
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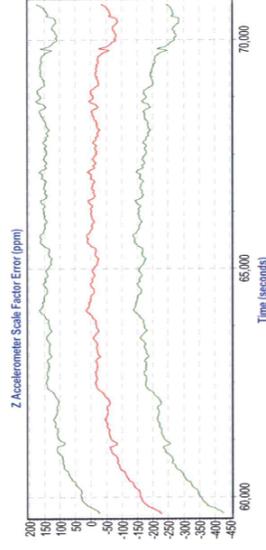
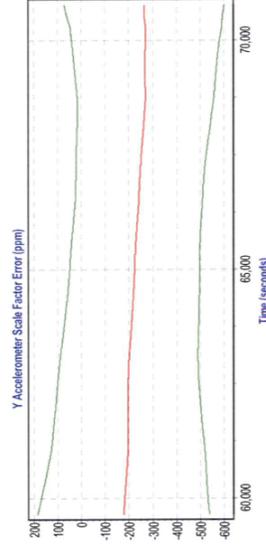
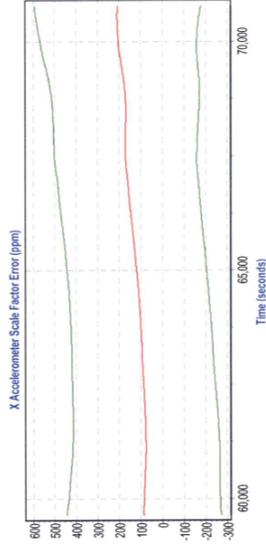
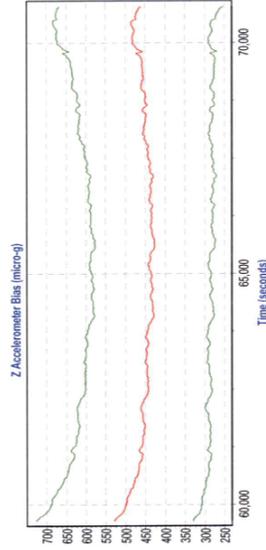
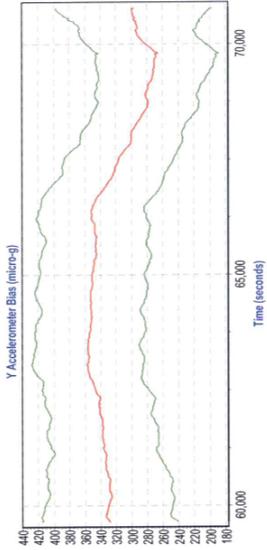
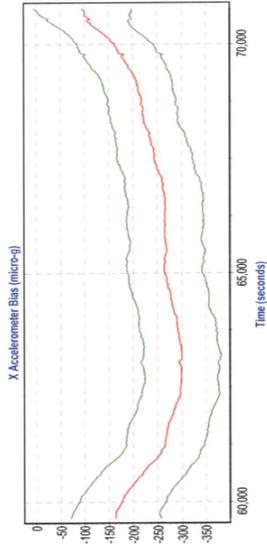


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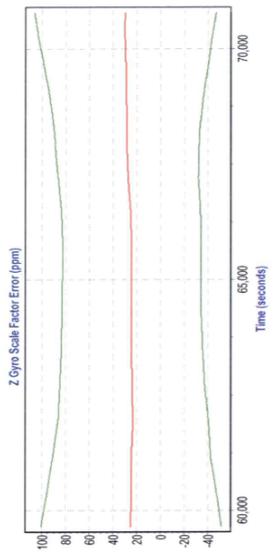
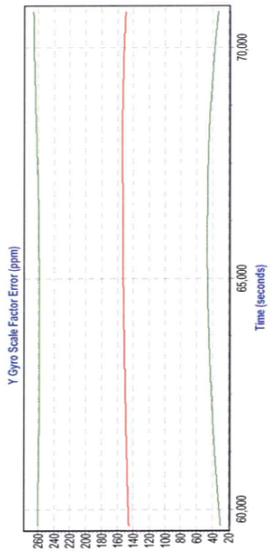
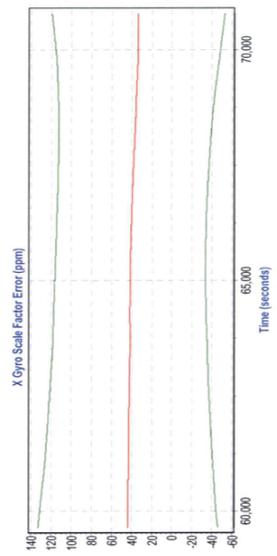
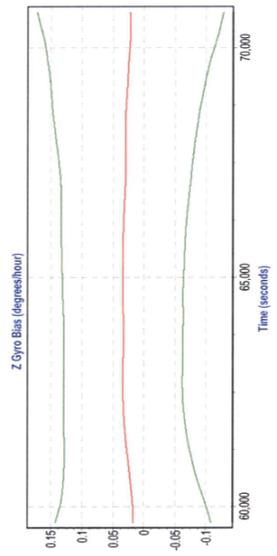
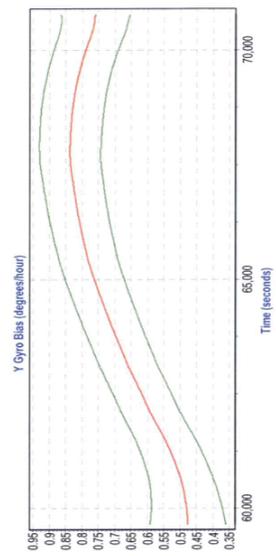
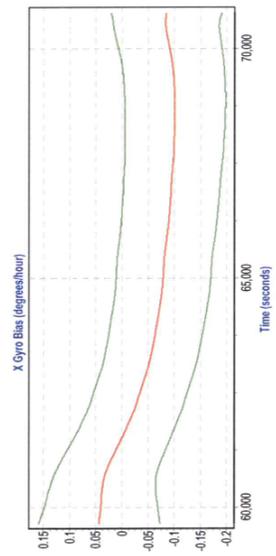
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Appendix D2: Terrapoint LiDAR Processing Report

PROJECT REPORT

Terrapoint #: 2007-150-U

Dewberry #: 07-HS-34-14-00-22-469 Task Order 20070525-4927

Florida (Wakulla/Franklin Counties) 2007 LiDAR Collection

Originally submitted: 2008-06-17

Revisions: 2008-06-17

Presented to:

 **Dewberry**
Fairfax, Virginia

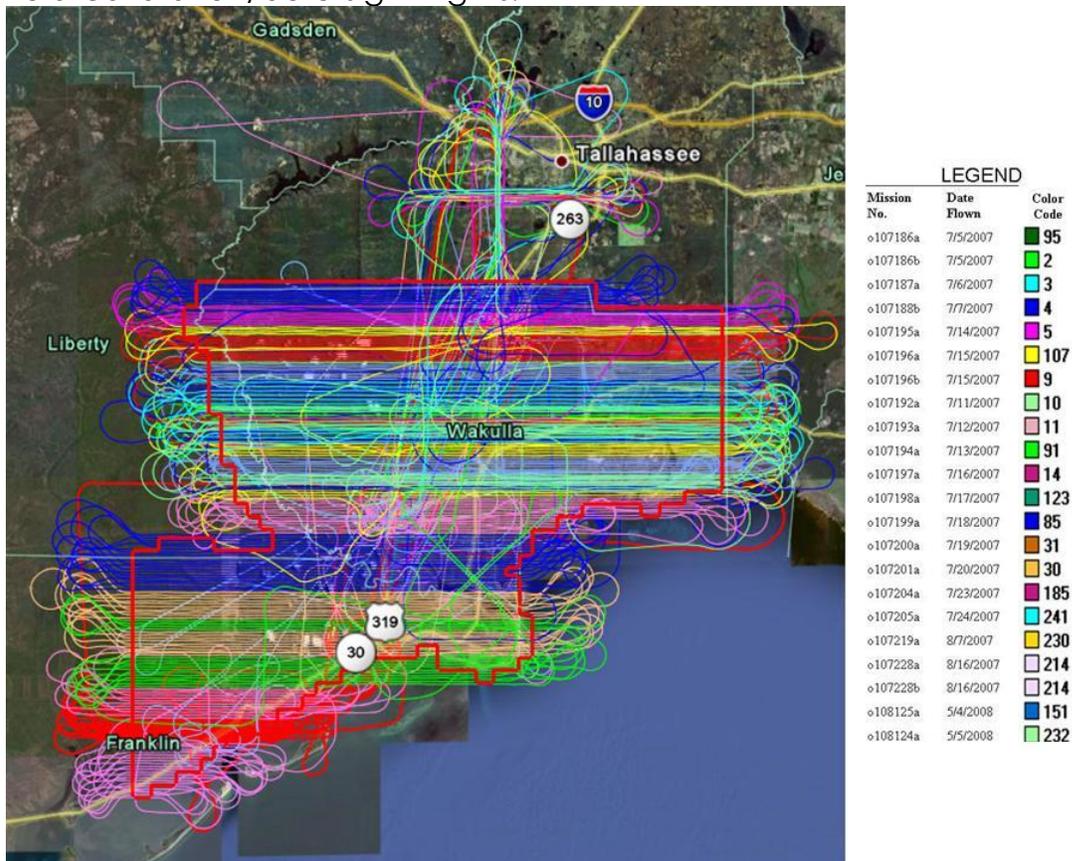
Submitted by:

 **Terrapoint**
Houston, Texas

EXECUTIVE SUMMARY

This LiDAR project was to provide high accuracy, classified multiple return LiDAR, for 983.7 square miles, of the Wakulla and Franklin Counties, FL. The LiDAR data were acquired and processed by Terrapoint USA to support FDEM. The product is a high density mass point dataset with an average point spacing of 1m². The data is tiled without a buffer, stored in LAS 1.1 format, and LiDAR returns are classified in 4 ASPRS classes: Unclassified (1), Ground (2), Noise (7) and Water (9), Overlap (12).

The flight lines and dates are shown in the image below, to include the field-calibration/bore-sight flights.



The elevation data was verified internally prior to delivery to ensure it met fundamental accuracy requirements when compared kinematic to Terrapoint GPS checkpoints. Below is the summary for the project site.

- The Raw elevation measurements for Wakulla/Franklin have been tested to 0.374 US Survey Feet for vertical accuracy at 95 percent confidence level.

All data delivered meets and exceeds Terrapoint's deliverable product requirements as setout by Terrapoint's IPROVE program.



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WAKULLA/FRANKLIN COUNTIES PROJECT REPORT

Introduction

LiDAR data is remotely sensed high-resolution elevation data collected by an airborne collection platform. By positioning laser range finding with the use of 1 second GPS with 200 Hz inertial measurement unit corrections; Terrapoint's LiDAR instruments are able to make highly detailed geospatial elevation products of the ground, man-made structures and vegetation.

The LiDAR ground extraction process takes place by building an iterative surface model. This surface model is generated using three main parameters: building size, iteration angle and iteration distance.

The purpose of this LiDAR data was to produce high accuracy 3D terrain geospatial products for the Wakulla/Franklin Counties.

This report covers the mission parameter and details, processing step outlines and deliverables.

This report is submitted as a supporting overview document for the FGDC metadata reports that are included as an addendum to this report.

Acquisition

Parameter Overview

The Airborne LiDAR survey was conducted using one Optech 3100EA systems flying at a nominal height of 1550 meters AGL with a total angular coverage of 25 degrees with a 5 degree cutoff. Flight line spacing was nominally 507.74 meters providing overlap of 55% on adjacent flight lines. Lines were flown in east/west orientated blocks to best optimize flying time considering the layout for the project. The aircraft was a Piper Navajo, registrations C-GPJT, used for the survey. This aircraft has a flight range of approximately 6 hours and was flown at an average altitude of 1550 meters above sea level (ASL), thereby encountering flying altitudes of approximately 1550 meters above ground level (AGL). The aircraft was staged from Tallahassee Regional Airport (TLH), Tallahassee, Florida, and ferried daily to the project site for flight operations.

The Optech 3100EA system was configured in the following manner for the Wakulla/Franklin Counties:

- Type of Scanner = Optech 3100EA
- Data Acquisition Height = 1550 meters AGL
- Scanner Field of View = 25 degrees with a 5 degree cutoff
- Scan Frequency = 30.8 Hertz
- Pulse Repetition Rate = 71 Kilohertz
- Aircraft Speed = 150 Knots
- Swath Width = 1028.31 m Nominal
- Ground Sample Distance = 1.25 meters - no overlap
- Number of Returns per Pulse = 4
- Distance between Flight Lines = 507.74m

GPS Receivers

A combination of Sokkia GSR 2600 and NovAtel DL-4+ dual frequency GPS receivers were used to support the airborne operations of this survey and to establish the GPS control network.

Missions Statistics

For the Wakulla/Franklin Counties, a total of 22 missions were flown for this project with good meteorological and GPS conditions. 286 flight lines were flown over the project site to provide complete coverage.

The LiDAR missions for the Wakulla/Franklin Counties were carried out from May 5, 2007 and May 4, 2008.

Reference Coordinate System Used

Wakulla/Franklin Counties

Seven existing NGS (National Geodetic Survey) monuments were observed in a GPS control network.

Existing monuments FB175P05, FB175P06, FB175P07, FB170P40, BE1938, AS0883, and AS0213 were used as primary control for this project.

The published horizontal datum of the NGS stations is NAD83 HARN and the vertical datum NAVD88.

The following are the final coordinates of the newly established control points used in this project:

Station_ID: FB175P05
West_Longitude: -84 21 21.41670
North_Latitude: 30 15 36.00059
Ellips_Elev: -21.307

Station_ID: FB175P06
West_Longitude: -84 43 33.69820
North_Latitude: 30 11 34.60055
Ellips_Elev: -9.453

Station_ID: FB175P07
West_Longitude: -84 26 28.95877
North_Latitude: 30 10 36.80317
Ellips_Elev: -13.028

Station_ID: FB170P40
West_Longitude: -84 29 54.23450
North_Latitude: 30 03 14.02802
Ellips_Elev: -22.471

Station_ID: BE1938
West_Longitude: -84 17 20.49454
North_Latitude: 30 3 27.78507
Ellips_Elev: -25.349

Station_ID: AS0883
West_Longitude: -84 30 42.12339
North_Latitude: 29 54 58.98776
Ellips_Elev: -25.218

Station_ID: AS0213
West_Longitude: -84 44 31.54609
North_Latitude: 29 48 1.35670
Ellips_Elev: -19.936

Geoid Model Used

The Geoid03 geoid model, published by the NGS, was used to transform all ellipsoidal heights to orthometric.

Processing

Airborne GPS Kinematic

Airborne GPS kinematic data was processed on-site using GrafNav kinematic On-The-Fly (OTF) software. Flights were flown with a minimum of 6 satellites in view (13° above the horizon) and with a PDOP of better than 4.5. Distances from base station to aircraft were kept to a maximum of 30 km, to ensure a strong OTF (On-The-Fly) solution. For all flights, the GPS data can be classified as excellent, with GPS residuals of 5cm average but no larger than 9 cm being recorded.

Generation and Calibration of Laser Points (raw data)

Calibration is performed to eliminate systematic bias in the system, which would result in a bias in the data. By determining the bias they can then be modeled and the effects removed from the data. The manufacturer initially calibrates the system on manufacture. Subsequently each mission is checked and calibrated to ensure data quality.

Manufacturer Calibration

Manufacturer calibration was completed upon manufacture and upon delivery of the system to Terrapoint. The manufacturer maintains and calibrates each LiDAR system annually and upon any field visits to service the system.

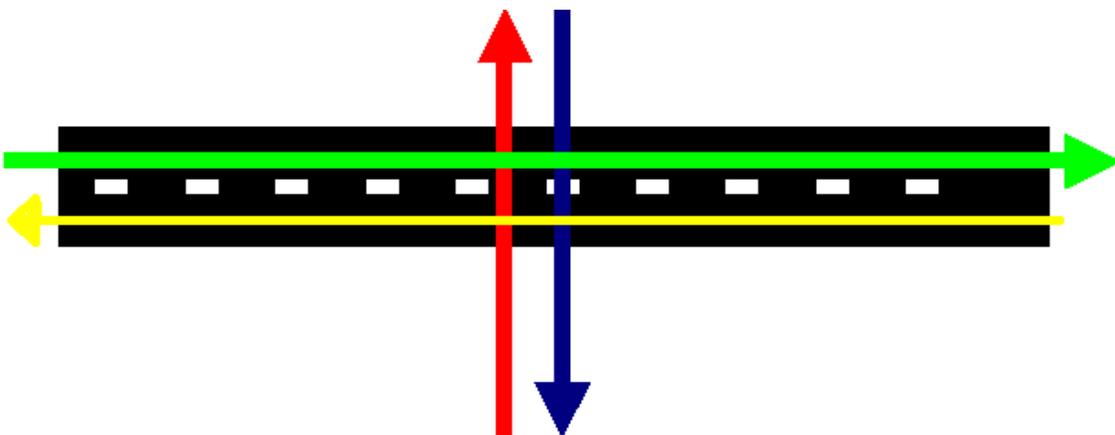
Manufacturer calibration addresses both radiometric and geometric calibration. Radiometric calibration is to ensure that the laser meets specification for pulse energy, width, and rise time, frequency and beam divergence. These values are tested by the manufacturer and annually certified. Radiometric calibration also checks the alignment between transmitter and receiver and assures that alignment is optimal.

Geometric calibration is also conducted by the manufacturer both in the laboratory and with onsite flights in previously surveyed areas. Range calibration determines the first/last range offsets. Scanner calibration provides values for scanner offset and scale. Position orientation alignment provides Pos misalignment angles.

The Following are the manufacturer derived calibration values that are constant unless the IMU is changed:

AltmSerialNo= 05Sen183
ImuType= LN200A1
ImuRate= 200
ScannerScale= 1.0064
ScannerOffset= -0.0171
FirstPulseRange= -2.76
SecondPulseRange= -2.76
ThirdPulseRange= -2.76
LastPulseRange= -2.76
IMURoll= 0.031
IMUPitch= -0.008
IMUHeading= 0.000
UserToImuEx= -0.020
UserToImuEy= 0.005
UserToImuEz= -0.150
UserToImuDx= -0.09
UserToImuDy= -0.008
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UserToRefDy= -0.030
UserToRefDz= -0.488
TimeLag= 0.000012
IntensityGainFor3070= 20
UseDroopCorrection= 15.0

Field Calibration is used to determine the roll, pitch, heading and scanner scale values. This is essentially the same as bore-sighting. The roll pitch heading and scanner scale biases are determined by comparing overlapping and opposing flightlines. Each mission is flown to have two cross lines that intersect every flightline and these lines are used to determine the roll, pitch heading and scanner scale.



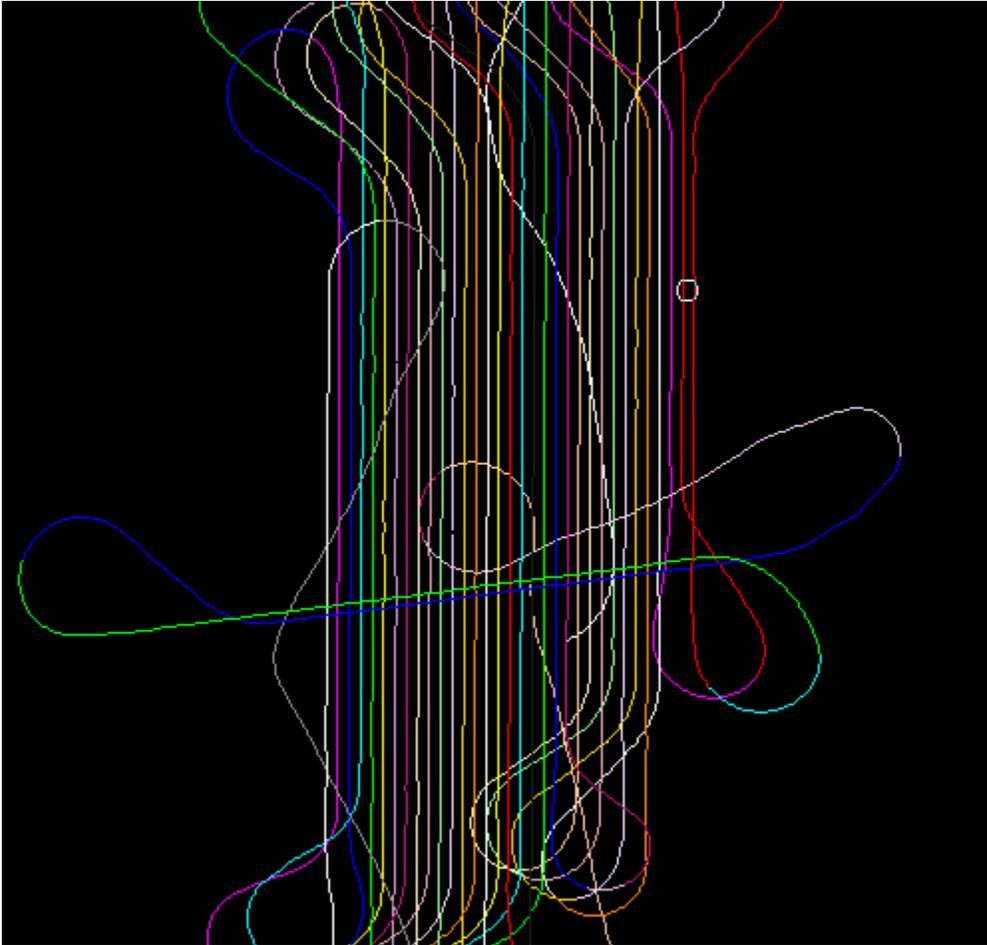


Figure 4 Example of mission trajectory showing cross lines used to determine calibration values

The mission data is initially output using the manufacturer calibration default values for the specific system. The data is then examined using a combination of Terrascan Terramodel and Terramatch and user input to determine the final roll, pitch, and heading and scanner scale. Once the values are finalized the mission data is output in LAS format.

The data is then checked against static and kinematic control data to ensure vertical accuracy. Each mission's data is based on the post-processed position of a base station. The base stations used were all tied into geodetic control points or were geodetic control points. Units are in US Survey Feet.

Table 2: Kinematic Point Comparison	
Average dz	-0.224
Minimum dz	-1.121
Maximum dz	+0.645
Average magnitude	0.300
Root mean square	0.374
Std deviation	0.299

Because of this, the positional accuracy of the LiDAR data is ensured. The individual mission data can then be compared to adjoining missions to ensure both vertical and horizontal accuracy. If any offset either vertical or horizontal is found then the mission is reprocessed and checked for accuracy.

Vertical Bias Resolution

Due to limitations in the Optech Dashmap software, the following D_z adjustments were adjusted post calibration manually in Terrascan to the following missions to ensure they tie to adjoining missions and GPS kinematic validation points:

Wakulla/Franklin Counties

System	Year	Mission	Delta Z Adjustment (cm)
o1	7	186a	0.35
o1	7	186b	0.4
o1	7	187a	0.48
o1	7	195a	0.15
o1	7	188b	0.37
o1	7	196b	0.11
o1	7	198a	0.09
o1	7	200a	0.2688
o1	7	204a	0.1
o1	7	205a	0.15
o1	7	219a	0.22
o1	7	228a	0.13
o1	7	228b	0.18
o1	7	193a	No shift
o1	7	192a	No shift
o1	7	194a	No shift
o1	7	197a	No shift
o1	7	199a	No shift
o1	7	201a	No shift
o1	7	196a	No shift
o1	8	124a	No shift
o1	8	125a	No shift

Data Classification and Editing

The data was processed using the software Terrascan, and following the methodology described herein. The initial step is the setup of the Terrascan project, which is done by importing the Dewberry provided tile boundary index encompassing the entire project areas. The 3D laser point clouds, in binary format, were imported into the Terrascan project and divided in 1096 tiles for the Wakulla/Franklin in LAS 1.1 format. Once tiled, the laser points were classified using a proprietary routine in Terrascan. This routine removes any obvious outliers from the dataset following which the ground layer is extracted from the point cloud. The ground extraction process encompassed in this routine takes place by building an iterative surface model. This surface model is generated using three main parameters: building size, iteration angle and iteration distance. The initial model is based on low points being selected by a "roaming window" with the assumption is that these are the ground points. The size of this roaming window is determined by the building size parameter. The low points are triangulated and the remaining points are evaluated and subsequently added to the model if they meet the iteration angle and distance constraints. This process is repeated until no additional points are added within iteration. A second critical parameter is the maximum terrain angle constraint, which determines the maximum terrain angle allowed within the classification model. The data is then manually quality controlled with the use of hillshading, cross-sections and profiles. Any points found to be of class vegetation, building or error during the quality control process, are removed from the ground model and placed on the appropriate layer. An integrity check is also performed simultaneously to verify that ground features such as rock cuts, elevated roads and crests are present. Once data has been cleaned and complete, it is then by a supervisor via manual inspection and through the use of a hillshade mosaic.

Deliverable Product Generation

Deliverable Tiling Scheme

All files were retilled in the provided tiling scheme with a total of 1096 tiles for Wakulla/Franklin Counties.

LiDAR Point Data

The LiDAR point data was delivered in LAS 1.1 adhering to the following ASPRS classification scheme:

Class 1 – Unclassified
Class 2 – Ground
Class 7 – Noise
Class 9 – Water
Class 12 - Overlap

Water body delineation was collected using hillshades and intensity images generated from ground DEM and LiDAR.

The LAS files contain the following fields of information (Precision reported in brackets):

Class (Integer)
GPS Week Time (0.0001 seconds)
Easting (0.01 meter)
Northing (0.01 meter)
Elevation (0.01 meter)
Echo Number (Integer 1 to 4)
Echo (Integer 1 to 4)
Intensity (8 Bit Integer)
Flightline (Integer)
Scan Angle (Integer Degree)

Please note that the LiDAR intensity is not calibrated or normalized. The intensity value is meant to provide relative signal return strengths for features imaged by the sensor.

Point data was clipped to the project boundary.

FGDC Report

Separate metadata FGDC reports were delivered for the Wakulla/Franklin Counties. The reports are included as an addendum to this report.

Quality Control

Quality Control for Data Acquisition

A daily calibration flight is key to the QC process since it helps identify any systematic issues in data acquisition or failures on the part of the GPS, IMU or other equipment that may not have been evident to the LiDAR operator during the mission. The aircraft initially performs a figure-8 manoeuvre over the selected calibration site to collect calibration data for use in post-processing. The calibration site is ideally selected in a relatively open, tree-less area where several large buildings are located. The buildings used for calibration are surveyed using both GPS and conventional survey methods. A local network of GPS points are established to provide a baseline for conventional traversing around the perimeter of the buildings.

Ground truth validation is used to assess the data quality and consistency over sample areas of the project. To facilitate a confident evaluation, existing survey control is used to validate the LiDAR data. Published survey control, where the orthometric height (elevation) has been determined by precise differential levelling observation, is deemed to be suitable.

Ground truth validation points may be collected for each of the any terrain categories that Dewberry requires to establish RMSE accuracies for the LIDAR project. These points must be gathered in flat or uniformly sloped terrain (<20% slope) away from surface features such as stream banks, bridges or embankments. If collected, these points will be used during data processing to test the RMSE_z accuracy of the final LiDAR data products.

The LiDAR operator performs kinematic post-processing of the aircraft GPS data in conjunction with the data collected at the Reference Station in closest proximity to the area flown. Double difference phase processing of the GPS data is used to achieve the greatest accuracy. The GPS position accuracy is assessed by comparison of forward and reverse processing solutions and a review of the computational statistics. Any data anomalies are identified and the necessary corrective actions are implemented prior to the next mission.

The quality control of LIDAR data and data products has proven to be a key concern by Dewberry. Many specifications detail how to measure the quality of LiDAR data given RMSE statistical methods to a 95% confidence level. In order to assure meeting all levels of QC concerns, Terrapoint has quality control and assurance steps in both the data acquisition phase and the data processing

phase. Any acquired data sets that fail these checks are flagged for re-acquisition.

QC Step 1 - The Data Acquisition (DAQ) software performs automatic system and subsystem tests on power-up to verify proper functionality of the entire data acquisition system. Any anomalies are immediately investigated and corrected by the LiDAR operator if possible. Any persistent problems are referred to the engineering staff, which can usually resolve the issue by telephone and/or email. In the unlikely event that these steps do not resolve the problem, a trained engineer is immediately dispatched to the project site with the appropriate test equipment and spare parts needed to repair the system.

QC Step 2 - The DAQ software continuously monitors the health and performance of all subsystems. Any anomalies are recorded in the System Log and reported to the LiDAR operator for resolution. If the operator is unable to correct the problem, the engineering staffs are immediately notified. They provide the operator with instructions or on-site assistance as needed to resolve the problem.

The DAQ software also provides real-time terrain viewers that allow the operator to directly monitor the data quality. Multiple returns from individual laser shots are color coded to provide the operator with an indication of the degree of penetration through dense vegetation. If any aspect of the data does not appear to be acceptable, the operator will review system settings to determine if an adjustment could improve the data quality. Navigation aids are provided to alert both the pilot and operator to any line following errors that could potentially compromise the data integrity. The pilot and operator review the data and determine whether an immediate re-flight of the line is required.

QC Step 3 - After the mission is completed, raw LiDAR data on the removable disk drive is transferred to the Field PC at the field operations staging area. An automated QA/QC program scans the System Log as well as the raw data files to detect potential errors. Any problems identified are reported to the operator for further analysis. Data is also retrieved from all GPS Reference Stations, which were active during the mission and transferred to the Field PC. The GPS data is processed and tested for internal consistency and overall quality. Any errors or limit violations are reported to the operator for more detailed evaluation.

QC Step 4 - The operators utilize a data viewer installed on the Field PC to review selected portions of the acquired LiDAR data. This permits a more thorough and detailed analysis than is possible in real-time during data collection. Corrupted files or problems in the data itself are noted. If the data indicates improper settings or operation of the LiDAR sensor, the operator determines the appropriate corrective actions needed prior to the next mission.

QC Step 5 - All LiDAR and GPS data is copied from the Field PC onto Hard Drives: one for transfer to data processing, and one for local backup. Each Hard drive is reviewed to ensure data completeness and readability.

Quality Control for Data Processing

Quality assurance and quality control procedures for the raw LiDAR data and processed deliverables for the DEM and DTM products are performed in an iterative fashion through the entire data processing cycle. All final products pass through a seven-step QC control check to verify that the data meets the criteria specified by Dewberry.

Terrapoint has developed a rigorous and complete process, which does everything possible to ensure data will meet or exceed the technical specifications. Experience dealing with all ranges of difficulty in all types of topographic regions has led to the development of our quality assurance methods. Our goal is to confidently deliver a final product to Dewberry that is as precise as possible, the first time. Terrapoint will go to extraordinary lengths to make our customer completely satisfied. The following list provides a step-by-step explanation of the process used by Terrapoint to review the data prior to customer delivery.

QC Step 1 - Data collected by the LiDAR unit is reviewed for completeness and to make sure all data is captured without errors or corrupted values. In addition, all GPS, aircraft trajectory, mission information, and ground control files are reviewed and logged into a database. At this time, the data will be confirmed to have been acquired using instrumentation that records first and last returns for each laser pulse, or multiple returns per laser pulse.

QC Step 2 - The LiDAR data is post processed and calibrated for as a preliminary step for product delivery. At this time, the data are inspected for flight line errors, flight line overlap, slivers or gaps in the data, point data minimums, or issues with the LiDAR unit or GPS. Flight line swath overlap will be confirmed to have adjacent flight lines at the tolerance specified by Dewberry for overlap throughout the project area thus enabling an evaluation of data reproducibility throughout the areas.

QC Step 3 - The full-featured product is reviewed as a grid and as raw points and attention is placed on locating and eliminating any outlier or anomalous points beyond three-sigma values. These points may be spikes, unusually high points, or pits, unusually low points. LiDAR points returning from low clouds, birds,

pollution, or noise in the system can cause spikes. Pit-like low returns can come from water features or damp soils or from system noise. Either type of point needs to be classified as an error point and eliminated from use by any grid products. In addition to these outliers, the full-feature product is reviewed for NO DATA points and regular looking non-surface errors like scan lines appearing in the data. Also, steps between flight lines are measured and adjusted as needed.

Unusual or odd-looking features and questionable returns are checked for validity and compared against additional source material such as aerial photos, USGS digital maps, local maps, or by field inspection. Most errors found at this QC step can be resolved by re-calibration of the data set or by eliminating specific problem points.

QC Step 4 - After the full-feature data is at a clean stage, all points are classified as ground and unclassified features. Any non-regular structures or features like radio towers, large rock outcrops, water bodies, bridges, piers, are confirmed to be classified into the category specified by Dewberry for these feature types. Additional data sets like commercially available data sources or data sources provided by Dewberry may be used to assist and verify that points are assigned into correct classifications.

QC Step 5 - After the full-featured data set is certified as passing for completeness and for the removal of outliers, attention may be shifted to quality controlling the bare-earth model. This product may take several iterations to create it to the quality level that Dewberry is looking for. As both Terrapoint and Dewberry inspect the bare-earth model, adjustments are made to fine-tune and fix specific errors.

Adjustments to the bare-earth model are generally made to fix errors created by over-mowing the data set along mountaintops, shorelines, or other areas of high percent slope. Also, vegetation artefacts leave a signature surface that appears bumpy or rough. Every effort is made to remove spurious vegetation values and remnants from the bare-earth model. All adjustments are made by re-classifying points from ground to unclassified or vice versa. No adjustments are made to the final grid product, as other parties cannot easily reproduce these types of adjustments from the original, raw data set.

QC Step 6 - Both $RMSE_z$ and $RMSE_{xy}$ are inspected in the classified bare-earth model and compared to project specifications. $RMSE_z$ is examined in open, flat areas away from breaks and under specified vegetation categories. Neither $RMSE_z$ nor $RMSE_{xy}$ are compared to orthoimagery or existing building footprints. Comparison against imagery can skew the determination of accuracy because of the lean and shadows in the imagery.

Instead, a point to point comparison of a recently acquired or existing high confidence ground survey point to its nearest neighbour LiDAR laser return point. This is done in the raw data set and usually with Terrascan software. The tolerance for finding a near-by LiDAR point elevation to compare to a survey point elevation is that the two points must be within a 0.5m radius of each other in open flat areas is made. If no LiDAR points can be found within in this tolerance, then alternative methodologies are used to convert the LiDAR to a TIN, though this can introduce biases and processing errors in the end products and could cause the RMSE values to be skewed and fall beyond project specifications.

QC Step 7 - A final QC step is made against all deliverables before they are sent to Dewberry. The deliverables are checked for file naming convention, integrity checks of the files, conformance to file format requirements, delivery media readability, and file size limits. In addition, as data are delivered all requested reports would be delivered as they become available.

Positional Accuracy

Vertical Positional Accuracy

The elevation data was verified internally prior to delivery to Dewberry to ensure it met fundamental accuracy requirements when compared kinematic to Terrapoint GPS checkpoints. Below is the summary for the three sites.

- The LiDAR dataset for Wakulla/Franklin Counties was tested 0.0686m vertical accuracy at 95 percent confidence level, based on consolidated $RMSE_z$ (0.035m) x 1.9600.

Horizontal Positional Accuracy

Compiled to meet 1 meter horizontal accuracy at the 95 percent confidence level.

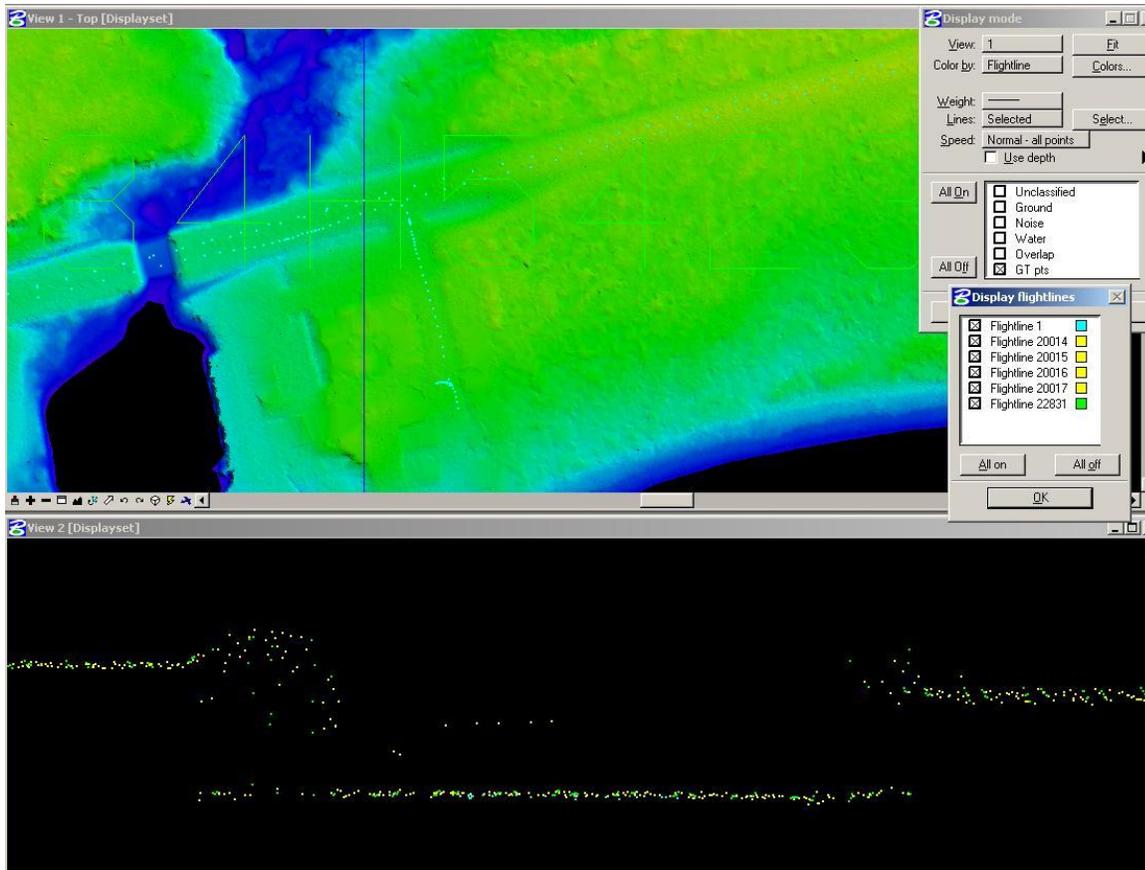


Figure 2 Example of Control pts (flightline 1) loaded with the raw data to check vertical accuracy

Conclusion

Overall the LiDAR data products submitted to Dewberry meet and exceed both the absolute and relative accuracy requirements set out in the task order for this project. The quality control requirements required in Terrapoint's IPROVE program were adhered to throughout the project cycle to ensure product quality.

Appendix A Wakulla/Franklin Counties FGDC Metadata

IDENTIFICATION_INFORMATION

Citation:

Citation_Information:

Originator: Terrapoint USA

Publication_Date: 20080620

Title: Dewberry FDEM Wakulla Franklin Counties Task Order 20070525-4927

Contract No. 07-HS-34-14-00-22-469

Geospatial_Data_Presentation_Form: Map

Online_Linkage: none

Larger_Work_Citation:

Citation_Information:

Originator: Terrapoint USA

Publication_Date: 20080620

Title: Dewberry Dewberry FDEM Wakulla Franklin Counties Contract

No. 2007-150-U

Publication_Information:

Publication_Place: Houston, Texas

Publisher: Terrapoint USA

Online_Linkage: none

Description:

Abstract:

LiDAR data is remotely sensed high-resolution elevation data collected by an airborne collection platform. By positioning laser range finding with the use of 1 second GPS with 100hz inertial measurement unit corrections; Terrapoint's LIDAR instruments are able to make highly detailed geospatial elevation products of the ground, man-made structures and vegetation. The LiDAR flightlines for this project was planned for a 55% acquisition overlap. The nominal resolution of this project without overlap is 1.25m. Four returns were recorded for each pulse in addition to an intensity value. GPS Week Time, Intensity, Flightline and number attributes were provided for each LiDAR point. Data is provided as random points, in LAS v1.1 format, classified in following code list 1=Unclassified 2=Ground 7=Noise 9=Water 12=Overlap

Purpose:

The purpose of this LiDAR data was to produce high accuracy 3D elevation based geospatial products for mapping.

Supplemental_Information:

LiDAR Collection Specific Supplemental Information:

- General Overview:

The Airborne LiDAR survey was conducted using 1 OPTECH 3100EA system flying at a nominal height of 1550m AGL with a total angular coverage of 20 degrees. Flight line spacing was nominally 507.74m providing overlap of 55% on adjacent flight lines. Lines were flown in east/west orientated blocks to best optimize flying time considering the layout for the project.

The total project size is 983.7 square kilometers

The aircraft was a Piper Navajo, registration C-GPJT was used for the survey. This aircraft has a flight range of approximately 6 hours and was flown at an average altitude of 1550 meters above sea level (ASL). The aircraft was staged from the TLH Airport, Tallahassee Regional Airport, Tallahassee, Florida, and ferried daily to

the project site for flight operations.

Aircraft Speed = 150 Knots

Number of Scanners = 1

Swath Width 1128.31m Nominal

Distance Between Flight Lines = 507.74m

Data Acquisition Height = 1550 meters AGL

Pulse Repetition Rate = 71 kHz

Number of Returns Per Pulse = 4

Scanner Field Of View = +/- 20 degrees

Scan Frequency = 30.38 Hertz

- GPS Receivers

A combination of Sokkia GSR 2600 and NovAtel DL-4+ dual frequency GPS receivers were used to support the airborne operations of this survey and to establish the GPS control network.

- Number of Flights and Flight Lines

A total of 22 missions and 286 flightlines were flown for this project with flight

times ranging approximately 6 hours under good meteorological and GPS conditions.

- Reference Coordinate System Used:

Existing monuments FB175P05, FB175P06, FB175P07, FB170P40, BE1938, AS0883, and AS0213 were used to control all flight missions and kinematic ground surveys.

The published horizontal datum of the NGS stations is NAD83 HARN and the vertical datum NAVD88. The following are the final coordinates of the newly established control points used in this project:

Station_ID: FB175P05

West_Longitude: -84 21 21.41670

North_Latitude: 30 15 36.00059

Ellips_Elev: -21.307

Station_ID: FB175P06

West_Longitude: -84 43 33.69820

North_Latitude: 30 11 34.60055

Ellips_Elev: -9.453
Station_ID: FB175P07
West_Longitude: -84 26 28.95877
North_Latitude: 30 10 36.80317
Ellips_Elev: -13.028
Station_ID: FB170P40
West_Longitude: -84 29 54.23450
North_Latitude: 30 03 14.02802
Ellips_Elev: -22.471
Station_ID: BE1938
West_Longitude: -84 17 20.49454
North_Latitude: 30 3 27.78507
Ellips_Elev: -25.349
Station_ID: AS0883
West_Longitude: 29 54 58.98776
North_Latitude: -84 30 42.12339
Ellips_Elev: -25.218
Station_ID: AS0213
West_Longitude: -84 44 31.54609
North_Latitude: 29 48 1.35670
Ellips_Elev: -19.936

- Geoid Model Used
The Geoid03 geoid model, published by the NGS, was used to transform
all ellipsoidal heights to orthometric.

-General LiDAR notes

-Intensity
Please note that the LiDAR intensity is not calibrated or
normalized. The intensity value is meant to provide
relative signal return strengths for features imaged by the
sensor.

-Waterbodies
Water is not included in the bare earth ground points for lakes, rather
it is classified as water on Class 9. Water body delineation was collected
using hillshades and intensity images generated from ground DEM and LiDAR.

Time_Period_of_Content:
Time_Period_Information:
Range_of_Dates/Times:
Beginning_Date: 20070705
Ending_Date: 20080504
Currentness_Reference: Ground Condition
Status:
Progress: Complete
Maintenance_and_Update_Frequency: None planned
Spatial_Domain:
Bounding_Coordinates:
West_Bounding_Coordinate: -84.10
East_Bounding_Coordinate: -84.08
North_Bounding_Coordinate: 30.27
South_Bounding_Coordinate: 30.07
Keywords:

Theme:

Theme_Keyword_Thesaurus: None
Theme_Keyword: ASPRS standards
Theme_Keyword: DEM
Theme_Keyword: digital elevation model
Theme_Keyword: elevation
Theme_Keyword: LAS_v1.1
Theme_Keyword: laser
Theme_Keyword: LiDAR
Theme_Keyword: OPTECH_3100EA
Theme_Keyword: surface model

Place:

Place_Keyword_Thesaurus: None
Place_Keyword: Wakulla/Franklin Counties
Place_Keyword: Florida
Place_Keyword: United States of America
Place_Keyword: Southeast

Access_Constraints:

All deliverable data and documentation shall be free from restrictions regarding use and distribution. Data and documentation provided under this task order shall be freely distributable by government agencies.

Use_Constraints:

Any conclusions from results of the analysis of this LiDAR are not the responsibility of Terrapoint. The LiDAR data was thoroughly visually verified to represent the true ground conditions at time of collection. Users should be aware of this limitations of this dataset if using for critical applications.

Point_of_Contact:

Contact_Information:

Contact_Organization_Primary:
Contact_Organization: Terrapoint USA
Contact_Person: Peggy Cobb
Contact_Position: Production Manager
Contact_Address:
Address_Type: mailing and physical address
Address: 25216 Grogan's Park Drive
City: The Woodlands
State_or_Province: Texas
Postal_Code: 77380
Country: USA
Contact_Voice_Telephone: 1-877-999-7687
Contact_Facsimile_Telephone: 1-281-296-0869
Contact_Electronic_Mail_Address: peggy.cobb@terrapoint.com
Hours_of_Service: Monday to Friday, 8-5, CST

DATA_QUALITY_INFORMATION

Attribute_Accuracy:

Attribute_Accuracy_Report:
Raw elevation measurements have been tested to 0.378 US Survey Ft.

Logical_Consistency_Report:

All LiDAR files delivered were verified and tested to ensure they open and are positioned properly.

Completeness_Report:

According to Terrapoint standards; the following aspects of the LiDAR data was verified during the course of the project processing:

- Data completeness and integrity
- Data accuracy and errors
- Anomaly checks through full-feature hillshades
- Post automated classification Bare-earth verification
- RMSE inspection of final bare-earth model using kinematic GPS
- Final quality control of deliverable products; ensuring integrity; graphical quality; conformance to Terrapoint standards are met for all delivered products.
- Special note for this dataset: On a project level, a coverage check is carried out to ensure no slivers are present; however due to resale

nature

of this task order and the desire to maximize coverage, some minor slivers

were detected and reported to the client via polygon shape files. The slivers were reflowed and filled.

Positional_Accuracy:

Horizontal_Positional_Accuracy:

Horizontal_Positional_Accuracy_Report:

Compiled to meet 1 meter horizontal accuracy at the 95 percent confidence level

Vertical_Positional_Accuracy:

Vertical_Positional_Accuracy_Report:

Tested to 0.378 US Survey Ft.

Lineage:

Source_Information:

Source_Citation:

Citation_Information:

Originator: Terrapoint USA
Publication_Date: 20080429
Title: Dewberry FDEM Wakulla Counties
Edition: One
Geospatial_Data_Presentation_Form: map

Publication_Information:

Publication_Place: Houston, Texas
Publisher: Terrapoint USA
Online_Linkage: www.terrapoint.com

Larger_Work_Citation:

Citation_Information:

Originator: Terrapoint USA
Publication_Date: 20080429
Title: Dewberry FDEM Wakulla/Franklin Counties
Publication_Information:

Publication_Place: Houston, Texas
Publisher: Terrapoint USA

Online_Linkage: www.terrapoint.com

Type_of_Source_Media: Hard Drive

Source_Time_Period_of_Content:

Time_Period_Information:

Range_of_Dates/Times:

Beginning_Date: 20070505

Ending_Date: 20080504

Source_Currentness_Reference: Ground Condition

Source_Citation_Abbreviation: none
Source_Contribution: none

Process_Step:

Process_Description:

- Airborne GPS Kinematic

Airborne GPS kinematic data was processed on-site using GrafNav kinematic On-The-Fly (OTF) software. Flights were flown with a minimum of 6 satellites in view (130 above the horizon) and with a PDOP of better than 4.5. Distances from base station to aircraft were kept to a maximum of 30 km, to ensure a strong OTF (On-The-Fly) solution. For all flights, the GPS data can be classified as excellent, with GPS residuals of 5cm average but no larger than 9 cm being recorded.

Source_Used_Citation_Abbreviation: GPS Processing

Process_Date: 200705

Source_Produced_Citation_Abbreviation: GPS

Process_Contact:

Contact_Information:

Contact_Person_Primary:

Contact_Organization: Terrapoint USA

Contact_Person: Peggy Cobb

Contact_Position: Production Manager

Contact_Address:

Address_Type: mailing and physical address

Address: 251216 Grogan's Park Drive

City: The Woodlands

State_or_Province: Texas

Postal_Code: 77380

Country: USA

Contact_Voice_Telephone: 1-877-999-7687

Contact_Facsimile_Telephone: 1-281-296-0869

Contact_Electronic_Mail_Address: peggy.cobb@terrapoint.com

Hours_of_Service: Monday to Friday, 8 - 5, CST

Process_Step:

Process_Description:

- Generation and Calibration of laser points (raw data)

The initial step of calibration is to verify availability and status of all needed GPS and Laser data against field notes and compile any data if not complete.

Subsequently the mission points are output using Optech's Dashmap, initially with default values from Optech or the last mission calibrated for system. The initial point generation for each mission calibration is verified within Microstation/Terrascan for calibration errors. If a calibration error greater than specification is observed

within the mission, the roll pitch and scanner scale corrections that need to be applied are calculated. The missions with the new calibration values are regenerated and validated internally once again to ensure quality. All missions are validated against the adjoining missions for relative vertical biases and collected GPS kinematic ground truthing points for absolute vertical accuracy purposes.

On a project level, a coverage check is carried out to ensure no slivers are present.

Source_Used_Citation_Abbreviation: Calibration

Process_Date: 200705

Source_Produced_Citation_Abbreviation: CAL

Process_Contact:

Contact_Information:

Contact_Person_Primary:

Contact_Organization: Terrapoint USA

Contact_Person: Peggy Cobb

Contact_Position: Production Manager

Contact_Address:

Address_Type: mailing and physical address

Address: 251216 Grogan's Park Drive

City: The Woodlands

State_or_Province: Texas

Postal_Code: 77380

Country: USA

Contact_Voice_Telephone: 1-877-999-7687

Contact_Facsimile_Telephone: 1-281-296-0869

Contact_Electronic_Mail_Address: peggy.cobb@terrapoint.com

Hours_of_Service: Monday to Friday, 8 - 5, CST

Process_Step:

Process_Description:

- Vertical Bias Resolution

Due to limitations in the Optech Dashmap software, the following Dz adjustments

were adjusted post calibration manually in Terrascan to the following missions

to ensure they tie to adjoining missions and GPS kinematic validation points:

System;Year;Mission;Delta_Z_Adjustment_(cm): 01;186a;.35
01;7;186b;.40 01;7;187a;.48 01;7;195a;.15 01;7;188b;.37 01;7;196b;.11
01;7;198a;.09 01;7;200a;.2688 01;7;204a;.1 01;7;205a;.15 01;219a;.22
01;7;228a;.13 01;7;228b;.18

Source_Used_Citation_Abbreviation: Vertical Bias Resolution

Process_Date: 200705

Source_Produced_Citation_Abbreviation: Dz

Process_Contact:

Contact_Information:

Contact_Person_Primary:

Contact_Organization: Terrapoint USA

Contact_Person: Peggy Cobb

Contact_Position: Production Manager

Contact_Address:

Address_Type: mailing and physical address

Address: 251216 Grogan's Park Drive

City: The Woodlands

State_or_Province: Texas

Postal_Code: 77380

Country: USA

Contact_Voice_Telephone: 1-877-999-7687

Contact_Facsimile_Telephone: 1-281-296-0869

Contact_Electronic_Mail_Address: peggy.cobb@terrapoint.com

Hours_of_Service: Monday to Friday, 8 - 5, CST

Process_Step:

Process_Description:

- Data Classification and Editing

The data was processed using the software TerraScan, and

following the methodology described herein. The initial step is the setup of the TerraScan project, which is done by importing client provided tile boundary index encompassing the entire project areas. The 3D laser point clouds, in binary format, were imported into the TerraScan project and divided in 1097 tiles.

Once tiled, the laser points were classified using a proprietary routine in TerraScan. This routine removes any obvious outliers from the dataset following which the ground layer is extracted from the point cloud. The ground extraction process encompassed in this routine takes place by building an iterative surface model. This surface model is generated using three main parameters: building size, iteration angle and iteration distance. The initial model is based on low points being selected by a "roaming window" with the assumption is that these are the ground points. The size of this roaming window is determined by the building size parameter. The low points are triangulated and the remaining points are evaluated and subsequently added to the model if they meet the iteration angle and distance constraints. This process is repeated until no additional points are added within an iteration. A second critical parameter is the maximum terrain angle constraint, which determines the maximum terrain angle allowed within the classification model. The data is then manually quality controlled with the use of hillshading, cross-sections and profiles. Any points found to be of class vegetation, building or error during the quality control process, are removed from the ground model and placed on the appropriate layer. An integrity check is also performed simultaneously to verify that ground features such as rock cuts, elevated roads and crests are present. Once data has been cleaned and complete, it is then reviewed by a supervisor via manual inspection and through the use of a hillshade mosaic of the entire project area.

Source_Used_Citation_Abbreviation: Processing
Process_Date: 20070922
Source_Produced_Citation_Abbreviation: PRD
Process_Contact:
 Contact_Information:
 Contact_Person_Primary:
 Contact_Organization: Terrapoint USA
 Contact_Person: Peggy Cobb
 Contact_Position: Production Manager
 Contact_Address:
 Address_Type: mailing and physical address
 Address: 251216 Grogan's Park Drive
 City: The Woodlands
 State_or_Province: Texas
 Postal_Code: 77380
 Country: USA
 Contact_Voice_Telephone: 1-877-999-7687
 Contact_Facsimile_Telephone: 1-281-296-0869
 Contact_Electronic_Mail_Address: peggy.cobb@terrapoint.com
 Hours_of_Service: Monday to Friday, 8 - 5, CST

Process_Step:
 Process_Description:

-Deliverable Product Generation
 >LiDAR Point Data
 The LiDAR point data was delivered in LAS 1.0 adhering to the following ASPRS classification scheme:
 Class 1 - Non-ground; Class 2 - Ground; Class 7 - Noise; Class 9 - Water

The LAS files contain the following fields of information (Precision reported in brackets):
 Class (Integer); GPS Week Time (0.0001 seconds); Easting (0.01 meter); Northing (0.01 meter);
 Elevation (0.01 meter); Echo Number (Integer 1 to 4); Echo (Integer 1 to 4); Intensity (8 Bit Integer);
 Flightline (Integer); Scan Angle (Integer Degree)
 Point data was clipped to the project boundary.
 Water body delineation was collected using hillshades and intensity images generated from ground DEM and LiDAR.
 >FGDC Report
 Source_Used_Citation_Abbreviation: Processing_Deliverables
 Process_Date: 20080125
 Source_Produced_Citation_Abbreviation: PRD_DEL
 Process_Contact:
 Contact_Information:
 Contact_Person_Primary:
 Contact_Organization: Terrapoint USA
 Contact_Person: Peggy Cobb
 Contact_Position: Production Manager
 Contact_Address:
 Address_Type: mailing and physical address
 Address: 251216 Grogan's Park Drive
 City: The Woodlands
 State_or_Province: Texas
 Postal_Code: 77380
 Country: USA
 Contact_Voice_Telephone: 1-877-999-7687
 Contact_Facsimile_Telephone: 1-281-296-0869
 Contact_Electronic_Mail_Address: peggy.cobb@terrapoint.com
 Hours_of_Service: Monday to Friday, 8 - 5, CST

SPATIAL_REFERENCE_INFORMATION

Horizontal_Coordinate_System_Definition:
 Planar:
 Grid_Coordinate_System:
 Grid_Coordinate_System_Name: State Plane Coordinate System 1983
 State_Plane_Coordinate_System:
 SPCS_Zone_Identifier: 0903
 Transverse_Mercator:
 Scale_Factor_at_Central_Meridian: 0.9999
 Longitude_of_Central_Meridian: -84
 Latitude_of_Projection_Origin: 30
 False_Easting: 600000
 False_Northing: 0.000000
 Planar_Coordinate_Information:
 Planar_Coordinate_Encoding_Method: Coordinate pair
 Coordinate_Representation:
 Abscissa_Resolution: 0.01
 Ordinate_Resolution: 0.01

Planar_Distance_Units: US Survey Feet
Geodetic_Model:
Horizontal_Datum_Name: North American Datum of 1983 HARN
Ellipsoid_Name: GRS 80
Semi-major_Axis: 6378137.0000000
Denominator_of_Flattening_Ratio: 298.26
Vertical_Coordinate_System_Definition:
Altitude_System_Definition:
Altitude_Datum_Name: North American Vertical Datum of 1988
Altitude_Resolution: 0.01
Altitude_Distance_Units: US Survey Feet
Altitude_Encoding_Method: Explicit elevation coordinate included with
horizontal coordinates

ENTITY_AND_ATTRIBUTE_INFORMATION

Overview_Description:
Entity_and_Attribute_Overview:
Original LiDAR point data in LAS 1.0, all deliverables in LAS binary
1.1. The LAS binary files contain the following fields of information
(Precision reported in brackets):
Easting (0.01 meter); Northing (0.01 meter); Elevation (0.01 meter);
Class (Integer); Description; Flightline; Timestamp; Echo (return);
Intensity; Scan Angle; Echo number
Entity_and_Attribute_Detail_Citation: none

DISTRIBUTION_INFORMATION

Distributor:
Contact_Information:
Contact_Organization_Primary:
Contact_Organization: Terrapoint USA
Contact_Person: Peggy Cobb
Contact_Position: Production Manager
Contact_Address:
Address_Type: mailing and physical address
Address: 251216 Grogan's Park Drive
City: The Woodlands
State_or_Province: Texas
Postal_Code: 77380
Country: USA
Contact_Voice_Telephone: 1-877-999-7687
Contact_Facsimile_Telephone: 1-281-296-0869
Contact_Electronic_Mail_Address: peggy.cobb@terrapoint.com
Hours_of_Service: Monday to Friday, 8 - 5, CST

Resource_Description:
The LiDAR data was captured for Dewberry for
Proposed flood mapping purposes

Distribution_Liability:
Users must assume responsibility to determine the
appropriate use of this LiDAR dataset.

Data is representative of ground conditions at time of
acquisition only.

Standard_Order_Process:
Digital_Form:
Digital_Transfer_Information:

Format_Name:LAS binary
Digital_Transfer_Option:
Offline_Option:
 Offline_Media: Harddrive
 Recording_Format: Windows Compatible
 Compatibility_Information: Windows Compatible
Fees: Current Handling and Processing Terrapoint Fees
Ordering_Instructions:
 Proper release required from Dewberry for
 orders outside of Dewberry. Please contact Terrapoint
 sales for general Terrapoint LiDAR library sales.

METADATA_REFERENCE_INFORMATION

Metadata_Date: 20080613
Metadata_Review_Date: 20080617
Metadata_Contact:
 Contact_Information:
 Contact_Organization_Primary:
 Contact_Organization: Terrapoint USA
 Contact_Person: Peggy Cobb
 Contact_Position: Production Manager
 Contact_Address:
 Address_Type: Mailing and physical address
 Address: 251216 Grogan's Park Drive
 City: The Woodlands
 State_or_Province: Texas
 Postal_Code: 77380
 Country: USA
 Contact_Voice_Telephone: 1-877-999-7687
 Contact_Facsimile_Telephone: 1-281-296-0869
 Contact_Electronic_Mail_Address: peggy.cobb@terrapoint.com
 Hours_of_Service: Monday to Friday, 8 - 5, CST
Metadata_Standard_Name: FGDC CSDGM
Metadata_Standard_Version: FGDC-STD-001-1998

Appendix E: QA/QC Checkpoints and Accuracy Spreadsheet

Point Number	Land Cover Class		SPCS NAD83/99 East Zone		NAVD88	LIDAR-Z	ΔZ
			Easting-X (Ft)	Northing-Y (Ft)	Survey-Z Ft)		
FR001M4	1	BE & Low Grass	1,808,585.77	378,367.70	27.71	27.79	0.08
FR003M2	1	BE & Low Grass	1,846,726.92	360,138.72	31.24	30.59	-0.65
FR004M4	1	BE & Low Grass	1,867,418.58	360,187.22	28.44	28.53	0.09
FR005M6	1	BE & Low Grass	1,818,160.32	350,481.40	23.54	23.35	-0.19
FR006M4	1	BE & Low Grass	1,859,636.02	349,171.58	28.02	28.18	0.16
FR007M3	1	BE & Low Grass	1,806,335.42	344,129.34	16.72	16.56	-0.16
FR007M5	1	BE & Low Grass	1,806,413.98	344,101.58	15.56	15.26	-0.30
FR008M1	1	BE & Low Grass	1,814,380.72	317,393.41	9.70	9.29	-0.41
FR008M7	1	BE & Low Grass	1,814,183.46	317,397.52	10.69	10.19	-0.50
FR009M2	1	BE & Low Grass	1,831,926.20	321,887.74	15.17	14.74	-0.43
FR011M8	1	BE & Low Grass	1,827,141.35	306,043.12	10.71	10.71	0.00
FR012M3	1	BE & Low Grass	1,838,704.11	299,181.64	6.77	6.53	-0.24
FR013M3	1	BE & Low Grass	1,854,165.73	301,553.89	6.78	6.63	-0.15
FR014M4	1	BE & Low Grass	1,749,371.21	256,562.01	7.41	7.36	-0.05
FR016M8	1	BE & Low Grass	1,773,603.07	261,770.38	15.34	15.11	-0.23
FR017M8	1	BE & Low Grass	1,783,689.63	269,153.25	9.02	8.85	-0.17
FR018M9	1	BE & Low Grass	1,796,588.15	278,245.07	5.22	5.01	-0.22
FR019M4	1	BE & Low Grass	1,805,040.46	266,485.20	15.57	15.19	-0.38
FR020M3	1	BE & Low Grass	1,819,079.79	264,424.26	6.73	6.49	-0.25
FR021M5	1	BE & Low Grass	1,842,226.49	268,051.45	19.34	18.98	-0.36
FR022M8	1	BE & Low Grass	1,862,955.28	276,534.48	17.94	17.71	-0.23
FR023M4	1	BE & Low Grass	1,868,722.67	289,416.34	14.81	14.26	-0.55
FR024M7	1	BE & Low Grass	1,823,807.85	224,916.78	3.64	3.99	0.35
FR025M2	1	BE & Low Grass	1,851,596.56	241,127.70	5.73	5.67	-0.06
FR026M3	1	BE & Low Grass	1,876,774.10	250,747.11	4.18	4.09	-0.09
FR027M2	1	BE & Low Grass	1,898,933.11	269,088.19	4.04	4.24	0.20
FR028M6	1	BE & Low Grass	1,888,853.31	368,758.20	17.98	17.92	-0.06
FR029M5	1	BE & Low Grass	1,894,477.80	357,495.22	8.80	8.70	-0.10
FR031M3	1	BE & Low Grass	1,871,803.85	338,817.38	26.02	25.84	-0.18
FR032M7	1	BE & Low Grass	1,924,326.35	329,915.13	8.29	8.01	-0.28
FR034M2	1	BE & Low Grass	1,887,584.97	306,628.68	9.46	9.44	-0.02
FR035M2	1	BE & Low Grass	1,905,608.53	300,651.61	6.99	7.15	0.16
FR036M1	1	BE & Low Grass	1,892,726.24	291,949.07	8.92	9.14	0.22
FR036M4	1	BE & Low Grass	1,892,752.98	291,838.39	4.48	4.64	0.16
FR037M3	1	BE & Low Grass	1,873,418.94	279,831.39	8.66	8.58	-0.08
FR038M3	1	BE & Low Grass	1,943,561.82	323,185.36	10.50	10.28	-0.22
FR041M1	1	BE & Low Grass	1,963,726.17	333,327.13	13.53	13.94	0.41
FR042M2	1	BE & Low Grass	1,987,573.68	338,926.04	17.59	17.45	-0.14
FR043M5	1	BE & Low Grass	2,004,390.70	343,448.12	8.83	8.53	-0.30
FR044M3	1	BE & Low Grass	2,016,385.47	327,966.59	7.97	7.64	-0.33
FR001M3	2	Brush & Low Trees	1,808,653.55	378,329.49	30.63	30.71	0.08
FR002M1	2	Brush & Low Trees	1,831,709.91	368,046.61	30.91	30.88	-0.03
FR003M3	2	Brush & Low Trees	1,846,681.11	360,202.85	29.55	30.16	0.61
FR005M3	2	Brush & Low Trees	1,818,041.60	350,447.77	22.74	23.28	0.54
FR006M2	2	Brush & Low Trees	1,859,637.49	349,107.61	30.80	29.47	-1.33
FR007M10	2	Brush & Low Trees	1,806,313.78	343,844.62	16.23	16.21	-0.02
FR008M4	2	Brush & Low Trees	1,814,286.22	317,331.88	11.20	11.60	0.40
FR009M4	2	Brush & Low Trees	1,831,973.64	321,757.96	13.74	13.49	-0.25
FR010M4	2	Brush & Low Trees	1,865,272.54	319,922.88	12.18	12.68	0.50
FR011M5	2	Brush & Low Trees	1,826,954.97	306,113.18	8.95	9.16	0.21
FR013M6	2	Brush & Low Trees	1,854,157.54	301,527.82	6.99	6.45	-0.54
FR014M9	2	Brush & Low Trees	1,749,357.82	256,587.37	7.56	7.52	-0.04
FR015M5	2	Brush & Low Trees	1,764,549.14	259,978.81	15.15	15.07	-0.08

FR016M4	2	Brush & Low Trees	1,773,811.39	261,942.32	14.01	13.78	-0.23
FR017M6	2	Brush & Low Trees	1,783,675.75	268,901.19	8.54	8.82	0.28
FR018M8	2	Brush & Low Trees	1,796,854.42	278,098.25	5.49	5.54	0.05
FR020M7	2	Brush & Low Trees	1,818,781.44	264,370.71	6.94	6.55	-0.39
FR021M6	2	Brush & Low Trees	1,842,209.47	268,082.44	19.30	18.87	-0.43
FR022M2	2	Brush & Low Trees	1,862,545.53	276,370.54	16.70	16.55	-0.15
FR023M2	2	Brush & Low Trees	1,868,685.09	289,315.51	15.10	14.61	-0.49
FR024M8	2	Brush & Low Trees	1,823,818.19	224,890.17	3.30	3.57	0.27
FR025M6	2	Brush & Low Trees	1,851,594.93	241,153.32	6.16	6.24	0.08
FR026M4	2	Brush & Low Trees	1,876,813.42	250,639.30	4.34	4.42	0.08
FR027M5	2	Brush & Low Trees	1,898,802.51	269,138.95	12.89	12.88	-0.01
FR028M2	2	Brush & Low Trees	1,888,745.14	368,703.18	18.14	18.10	-0.04
FR030M1	2	Brush & Low Trees	1,908,860.09	348,888.52	20.04	20.07	0.03
FR030M4	2	Brush & Low Trees	1,908,886.59	349,025.86	19.71	20.07	0.36
FR031M5	2	Brush & Low Trees	1,871,807.76	338,664.89	25.71	26.13	0.42
FR031M6	2	Brush & Low Trees	1,871,802.37	338,551.01	25.80	26.28	0.48
FR032M4	2	Brush & Low Trees	1,924,441.82	329,799.16	10.83	11.32	0.49
FR033M1	2	Brush & Low Trees	1,917,689.55	318,288.27	13.09	13.29	0.20
FR034M6	2	Brush & Low Trees	1,887,686.94	306,643.76	8.61	8.87	0.26
FR036M2	2	Brush & Low Trees	1,892,658.62	291,907.97	8.87	8.83	-0.04
FR037M1	2	Brush & Low Trees	1,873,532.79	279,831.20	7.54	7.45	-0.09
FR038M6	2	Brush & Low Trees	1,943,652.80	323,334.12	12.33	12.07	-0.26
FR039M2	2	Brush & Low Trees	1,934,932.14	362,309.99	15.67	15.56	-0.11
FR040M3	2	Brush & Low Trees	1,967,089.69	346,077.08	20.60	20.30	-0.31
FR041M5	2	Brush & Low Trees	1,963,727.61	333,492.56	15.79	16.13	0.34
FR043M9	2	Brush & Low Trees	2,004,329.53	343,341.42	10.79	10.48	-0.31
FR044M7	2	Brush & Low Trees	2,016,455.67	328,028.89	12.11	12.00	-0.11
FR002M4	3	Forested	1,831,739.43	367,957.82	31.14	29.99	-1.15
FR003M4	3	Forested	1,846,772.63	360,201.66	29.73	29.33	-0.40
FR004M7	3	Forested	1,867,487.82	360,172.45	28.31	28.82	0.51
FR005M1	3	Forested	1,817,892.87	350,423.32	24.25	24.63	0.38
FR006M5	3	Forested	1,859,723.10	349,206.06	29.17	28.95	-0.23
FR007M9	3	Forested	1,806,437.19	344,069.04	16.20	16.20	0.00
FR008M9	3	Forested	1,814,272.46	317,458.27	9.79	9.27	-0.52
FR009M7	3	Forested	1,831,724.02	321,898.12	15.14	14.20	-0.94
FR010M3	3	Forested	1,865,291.94	319,838.43	11.60	11.65	0.05
FR011M1	3	Forested	1,826,860.69	306,030.87	9.23	9.47	0.24
FR012M6	3	Forested	1,838,629.63	299,073.79	6.75	6.78	0.03
FR013M5	3	Forested	1,854,225.71	301,529.33	7.26	7.18	-0.09
FR014M10	3	Forested	1,749,286.42	256,599.97	8.17	8.75	0.58
FR015M7	3	Forested	1,764,564.11	260,028.93	15.86	17.09	1.23
FR016M7	3	Forested	1,773,831.66	261,833.61	13.82	15.55	1.73
FR017M7	3	Forested	1,783,647.04	268,876.73	8.66	8.73	0.07
FR018M4	3	Forested	1,796,742.59	278,152.58	5.36	5.02	-0.35
FR019M1	3	Forested	1,805,116.08	266,508.16	15.55	15.49	-0.06
FR020M9	3	Forested	1,819,196.92	264,447.58	6.50	6.34	-0.16
FR021M10	3	Forested	1,842,202.61	268,137.45	19.61	19.07	-0.54
FR022M7	3	Forested	1,862,429.00	276,452.03	17.53	17.23	-0.30
FR023M5	3	Forested	1,868,776.37	289,427.14	14.06	13.56	-0.50
FR024M4	3	Forested	1,823,643.11	224,899.80	2.46	3.27	0.81
FR025M9	3	Forested	1,851,638.28	241,197.80	6.57	7.53	0.96
FR026M6	3	Forested	1,876,732.99	250,667.85	3.36	3.85	0.49
FR028M3	3	Forested	1,888,793.20	368,721.16	17.27	17.64	0.37
FR029M1	3	Forested	1,894,615.14	357,510.69	10.13	9.92	-0.21
FR029M4	3	Forested	1,894,669.83	357,388.29	9.15	8.82	-0.33
FR031M7	3	Forested	1,871,843.35	338,711.66	24.33	23.74	-0.59
FR032M6	3	Forested	1,924,279.20	329,876.26	8.95	8.79	-0.16
FR033M8	3	Forested	1,917,794.54	318,366.21	11.46	11.70	0.24
FR034M4	3	Forested	1,887,628.43	306,747.42	8.39	8.52	0.13
FR035M4	3	Forested	1,905,731.36	300,718.86	7.04	6.71	-0.33
FR037M2	3	Forested	1,873,497.26	279,777.03	7.37	7.32	-0.05

FR038M1	3	Forested	1,943,647.70	323,112.90	8.67	8.34	-0.33
FR039M6	3	Forested	1,935,068.67	362,338.08	15.79	15.93	0.14
FR040M9	3	Forested	1,967,369.58	346,026.22	13.63	13.06	-0.57
FR041M2	3	Forested	1,963,693.67	333,198.67	11.90	11.89	-0.01
FR042M4	3	Forested	1,987,607.79	339,072.92	27.28	27.06	-0.22
FR043M3	3	Forested	2,004,482.38	343,359.00	7.87	7.89	0.01
FR044M6	3	Forested	2,016,435.04	327,869.80	7.32	6.99	-0.33
FR001M5	4	Urban	1,808,552.77	378,351.56	29.59	29.73	0.14
FR001M6	4	Urban	1,808,484.76	378,358.74	30.29	30.55	0.26
FR002M5	4	Urban	1,831,723.90	367,878.93	31.11	31.32	0.21
FR004M1	4	Urban	1,867,458.56	360,129.74	29.94	30.05	0.11
FR005M5	4	Urban	1,818,099.79	350,463.90	24.54	24.46	-0.08
FR006M3	4	Urban	1,859,555.81	349,127.78	32.03	31.71	-0.32
FR010M2	4	Urban	1,865,344.79	319,867.22	13.97	13.90	-0.07
FR011M2	4	Urban	1,826,793.86	306,117.58	11.86	11.61	-0.25
FR012M7	4	Urban	1,838,700.25	299,436.64	8.04	7.68	-0.36
FR013M1	4	Urban	1,854,098.84	301,443.46	9.08	8.74	-0.34
FR014M1	4	Urban	1,749,260.77	256,474.49	8.27	7.98	-0.29
FR015M2	4	Urban	1,764,581.43	259,914.32	17.29	16.91	-0.38
FR016M1	4	Urban	1,773,895.59	261,901.16	15.29	14.83	-0.46
FR017M3	4	Urban	1,783,709.63	268,802.47	8.09	7.70	-0.39
FR018M2	4	Urban	1,796,683.35	278,118.36	6.54	6.42	-0.12
FR019M10	4	Urban	1,805,150.91	266,451.65	15.89	15.33	-0.56
FR020M4	4	Urban	1,818,932.35	264,338.74	6.68	6.45	-0.23
FR021M1	4	Urban	1,842,036.98	268,007.56	20.63	20.25	-0.38
FR022M4	4	Urban	1,862,456.01	276,404.30	17.98	17.74	-0.24
FR024M6	4	Urban	1,823,798.38	224,941.11	4.12	4.47	0.35
FR025M8	4	Urban	1,851,961.51	241,268.93	6.01	6.31	0.30
FR028M1	4	Urban	1,888,781.23	368,638.88	17.08	17.04	-0.04
FR029M3	4	Urban	1,894,655.42	357,469.75	10.73	10.57	-0.17
FR030M2	4	Urban	1,908,926.82	348,931.26	20.87	20.92	0.05
FR030M3	4	Urban	1,908,850.97	348,959.47	20.97	21.14	0.17
FR032M2	4	Urban	1,924,469.95	329,922.06	10.05	9.64	-0.41
FR032M5	4	Urban	1,924,325.83	329,792.64	11.59	11.24	-0.35
FR033M4	4	Urban	1,917,696.04	318,393.43	13.69	13.68	-0.01
FR033M9	4	Urban	1,917,758.12	318,305.21	13.83	13.86	0.03
FR035M5	4	Urban	1,905,778.96	300,706.60	8.86	8.75	-0.11
FR035M6	4	Urban	1,905,725.75	300,654.39	9.83	9.48	-0.35
FR036M7	4	Urban	1,892,694.13	291,870.50	9.08	9.05	-0.03
FR037M6	4	Urban	1,873,388.51	279,708.16	8.78	8.46	-0.32
FR038M4	4	Urban	1,943,529.64	323,227.56	11.64	11.55	-0.10
FR039M1	4	Urban	1,934,966.65	362,466.76	17.55	17.20	-0.35
FR039M5	4	Urban	1,935,000.81	362,305.20	18.80	18.54	-0.26
FR040M6	4	Urban	1,967,267.32	345,994.77	20.19	19.91	-0.28
FR040M8	4	Urban	1,967,306.43	346,056.82	16.18	16.35	0.17
FR041M6	4	Urban	1,963,682.85	333,452.29	16.45	16.63	0.18
FR042M1	4	Urban	1,987,589.63	338,955.91	18.54	18.53	-0.01
FR042M5	4	Urban	1,987,646.22	339,041.76	23.40	23.14	-0.26
FR043M2	4	Urban	2,004,446.32	343,424.70	11.03	10.83	-0.20
FR044M5	4	Urban	2,016,474.25	327,826.47	8.47	8.27	-0.21

100 % of Totals	# of Points	RMSE (ft) Spec = 0.61 (BE = 0.30)	Mean (ft)	Median (ft)	Min (ft)	Max (ft)
Consolidated	164	0.38	-0.07	-0.01	-1.33	1.73
BE & Low Grass	40	0.27	-0.14	-0.16	-0.65	0.41
Brush & Low Trees	40	0.37	0.01	-0.02	-1.33	0.61
Forested	41	0.54	-0.01	-0.06	-1.15	1.73
Urban	43	0.27	-0.14	-0.20	-0.56	0.35

Land Cover Category	# of Points	FVA — Fundamental Vertical Accuracy (RMSEz x 1.9600) Spec = 0.60 ft	CVA — Consolidated Vertical Accuracy (95th Percentile) Spec = 1.19 ft	SVA — Supplemental Vertical Accuracy (95th Percentile) Target = 1.19 ft
Consolidated	164		0.61	
BE & Low Grass	40	0.53		
Brush & Low Trees	40			0.55
Forested	41			1.15
Urban	43			0.41

Franklin County - Vertical Accuracy Assessment for Category 1 Points						
Point No	Land Cover Class	LIDAR TIN - Z	Survey - Z	ΔZ	ΔZ^2	ABS ΔZ
FR001M4	1	27.79	27.71	0.08	0.01	0.08
FR003M2	1	30.59	31.24	-0.65	0.43	0.65
FR004M4	1	28.53	28.44	0.09	0.01	0.09
FR005M6	1	23.35	23.54	-0.19	0.04	0.19
FR006M4	1	28.18	28.02	0.16	0.02	0.16
FR007M3	1	16.56	16.72	-0.16	0.03	0.16
FR007M5	1	15.26	15.56	-0.30	0.09	0.30
FR008M1	1	9.29	9.7	-0.41	0.17	0.41
FR008M7	1	10.19	10.69	-0.50	0.25	0.50
FR009M2	1	14.74	15.17	-0.43	0.18	0.43
FR011M8	1	10.71	10.71	0.00	0.00	0.00
FR012M3	1	6.53	6.77	-0.24	0.06	0.24
FR013M3	1	6.63	6.78	-0.15	0.02	0.15
FR014M4	1	7.36	7.41	-0.05	0.00	0.05
FR016M8	1	15.11	15.34	-0.23	0.05	0.23
FR017M8	1	8.85	9.02	-0.17	0.03	0.17
FR018M9	1	5.01	5.22	-0.22	0.05	0.22
FR019M4	1	15.19	15.57	-0.38	0.15	0.38
FR020M3	1	6.49	6.73	-0.25	0.06	0.25
FR021M5	1	18.98	19.34	-0.36	0.13	0.36
FR022M8	1	17.71	17.94	-0.23	0.06	0.23
FR023M4	1	14.26	14.81	-0.55	0.31	0.55
FR024M7	1	3.99	3.64	0.35	0.12	0.35
FR025M2	1	5.67	5.73	-0.06	0.00	0.06
FR026M3	1	4.09	4.18	-0.09	0.01	0.09
FR027M2	1	4.24	4.04	0.20	0.04	0.20
FR028M6	1	17.92	17.98	-0.06	0.00	0.06
FR029M5	1	8.70	8.8	-0.10	0.01	0.10
FR031M3	1	25.84	26.02	-0.18	0.03	0.18
FR032M7	1	8.01	8.29	-0.28	0.08	0.28
FR034M2	1	9.44	9.46	-0.02	0.00	0.02
FR035M2	1	7.15	6.99	0.16	0.02	0.16
FR036M1	1	9.14	8.92	0.22	0.05	0.22
FR036M4	1	4.64	4.48	0.16	0.02	0.16
FR037M3	1	8.58	8.66	-0.08	0.01	0.08
FR038M3	1	10.28	10.5	-0.22	0.05	0.22
FR041M1	1	13.94	13.53	0.41	0.17	0.41
FR042M2	1	17.45	17.59	-0.14	0.02	0.14
FR043M5	1	8.53	8.83	-0.30	0.09	0.30
FR044M3	1	7.64	7.97	-0.33	0.11	0.33
	Geo-Referencing			sum of dz ²	2.97	
	Horiz	NAD83(1992) NZ		count	40.00	

	Vert.	NAVD88 (Geoid99)		sum dz2/count	0.07	
	Units	US Survey Feet		RMSE	0.27	
				1.96 * RMSE	0.53	
	RMSE Calculation			mean	-0.14	
	Square Root of $\sum(Z_n - Z_n)^2/N$			median	-0.16	
	Zn = LiDAR Dem Heights			skew	0.24	
	Z'n = Checkpoint Heights			std dev	0.24	
	N = The number of check points			95th percentile	0.50	
Ground Cover CAT	CAT Description	Survey CAT	Surv. CAT Ground Cover Equivalent	DZ MIN	DZ MAX	
CAT 1	BE & Low Grass	GND 1, DRD, MGF	GND 1 = Ground - BE & Low Grass	-0.65	0.41	
CAT 2	Brush & Low Trees	GND 2	GND 2 = Ground - Brush & Low Trees			
CAT 3	Forested	GND 3	GND 3 = Ground - Forested			
CAT 4	Urban	PVM 4	DRD = Ground - Dirt/Clay Road			
			PVM = Pavement (Asphalt/Concrete)			
			MGF= Well Maintained Ground Feature			
Land Cover Categories and Accuracy Criteria			Computed Accuracies			
Ground Cover CAT	RMSEz (Ft) ≤	ACCURACYz (Ft) ≤	Actual RMSEz	95% Acc Z	95th Percentile	
CAT 1	0.30	0.60	0.27	0.53	0.50	
CAT 2	0.61	1.19				
CAT 3	0.61	1.19				
CAT 4	0.61	1.19				
COMBINED	0.61	1.19				

Franklin County - Vertical Accuracy Assessment for Category 2 Points						
PID	Land Cover Cat.	LIDAR TIN - Z	Survey Height	DELTA Z	DZ ²	ABS DZ
FR001M3	2	30.71	30.63	0.08	0.01	0.08
FR002M1	2	30.88	30.91	-0.03	0.00	0.03
FR003M3	2	30.16	29.55	0.61	0.37	0.61
FR005M3	2	23.28	22.74	0.54	0.29	0.54
FR006M2	2	29.47	30.8	-1.33	1.76	1.33
FR007M10	2	16.21	16.23	-0.02	0.00	0.02
FR008M4	2	11.60	11.2	0.40	0.16	0.40
FR009M4	2	13.49	13.74	-0.25	0.06	0.25
FR010M4	2	12.68	12.18	0.50	0.25	0.50
FR011M5	2	9.16	8.95	0.21	0.04	0.21
FR013M6	2	6.45	6.99	-0.54	0.29	0.54
FR014M9	2	7.52	7.56	-0.04	0.00	0.04
FR015M5	2	15.07	15.15	-0.08	0.01	0.08
FR016M4	2	13.78	14.01	-0.23	0.05	0.23
FR017M6	2	8.82	8.54	0.28	0.08	0.28
FR018M8	2	5.54	5.49	0.05	0.00	0.05
FR020M7	2	6.55	6.94	-0.39	0.15	0.39
FR021M6	2	18.87	19.3	-0.43	0.19	0.43
FR022M2	2	16.55	16.7	-0.15	0.02	0.15
FR023M2	2	14.61	15.1	-0.49	0.24	0.49
FR024M8	2	3.57	3.3	0.27	0.07	0.27
FR025M6	2	6.24	6.16	0.08	0.01	0.08
FR026M4	2	4.42	4.34	0.08	0.01	0.08
FR027M5	2	12.88	12.89	-0.01	0.00	0.01
FR028M2	2	18.10	18.14	-0.04	0.00	0.04
FR030M1	2	20.07	20.04	0.03	0.00	0.03
FR030M4	2	20.07	19.71	0.36	0.13	0.36
FR031M5	2	26.13	25.71	0.42	0.18	0.42
FR031M6	2	26.28	25.8	0.48	0.23	0.48
FR032M4	2	11.32	10.83	0.49	0.24	0.49
FR033M1	2	13.29	13.09	0.20	0.04	0.20
FR034M6	2	8.87	8.61	0.26	0.07	0.26
FR036M2	2	8.83	8.87	-0.04	0.00	0.04
FR037M1	2	7.45	7.54	-0.09	0.01	0.09
FR038M6	2	12.07	12.33	-0.26	0.07	0.26
FR039M2	2	15.56	15.67	-0.11	0.01	0.11
FR040M3	2	20.30	20.6	-0.31	0.09	0.31
FR041M5	2	16.13	15.79	0.34	0.12	0.34
FR043M9	2	10.48	10.79	-0.31	0.10	0.31
FR044M7	2	12.00	12.11	-0.11	0.01	0.11
				sum of dz ²	5.35	
	Horiz	NAD83(1992) NZ		count	40.00	
	Vert.	NAVD88 (Geoid99)		sum dz ² /count	0.13	

Franklin County - Vertical Accuracy Assessment for Category 3 Points						
PID	Land Cover Cat.	DTM Height	Survey Height	DELTA Z	DZ ²	ABS DZ
FR002M4	3	29.99	31.14	-1.15	1.32	1.15
FR003M4	3	29.33	29.73	-0.40	0.16	0.40
FR004M7	3	28.82	28.31	0.51	0.26	0.51
FR005M1	3	24.63	24.25	0.38	0.14	0.38
FR006M5	3	28.95	29.17	-0.23	0.05	0.23
FR007M9	3	16.20	16.2	0.00	0.00	0.00
FR008M9	3	9.27	9.79	-0.52	0.27	0.52
FR009M7	3	14.20	15.14	-0.94	0.89	0.94
FR010M3	3	11.65	11.6	0.05	0.00	0.05
FR011M1	3	9.47	9.23	0.24	0.06	0.24
FR012M6	3	6.78	6.75	0.03	0.00	0.03
FR013M5	3	7.18	7.26	-0.09	0.01	0.09
FR014M10	3	8.75	8.17	0.58	0.34	0.58
FR015M7	3	17.09	15.86	1.23	1.51	1.23
FR016M7	3	15.55	13.82	1.73	2.98	1.73
FR017M7	3	8.73	8.66	0.07	0.00	0.07
FR018M4	3	5.02	5.36	-0.35	0.12	0.35
FR019M1	3	15.49	15.55	-0.06	0.00	0.06
FR020M9	3	6.34	6.5	-0.16	0.03	0.16
FR021M10	3	19.07	19.61	-0.54	0.29	0.54
FR022M7	3	17.23	17.53	-0.30	0.09	0.30
FR023M5	3	13.56	14.06	-0.50	0.25	0.50
FR024M4	3	3.27	2.46	0.81	0.66	0.81
FR025M9	3	7.53	6.57	0.96	0.91	0.96
FR026M6	3	3.85	3.36	0.49	0.24	0.49
FR028M3	3	17.64	17.27	0.37	0.14	0.37
FR029M1	3	9.92	10.13	-0.21	0.04	0.21
FR029M4	3	8.82	9.15	-0.33	0.11	0.33
FR031M7	3	23.74	24.33	-0.59	0.35	0.59
FR032M6	3	8.79	8.95	-0.16	0.02	0.16
FR033M8	3	11.70	11.46	0.24	0.06	0.24
FR034M4	3	8.52	8.39	0.13	0.02	0.13
FR035M4	3	6.71	7.04	-0.33	0.11	0.33
FR037M2	3	7.32	7.37	-0.05	0.00	0.05
FR038M1	3	8.34	8.67	-0.33	0.11	0.33
FR039M6	3	15.93	15.79	0.14	0.02	0.14
FR040M9	3	13.06	13.63	-0.57	0.32	0.57
FR041M2	3	11.89	11.9	-0.01	0.00	0.01
FR042M4	3	27.06	27.28	-0.22	0.05	0.22
FR043M3	3	7.89	7.87	0.01	0.00	0.01
FR044M6	3	6.99	7.32	-0.33	0.11	0.33
	Geo-Referencing			sum of dz ²	12.04	
	Horiz	NAD83(1992) NZ		count	41.00	

	Vert.	NAVD88 (Geoid99)		sum dz2/count	0.29	
	Units	US Survey Feet		RMSE	0.54	
				1.96 * RMSE	1.06	
	RMSE Calculation			mean	-0.01	
	Square Root of $\sum(Z_n - Z'_n)^2/N$			median	-0.06	
	Zn = LiDAR Dem Heights			skew	0.94	
	Z'n = Checkpoint Heights			std dev	0.55	
	N = The number of check points			95th percentile	1.15	
Ground Cover CAT	CAT Description	Survey CAT	Surv. CAT Ground Cover Equivalent		DZ MIN	DZ MAX
CAT 1	BE & Low Grass	GND 1, DRD, MGF	GND 1 = Ground - BE & Low Grass		-1.15	1.73
CAT 2	Brush & Low Trees	GND 2	GND 2 = Ground - Brush & Low Trees			
CAT 3	Forested	GND 3	GND 3 = Ground - Forested			
CAT 4	Urban	PVM 4	DRD = Ground - Dirt/Clay Road			
			PVM = Pavement (Asphalt/Concrete)			
			MGF = Well Maintained Ground Feature			
Land Cover Categories and Accuracy Criteria			Computed Accuracies			
Ground Cover CAT	RMSEz (Ft) \leq	ACCURACYz (Ft) \leq	Actual RMSEz	95% Acc Z	95th Percentile	
CAT 1	0.30	0.60				
CAT 2	0.61	1.19				
CAT 3	0.61	1.19	0.54	1.06	1.15	
CAT 4	0.61	1.19				
COMBINED	0.61	1.19				

Franklin County - Vertical Accuracy Assessment for Category 4 Points						
PID	Land Cover Cat.	DTM Height	Survey Height	DELTA Z	DZ *2	ABS DZ
FR001M5	4	29.73	29.59	0.14	0.02	0.14
FR001M6	4	30.55	30.29	0.26	0.07	0.26
FR002M5	4	31.32	31.11	0.21	0.04	0.21
FR004M1	4	30.05	29.94	0.11	0.01	0.11
FR005M5	4	24.46	24.54	-0.08	0.01	0.08
FR006M3	4	31.71	32.03	-0.32	0.10	0.32
FR010M2	4	13.90	13.97	-0.07	0.00	0.07
FR011M2	4	11.61	11.86	-0.25	0.06	0.25
FR012M7	4	7.68	8.04	-0.36	0.13	0.36
FR013M1	4	8.74	9.08	-0.34	0.12	0.34
FR014M1	4	7.98	8.27	-0.29	0.08	0.29
FR015M2	4	16.91	17.29	-0.38	0.15	0.38
FR016M1	4	14.83	15.29	-0.46	0.21	0.46
FR017M3	4	7.70	8.09	-0.39	0.15	0.39
FR018M2	4	6.42	6.54	-0.12	0.01	0.12
FR019M10	4	15.33	15.89	-0.56	0.32	0.56
FR020M4	4	6.45	6.68	-0.23	0.06	0.23
FR021M1	4	20.25	20.63	-0.38	0.14	0.38
FR022M4	4	17.74	17.98	-0.24	0.06	0.24
FR024M6	4	4.47	4.12	0.35	0.12	0.35
FR025M8	4	6.31	6.01	0.30	0.09	0.30
FR028M1	4	17.04	17.08	-0.04	0.00	0.04
FR029M3	4	10.57	10.73	-0.17	0.03	0.17
FR030M2	4	20.92	20.87	0.05	0.00	0.05
FR030M3	4	21.14	20.97	0.17	0.03	0.17
FR032M2	4	9.64	10.05	-0.41	0.17	0.41
FR032M5	4	11.24	11.59	-0.35	0.12	0.35
FR033M4	4	13.68	13.69	-0.01	0.00	0.01
FR033M9	4	13.86	13.83	0.03	0.00	0.03
FR035M5	4	8.75	8.86	-0.11	0.01	0.11
FR035M6	4	9.48	9.83	-0.35	0.12	0.35
FR036M7	4	9.05	9.08	-0.03	0.00	0.03
FR037M6	4	8.46	8.78	-0.32	0.10	0.32
FR038M4	4	11.55	11.64	-0.10	0.01	0.10
FR039M1	4	17.20	17.55	-0.35	0.12	0.35
FR039M5	4	18.54	18.8	-0.26	0.07	0.26
FR040M6	4	19.91	20.19	-0.28	0.08	0.28
FR040M8	4	16.35	16.18	0.17	0.03	0.17
FR041M6	4	16.63	16.45	0.18	0.03	0.18
FR042M1	4	18.53	18.54	-0.01	0.00	0.01
FR042M5	4	23.14	23.4	-0.26	0.07	0.26
FR043M2	4	10.83	11.03	-0.20	0.04	0.20
FR044M5	4	8.27	8.47	-0.21	0.04	0.21

	Geo-Referencing			sum of dz ²	3.02
	Horiz	NAD83(1992) NZ		count	43.00
	Vert.	NAVD88 (Geoid99)		sum dz ² /count	0.07
	Units	US Survey Feet		RMSE	0.27
				1.96 * RMSE	0.52
	RMSE Calculation			mean	-0.14
	Square Root of $\sum(Z_n - Z_n)^2/N$			median	-0.20
	Zn = LiDAR Dem Heights			skew	0.42
	Zn = Checkpoint Heights			std dev	0.23
	N = The number of check points			95th percentile	0.41
Ground Cover CAT	CAT Description	Survey CAT	Surv. CAT Ground Cover Equivalent	DZ MIN	DZ MAX
CAT 1	BE & Low Grass	GND 1, DRD, MGF	GND 1 = Ground - BE & Low Grass	-0.56	0.35
CAT 2	Brush & Low Trees	GND 2	GND 2 = Ground - Brush & Low Trees		
CAT 3	Forested	GND 3	GND 3 = Ground - Forested		
CAT 4	Urban	PVM 4	DRD = Ground - Dirt/Clay Road		
			PVM = Pavement (Asphalt/Concrete)		
			MGF= Well Maintained Ground Feature		
Land Cover Categories and Accuracy Criteria			Computed Accuracies		
Ground Cover CAT	RMSEz (Ft) ≤	ACCURACYz (Ft) ≤	Actual RMSEz	95% Acc Z	95th Percentile
CAT 1	0.30	0.60			
CAT 2	0.61	1.19			
CAT 3	0.61	1.19			
CAT 4	0.61	1.19	0.27	0.52	0.41
COMBINED	0.61	1.19			

Franklin County - Vertical Accuracy Assessment for All Categories Combined						
PID	Land Cover Cat.	DTM Height	Survey Height	DELTA Z	DZ*2	ABS DZ
FR001M4	1	27.79	27.71	0.08	0.01	0.08
FR003M2	1	30.59	31.24	-0.65	0.43	0.65
FR004M4	1	28.53	28.44	0.09	0.01	0.09
FR005M6	1	23.35	23.54	-0.19	0.04	0.19
FR006M4	1	28.18	28.02	0.16	0.02	0.16
FR007M3	1	16.56	16.72	-0.16	0.03	0.16
FR007M5	1	15.26	15.56	-0.30	0.09	0.30
FR008M1	1	9.29	9.7	-0.41	0.17	0.41
FR008M7	1	10.19	10.69	-0.50	0.25	0.50
FR009M2	1	14.74	15.17	-0.43	0.18	0.43
FR011M8	1	10.71	10.71	0.00	0.00	0.00
FR012M3	1	6.53	6.77	-0.24	0.06	0.24
FR013M3	1	6.63	6.78	-0.15	0.02	0.15
FR014M4	1	7.36	7.41	-0.05	0.00	0.05
FR016M8	1	15.11	15.34	-0.23	0.05	0.23
FR017M8	1	8.85	9.02	-0.17	0.03	0.17
FR018M9	1	5.01	5.22	-0.22	0.05	0.22
FR019M4	1	15.19	15.57	-0.38	0.15	0.38
FR020M3	1	6.49	6.73	-0.25	0.06	0.25
FR021M5	1	18.98	19.34	-0.36	0.13	0.36
FR022M8	1	17.71	17.94	-0.23	0.06	0.23
FR023M4	1	14.26	14.81	-0.55	0.31	0.55
FR024M7	1	3.99	3.64	0.35	0.12	0.35
FR025M2	1	5.67	5.73	-0.06	0.00	0.06
FR026M3	1	4.09	4.18	-0.09	0.01	0.09
FR027M2	1	4.24	4.04	0.20	0.04	0.20
FR028M6	1	17.92	17.98	-0.06	0.00	0.06
FR029M5	1	8.70	8.8	-0.10	0.01	0.10
FR031M3	1	25.84	26.02	-0.18	0.03	0.18
FR032M7	1	8.01	8.29	-0.28	0.08	0.28
FR034M2	1	9.44	9.46	-0.02	0.00	0.02
FR035M2	1	7.15	6.99	0.16	0.02	0.16
FR036M1	1	9.14	8.92	0.22	0.05	0.22
FR036M4	1	4.64	4.48	0.16	0.02	0.16
FR037M3	1	8.58	8.66	-0.08	0.01	0.08
FR038M3	1	10.28	10.5	-0.22	0.05	0.22
FR041M1	1	13.94	13.53	0.41	0.17	0.41
FR042M2	1	17.45	17.59	-0.14	0.02	0.14
FR043M5	1	8.53	8.83	-0.30	0.09	0.30
FR044M3	1	7.64	7.97	-0.33	0.11	0.33
FR001M3	2	30.71	30.63	0.08	0.01	0.08
FR002M1	2	30.88	30.91	-0.03	0.00	0.03
FR003M3	2	30.16	29.55	0.61	0.37	0.61
FR005M3	2	23.28	22.74	0.54	0.29	0.54

FR006M2	2	29.47	30.8	-1.33	1.76	1.33
FR007M10	2	16.21	16.23	-0.02	0.00	0.02
FR008M4	2	11.60	11.2	0.40	0.16	0.40
FR009M4	2	13.49	13.74	-0.25	0.06	0.25
FR010M4	2	12.68	12.18	0.50	0.25	0.50
FR011M5	2	9.16	8.95	0.21	0.04	0.21
FR013M6	2	6.45	6.99	-0.54	0.29	0.54
FR014M9	2	7.52	7.56	-0.04	0.00	0.04
FR015M5	2	15.07	15.15	-0.08	0.01	0.08
FR016M4	2	13.78	14.01	-0.23	0.05	0.23
FR017M6	2	8.82	8.54	0.28	0.08	0.28
FR018M8	2	5.54	5.49	0.05	0.00	0.05
FR020M7	2	6.55	6.94	-0.39	0.15	0.39
FR021M6	2	18.87	19.3	-0.43	0.19	0.43
FR022M2	2	16.55	16.7	-0.15	0.02	0.15
FR023M2	2	14.61	15.1	-0.49	0.24	0.49
FR024M8	2	3.57	3.3	0.27	0.07	0.27
FR025M6	2	6.24	6.16	0.08	0.01	0.08
FR026M4	2	4.42	4.34	0.08	0.01	0.08
FR027M5	2	12.88	12.89	-0.01	0.00	0.01
FR028M2	2	18.10	18.14	-0.04	0.00	0.04
FR030M1	2	20.07	20.04	0.03	0.00	0.03
FR030M4	2	20.07	19.71	0.36	0.13	0.36
FR031M5	2	26.13	25.71	0.42	0.18	0.42
FR031M6	2	26.28	25.8	0.48	0.23	0.48
FR032M4	2	11.32	10.83	0.49	0.24	0.49
FR033M1	2	13.29	13.09	0.20	0.04	0.20
FR034M6	2	8.87	8.61	0.26	0.07	0.26
FR036M2	2	8.83	8.87	-0.04	0.00	0.04
FR037M1	2	7.45	7.54	-0.09	0.01	0.09
FR038M6	2	12.07	12.33	-0.26	0.07	0.26
FR039M2	2	15.56	15.67	-0.11	0.01	0.11
FR040M3	2	20.30	20.6	-0.31	0.09	0.31
FR041M5	2	16.13	15.79	0.34	0.12	0.34
FR043M9	2	10.48	10.79	-0.31	0.10	0.31
FR044M7	2	12.00	12.11	-0.11	0.01	0.11
FR002M4	3	29.99	31.14	-1.15	1.32	1.15
FR003M4	3	29.33	29.73	-0.40	0.16	0.40
FR004M7	3	28.82	28.31	0.51	0.26	0.51
FR005M1	3	24.63	24.25	0.38	0.14	0.38
FR006M5	3	28.95	29.17	-0.23	0.05	0.23
FR007M9	3	16.20	16.2	0.00	0.00	0.00
FR008M9	3	9.27	9.79	-0.52	0.27	0.52
FR009M7	3	14.20	15.14	-0.94	0.89	0.94
FR010M3	3	11.65	11.6	0.05	0.00	0.05
FR011M1	3	9.47	9.23	0.24	0.06	0.24
FR012M6	3	6.78	6.75	0.03	0.00	0.03

FR013M5	3	7.18	7.26	-0.09	0.01	0.09
FR014M10	3	8.75	8.17	0.58	0.34	0.58
FR015M7	3	17.09	15.86	1.23	1.51	1.23
FR016M7	3	15.55	13.82	1.73	2.98	1.73
FR017M7	3	8.73	8.66	0.07	0.00	0.07
FR018M4	3	5.02	5.36	-0.35	0.12	0.35
FR019M1	3	15.49	15.55	-0.06	0.00	0.06
FR020M9	3	6.34	6.5	-0.16	0.03	0.16
FR021M10	3	19.07	19.61	-0.54	0.29	0.54
FR022M7	3	17.23	17.53	-0.30	0.09	0.30
FR023M5	3	13.56	14.06	-0.50	0.25	0.50
FR024M4	3	3.27	2.46	0.81	0.66	0.81
FR025M9	3	7.53	6.57	0.96	0.91	0.96
FR026M6	3	3.85	3.36	0.49	0.24	0.49
FR028M3	3	17.64	17.27	0.37	0.14	0.37
FR029M1	3	9.92	10.13	-0.21	0.04	0.21
FR029M4	3	8.82	9.15	-0.33	0.11	0.33
FR031M7	3	23.74	24.33	-0.59	0.35	0.59
FR032M6	3	8.79	8.95	-0.16	0.02	0.16
FR033M8	3	11.70	11.46	0.24	0.06	0.24
FR034M4	3	8.52	8.39	0.13	0.02	0.13
FR035M4	3	6.71	7.04	-0.33	0.11	0.33
FR037M2	3	7.32	7.37	-0.05	0.00	0.05
FR038M1	3	8.34	8.67	-0.33	0.11	0.33
FR039M6	3	15.93	15.79	0.14	0.02	0.14
FR040M9	3	13.06	13.63	-0.57	0.32	0.57
FR041M2	3	11.89	11.9	-0.01	0.00	0.01
FR042M4	3	27.06	27.28	-0.22	0.05	0.22
FR043M3	3	7.89	7.87	0.01	0.00	0.01
FR044M6	3	6.99	7.32	-0.33	0.11	0.33
FR001M5	4	29.73	29.59	0.14	0.02	0.14
FR001M6	4	30.55	30.29	0.26	0.07	0.26
FR002M5	4	31.32	31.11	0.21	0.04	0.21
FR004M1	4	30.05	29.94	0.11	0.01	0.11
FR005M5	4	24.46	24.54	-0.08	0.01	0.08
FR006M3	4	31.71	32.03	-0.32	0.10	0.32
FR010M2	4	13.90	13.97	-0.07	0.00	0.07
FR011M2	4	11.61	11.86	-0.25	0.06	0.25
FR012M7	4	7.68	8.04	-0.36	0.13	0.36
FR013M1	4	8.74	9.08	-0.34	0.12	0.34
FR014M1	4	7.98	8.27	-0.29	0.08	0.29
FR015M2	4	16.91	17.29	-0.38	0.15	0.38
FR016M1	4	14.83	15.29	-0.46	0.21	0.46
FR017M3	4	7.70	8.09	-0.39	0.15	0.39
FR018M2	4	6.42	6.54	-0.12	0.01	0.12
FR019M10	4	15.33	15.89	-0.56	0.32	0.56
FR020M4	4	6.45	6.68	-0.23	0.06	0.23

FR021M1	4	20.25	20.63	-0.38	0.14	0.38
FR022M4	4	17.74	17.98	-0.24	0.06	0.24
FR024M6	4	4.47	4.12	0.35	0.12	0.35
FR025M8	4	6.31	6.01	0.30	0.09	0.30
FR028M1	4	17.04	17.08	-0.04	0.00	0.04
FR029M3	4	10.57	10.73	-0.17	0.03	0.17
FR030M2	4	20.92	20.87	0.05	0.00	0.05
FR030M3	4	21.14	20.97	0.17	0.03	0.17
FR032M2	4	9.64	10.05	-0.41	0.17	0.41
FR032M5	4	11.24	11.59	-0.35	0.12	0.35
FR033M4	4	13.68	13.69	-0.01	0.00	0.01
FR033M9	4	13.86	13.83	0.03	0.00	0.03
FR035M5	4	8.75	8.86	-0.11	0.01	0.11
FR035M6	4	9.48	9.83	-0.35	0.12	0.35
FR036M7	4	9.05	9.08	-0.03	0.00	0.03
FR037M6	4	8.46	8.78	-0.32	0.10	0.32
FR038M4	4	11.55	11.64	-0.10	0.01	0.10
FR039M1	4	17.20	17.55	-0.35	0.12	0.35
FR039M5	4	18.54	18.8	-0.26	0.07	0.26
FR040M6	4	19.91	20.19	-0.28	0.08	0.28
FR040M8	4	16.35	16.18	0.17	0.03	0.17
FR041M6	4	16.63	16.45	0.18	0.03	0.18
FR042M1	4	18.53	18.54	-0.01	0.00	0.01
FR042M5	4	23.14	23.4	-0.26	0.07	0.26
FR043M2	4	10.83	11.03	-0.20	0.04	0.20
FR044M5	4	8.27	8.47	-0.21	0.04	0.21
		Geo-Referencing		sum of dz ²	23.38	
	Horiz	NAD83(1992) NZ		count	164.00	
	Vert.	NAVD88 (Geoid99)		sum dz ² /count	0.14	
	Units	US Survey Feet		RMSE	0.38	
				1.96 * RMSE	0.74	
		RMSE Calculation		mean	-0.07	
		Square Root of $\sum(Z_n - Z_n)^2 / N$		median	-0.10	
		Z _n = LiDAR Dem Heights		skew	0.81	
		Z _n = Checkpoint Heights		std dev	0.37	
		N = The number of check points		95th percentile	0.61	
Ground Cover CAT	CAT Description	Survey CAT	Surv. CAT Ground Cover Equivalent		DZ MIN	DZ MAX
CAT 1	BE & Low Grass	GND 1, DRD, MGF	GND 1 = Ground - BE & Low Grass		-1.33	1.73
CAT 2	Brush & Low Trees	GND 2	GND 2 = Ground - Brush & Low Trees			
CAT 3	Forested	GND 3	GND 3 = Ground - Forested			
CAT 4	Urban	PVM 4	DRD = Ground - Dirt/Clay Road			
				PVM = Pavement (Asphalt/Concrete)		

			MGF= Well Maintained Ground Feature			
Land Cover Categories and Accuracy Criteria			Computed Accuracies			
Ground Cover CAT	RMSEz (Ft) ≤	ACCURACYz (Ft) ≤	RMSEz	95% Acc Z	95th Percentile	
CAT 1	0.30	0.60	0.27	0.53	0.50	
CAT 2	0.61	1.19	0.37	0.72	0.55	
CAT 3	0.61	1.19	0.54	1.06	1.15	
CAT 4	0.61	1.19	0.27	0.52	0.41	
COMBINED	0.61	1.19	0.38	0.74	0.61	
Calculation of Estimated and Actual Number of Check Points and Clusters for This County Area						
Total Number of Tiles This County Area	Square Miles Per 5K Tile	Total Square Miles This County Area	Number of Check Points per Sq. Mi.	Estimated Number of Check Points	Estimated Number of Point Clusters	Actual No. of Points / Clusters
747	0.897	670	4.17	161	40	164 / 44

Appendix F: LiDAR Vertical Accuracy Report

Vertical Accuracy Assessment Report 2007 LiDAR Bare-Earth Dataset for Franklin County, Florida

Date: August 19, 2008

References: A — State of Florida Division of Emergency Management (FDEM), Contract Number 07-HS-34-14-00-22-469, Task Order Number 20070525-492718a
B — Part 3: *National Standard for Spatial Data Accuracy (NSSDA)*, “Geospatial Positioning Accuracy Standards,” published by the Federal Geographic Data Committee (FGDC), 1998
C — Appendix A, *Guidance for Aerial Mapping and Surveying*, “Guidelines and Specifications for Flood Hazard Mapping Partners,” published by the Federal Emergency Management Agency (FEMA), April 2003
D — *Guidelines for Digital Elevation Data*, Version 1.0, published by the National Digital Elevation Program (NDEP), May 10, 2004
E — *ASPRS Guidelines, Vertical Accuracy Reporting for Lidar Data*, published by the American Society for Photogrammetry and Remote Sensing (ASPRS), May 24, 2004

Background

FDEM Guidance: Reference A tasked PDS to validate the bare-earth LiDAR dataset of Franklin County, FL, both quantitatively (for accuracy) and qualitatively (for usability). This report addresses the vertical accuracy assessment only, for which FDEM’s major specifications are summarized as follows:

- Vertical accuracy: ≤ 0.30 feet $RMSE_z = \leq 0.60$ feet vertical accuracy at 95% confidence level, tested in flat, non-vegetated terrain only, employing NSSDA procedures in Reference B.
- Validation that the data also satisfies FEMA requirements in Reference C.
- Vertical units (orthometric heights) are in US Survey Feet, NAVD88.

NSSDA Guidance: Section 3.2.2 of Reference B specifies: “A minimum of 20 check points shall be tested, distributed to reflect the geographic area of interest and the distribution of error in the dataset. When 20 points are tested, the 95% confidence level allows one point to fail the threshold given in product specifications.”

FEMA Guidance: Section A.8.6 of Reference C specifies the following LiDAR testing requirement for data to be used by the National Flood Insurance Program (NFIP): “For the NFIP, TINs (and DEMs derived there from) should normally have a maximum RMSE of 18.5 centimeters, equivalent to 2-foot contours, in flat terrain; and a maximum RMSE of 37 centimeters, equivalent to 4-foot contours, in rolling to hilly terrain. The Mapping Partner shall field verify the vertical accuracy of this TIN to ensure that the 18.5- or 37.0-centimeter RMSE requirement is satisfied for all major vegetation categories that predominate within the floodplain being studied ... The assigned Mapping Partner shall separately evaluate and report on the TIN accuracy for the main categories of ground cover in the study area, including the following: [followed by explanations of seven potential categories]... Ground cover Categories 1 through 5 are fairly common everywhere ... The assigned Mapping Partner shall select a minimum of 20 test points for each major vegetation category identified. Therefore, a minimum of 60 test points shall be selected for three (minimum) major land cover categories, 80 test points for four major categories, and so on.”

Note: for this project PDS followed the FDEM guidelines in Reference A, which stipulates that the vertical accuracy report will be based on a minimum of 30 ground measurements for each of four land

cover categories, totaling 120 test points for each 500 square mile area of new topographic data collection. Note the area covered in Franklin County contained approximately 544 square miles and there minimum of 40 checkpoints established in each land cover category. The land cover measurements distributed through each project area will be collected for each of the following land cover categories:

1. Bare-earth and low grass
2. Brush Lands and low trees
3. Forested areas fully covered by trees
4. Urban areas

NDEP and ASPRS Guidance: NDEP guidelines (Reference D) and ASPRS guidelines (Reference E) also recommend a minimum of 60 checkpoints, with up to 100 points preferred. (These guidelines are referenced because FEMA’s next update to Appendix A will include these newer NDEP and ASPRS guidelines, now recognizing that vertical errors for LiDAR bare-earth datasets in vegetated terrain do not necessarily follow a normal error distribution as assumed by the NSSDA.)

Vertical Accuracy Test Procedures

Ground Truth Surveys: The PDS team established a primary geodetic network covering approximately 6,000 square miles along the panhandle area of Northwest Florida to provide accurate and consistent control throughout the project area, which includes Franklin County. The Primary Network was used to establish base stations to support airborne GPS data acquisition. Two Secondary control networks were established to support the measurement of checkpoints used in the accuracy validation process for newly generated LiDAR and Orthophotography.

Assessment Procedures and Results: The LiDAR accuracy assessment for Franklin County was performed in accordance with References D and E which assume that LiDAR errors in some land cover categories may not follow a normal error distribution. This assessment was also performed in accordance with References B and C which assume that LiDAR bare-earth datasets errors do follow a normal error distribution. Comparisons between the two methods help determine the degree to which *systematic errors* may exist in Franklin County’s four major land cover categories: (1) bare-earth and low grass, (2) brush lands and low trees, (3) forested areas fully covered by trees, (4) urban areas. When a LiDAR bare-earth dataset passes testing by both methods, compared with criteria specified in Reference A, the dataset clearly passes all vertical accuracy testing criteria for a digital terrain model (DTM) suitable for FDEM and FEMA requirements.

The relevant testing criteria, as stipulated in Reference A are summarized in Table 1.

Table 1 — DTM Acceptance Criteria for Franklin County

Quantitative Criteria	Measure of Acceptability
Fundamental Vertical Accuracy (FVA) in open terrain only = 95% confidence level	0.60 ft (0.30 ft RMSE _z x 1.96000) for open terrain only
Supplemental Vertical Accuracy (SVA) in individual land cover categories = 95% confidence level	1.19 ft (based on 95 th percentile per land cover category)
Consolidated Vertical Accuracy (CVA) in all land cover categories combined = 95% confidence lever	1.19 ft (based on combined 95 th percentile)

Vertical Accuracy Testing in Accordance with NDEP and ASPRS Procedures

References D and E specify the mandatory determination of Fundamental Vertical Accuracy (FVA) and the optional determination of Supplemental Vertical Accuracy (SVA) and Consolidated Vertical Accuracy (CVA). FVA determines how well the LiDAR sensor performed in category (1), open terrain, where errors are random and normally distributed; whereas SVA determines how well the vegetation classification algorithms worked in land cover categories (2) and (3) where LiDAR elevations are often higher than surveyed elevations and category (4) where LiDAR elevations are often lower.

FVA is determined with check points located only in land cover category (1), open terrain (grass, dirt, sand, and/or rocks), where there is a very high probability that the LiDAR sensor will have detected the bare-earth ground surface and where random errors are expected to follow a normal error distribution. The FVA determines how well the calibrated LiDAR sensor performed. With a normal error distribution, the vertical accuracy at the 95% confidence level is computed as the vertical root mean square error ($RMSE_z$) of the checkpoints x 1.9600, as specified in Reference B. For Franklin County, for which floodplains are essentially flat, FDEM required the FVA to be 0.60 ft (18.29 cm) at the 95% confidence level (based on an $RMSE_z$ of 0.30 ft (9.14 cm), equivalent to 1 ft contours).

CVA is determined with all checkpoints in all land cover categories combined where there is a possibility that the LiDAR sensor and post-processing may yield elevation errors that do not follow a normal error distribution. CVA at the 95% confidence level equals the 95th percentile error for all checkpoints in all land cover categories combined. FDEM's CVA standard is 1.19 ft at the 95% confidence level. The CVA is accompanied by a listing of the 5% outliers that are larger than the 95th percentile used to compute the CVA; these are always the largest outliers that may depart from a normal error distribution. Here, $Accuracy_z$ differs from CVA because $Accuracy_z$ assumes elevation errors follow a normal error distribution where RMSE procedures are valid, whereas CVA assumes LiDAR errors may not follow a normal error distribution in vegetated categories, making the RMSE process invalid.

SVA is determined separately for each individual land cover category, again recognizing that the LiDAR sensor and post-processing may yield elevation errors that do not follow a normal error distribution, and where discrepancies can be used to identify the nature of systematic errors by land cover category. For each land cover category, the SVA at the 95% confidence level equals the 95th percentile error for all checkpoints in each individual land cover category. SVA statistics are calculated individually for bare-earth and low grass, brush lands and low trees, forested areas, and urban areas, in order to facilitate the analysis of the data based on each of these land cover categories that exist within Franklin County. The SVA criteria in Table 1 (1.19 ft at the 95% confidence level for each category) are target values only and are not mandatory; it is common for some SVA criteria to fail individual target values, yet satisfy FEMA's mandatory CVA criterion.

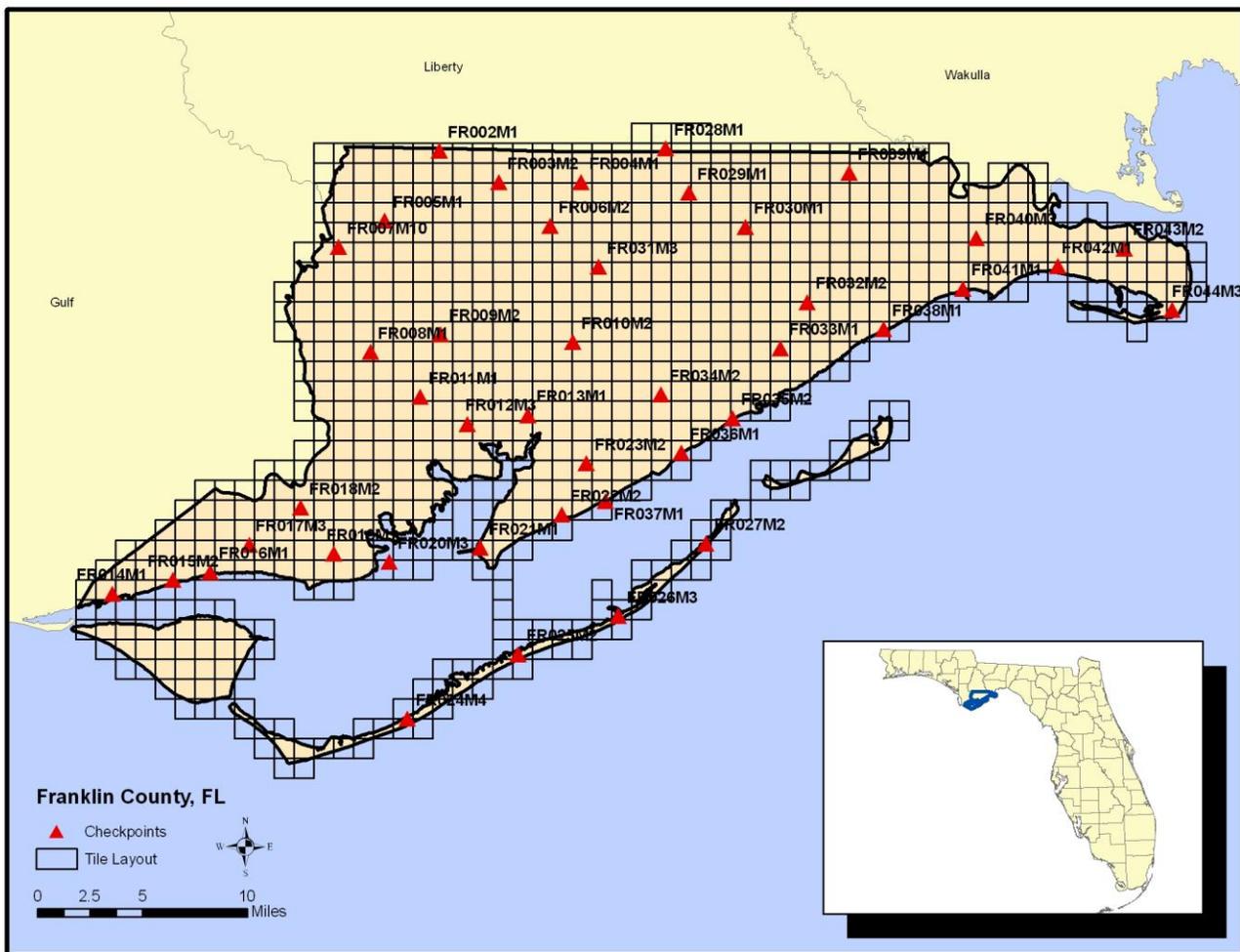
QA/QC Steps: The primary QA/QC steps used by PDS were as follows:

1. PDS surveyed "ground truth" QA/QC vertical checkpoints in accordance with guidance in references B, C, D and E. Figure 1 shows the location of "cluster areas" where PDS attempted to survey a minimum of 40 QA/QC checkpoints in each of the four land cover categories. Some clusters may not include points from all cover categories. The final totals were 40 checkpoints in bare-earth and low grass; 40 checkpoints in brush and low trees; 41 checkpoints in forested areas; and 43 checkpoints in urban areas, for a total of 164 checkpoints.
2. Next, PDS interpolated the bare-earth LiDAR DTM to provide the z-value for each of the 164 checkpoints.
3. PDS then computed the associated z-value differences between the interpolated z-value from the LiDAR data and the ground truth survey checkpoints and computed the FVA, CVA and SVA values using procedures in References D and E.

- The data were analyzed by PDS to assess the accuracy of the data. The review process examined the various accuracy parameters as defined by FDEM guidelines. Also, the overall descriptive statistics of each dataset were computed to assess any trends or anomalies. The following tables, graphs and figures illustrate the data quality.

Figure 1 shows the location of the QA/QC checkpoint clusters within Franklin County. Each point represents a checkpoint cluster. There are nominally four checkpoints in each cluster, one per land cover category.

Figure 1 — Location of QA/QC Checkpoint Clusters for Franklin County



Note the initial vertical accuracy assessment of Franklin County clearly indicated a negative error bias averaging \sim .35 ft. This information was passed on to the LiDAR vendor with the recommendation that they apply a positive “z-bump” to all of the points contained in the .LAS files for this county. The z-bump was accurately applied and it is those corrected .LAS files that were used in this final vertical accuracy assessment.

Table 2 summarizes the vertical accuracy by fundamental, consolidated and supplemental methods:

Table 2 — FVA, CVA and SVA Vertical Accuracy at 95% Confidence Level

Land Cover Category	# of Points	FVA — Fundamental Vertical Accuracy (RMSE _z x 1.9600) Spec = 0.60 ft	CVA — Consolidated Vertical Accuracy (95 th Percentile) Spec = 1.19 ft	SVA — Supplemental Vertical Accuracy (95 th Percentile) Target = 1.19 ft
Total Combined	164		0.61	
BE & Low Grass	40	0.53		0.50
Brush & Low Trees	40			0.55
Forested	41			1.15
Urban	43			0.41

Fundamental and Consolidated Vertical Accuracy at 95% confidence level, using NDEP/ASPRS methodology:

The RMSE_z in bare-earth and low grass was within the target criteria of 0.30 ft, and the FVA tested 0.53 ft at the 95% confidence level in open terrain, based on RMSE_z x 1.9600.

Compared with the 1.19 ft specification, CVA tested 0.61ft at the 95% confidence level in bare-earth and low grass, brush and low trees, forested, and urban areas combined, based on the 95th Percentile. Table 3 lists the 5% outliers larger than the 95th percentile error; whereas 5% of the points (8 points) could have exceeded the 1.19 ft criterion; 3 points actually did exceed this criterion and are listed in the table below.

Table 3 — 5% Outliers Larger than 95th Percentile

Point No.	Land Cover Classification	Delta-Z (ft)	Comments
FR006M2	Brush and low trees	-1.33	3 points had errors larger than the CVA standard of 1.19 ft., which permits up to 5% of the checkpoints, 8 of 164 points, to exceed 1.19 ft
FR015M7	Forested	1.23	
Fro016M7	Forested	1.73	

Compared with the 1.19 ft SVA target values, SVA tested 0.50 ft at the 95% confidence level in bare-earth and low grass; 0.55 ft in brush and low trees; 1.15 ft in forested areas; and 0.41 ft in urban areas, based on the 95th Percentile. Each of the four land cover categories were within the target value of 1.19 ft.

Figure 2 illustrates the SVA by specific land cover category.

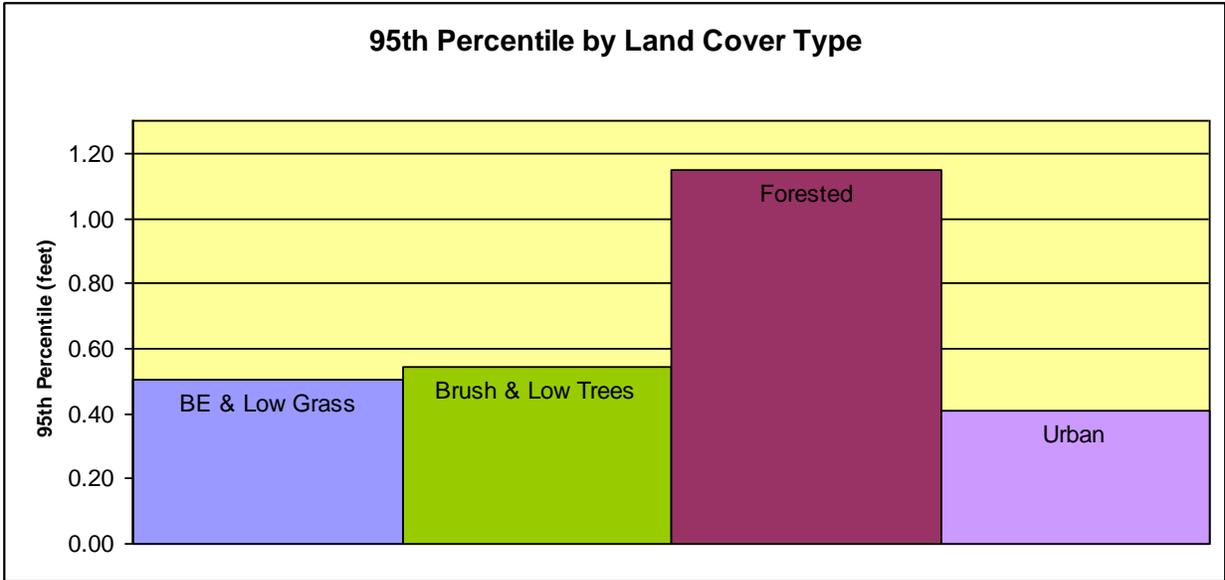


Figure 2 — Graph of SVA Values by Land Cover

Figure 3 illustrates the magnitude of the differences between the QA/QC checkpoints and LiDAR data by specific land cover category and sorted from lowest to highest. This shows a negative skew to the distribution of points in bare-earth and low grass; however, that deltas are well within specification.

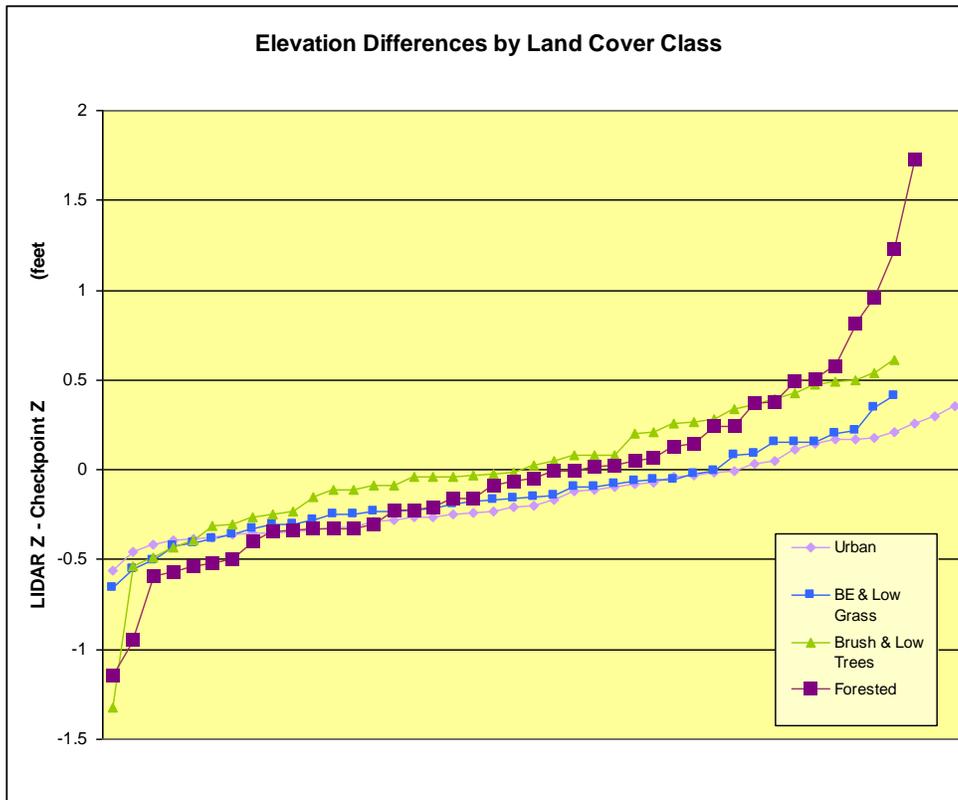


Figure 3 – Magnitude of Elevation Discrepancies, Sorted from Largest Negative to Largest Positive

The NSSDA and FEMA guidelines were both published before it was recognized that LiDAR errors do not always follow a normal error distribution. Future changes to these FGDC and FEMA documents are expected to follow the lead of the NDEP and ASPRS. Nevertheless, to comply with FEMA’s current guidelines in Reference C, $RMSE_z$ statistics were computed in all four land cover categories, individually and combined, as well as other statistics that FEMA recommends to help identify any unusual characteristics in the LiDAR data. These statistics are summarized in Figures 4 and 5 and Table 4 below, consistent with Section A.8.6.3 of Reference C.

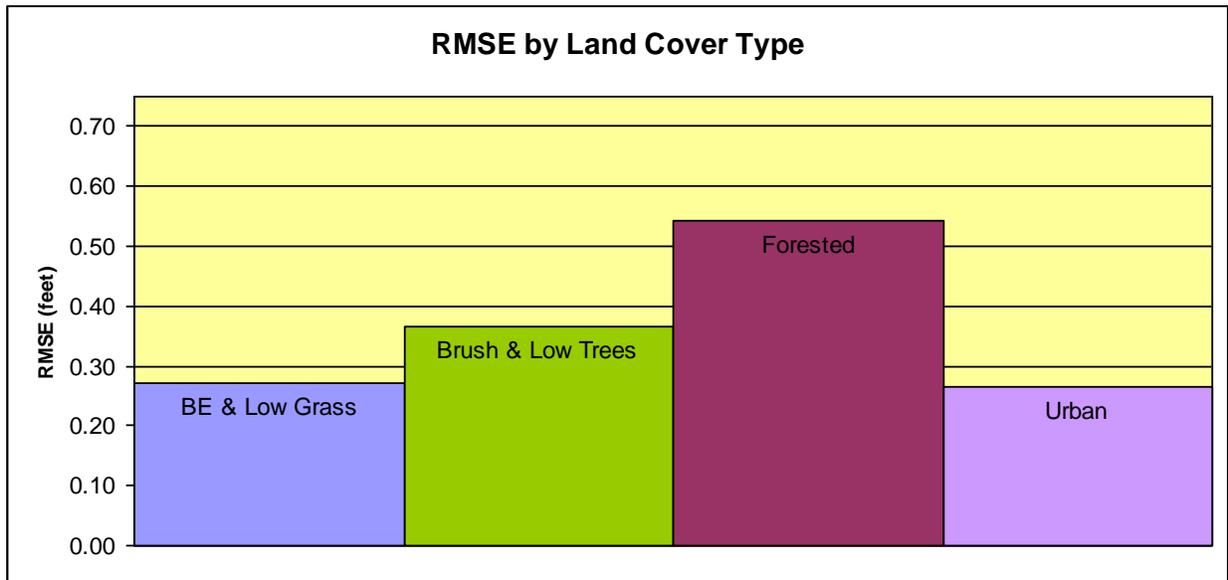


Figure 4 — $RMSE_z$ statistics by Land Cover Category

Table 4 — Overall Descriptive Statistics by Land Cover Category and Consolidated

Descriptive Statistics							
Land Cover Category	Points	RMSE (feet)	Mean Error (feet)	Median Error (feet)	SKEW	STDEV (feet)	95th Percentile (feet)
Consolidated	164	0.38	-0.07	-0.10	0.81	0.37	0.61
BE & Low Grass	40	0.27	-0.14	-0.16	0.24	0.24	0.50
Brush & Low Trees	40	0.37	0.01	-0.02	-1.06	0.37	0.55
Forested	41	0.54	-0.01	-0.06	0.94	0.55	1.15
Urban	43	0.27	-0.14	-0.20	0.42	0.23	0.41

Fundamental and Consolidated Vertical Accuracy at 95% confidence level, using NSSDA/FEMA methodology:

Although the NSSDA and FEMA guidelines predated FVA and CVA terminology, vertical accuracy at the 95% confidence level (called Accuracy_z) is computed by the formula $RMSE_z \times 1.9600$. Accuracy_z in open terrain = 0.27 ft x 1.9600 = 0.53 ft, satisfying the 0.60 ft FVA standard. Accuracy_z in consolidated categories = 0.38 ft x 1.9600 = 0.74 ft, satisfying the 1.19 ft CVA standard.

Figure 5 illustrates a histogram of the associated elevation discrepancies between the QA/QC checkpoints and elevations interpolated from the LiDAR triangulated irregular network (TIN). The frequency shows the number of discrepancies within each band of elevation differences. Although the discrepancies vary between a low of -1.33 ft and a high of +1.73 ft, the histogram shows that the majority of the discrepancies are skewed on the positive side of what would be a “bell curve,” with mean of zero, if the data were truly normally distributed. Typically the discrepancies tend to skew a bit more to the positive side, because discrepancies in vegetation are typically positive. The vast majority of points are within +/- 0.5 ft range.

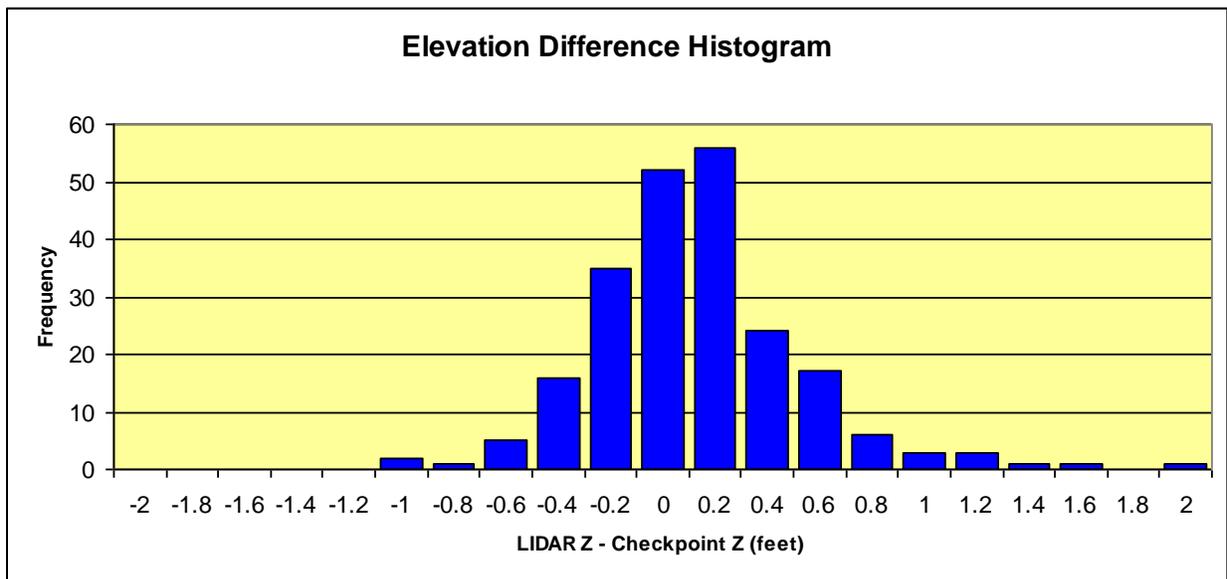


Figure 5 — Histogram of Elevation Discrepancies within 0.10 m Bands

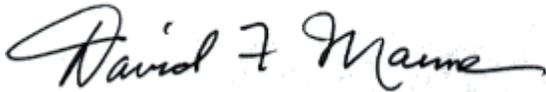
Checkpoints That Were Not Used

None of the 164 checkpoints were re-classified or omitted from the vertical accuracy analysis for this county.

Conclusions

Based on the vertical accuracy testing conducted by PDS, the undersigned certifies that the LiDAR dataset for Franklin County, Florida satisfies the criteria established by Reference A:

- Based on NSSDA, FEMA, NDEP and ASPRS methodology: Tested 0.53' vertical accuracy at 95% confidence level in open terrain.
- Based on NSSDA, FEMA, NDEP and ASPRS methodology: Tested 0.61' vertical accuracy at 95% confidence level in all land cover categories combined.



David F. Maune, Ph.D., PSM, PS, GS, CP
QA/QC Manager

Appendix G: LiDAR Qualitative Assessment Report

References:

- A — State of Florida Division of Emergency Management (FDEM), Contract Number 07-HS-34-14-00-22-469, Task Order Number 20070525-492718a
- B — Part 3: *National Standard for Spatial Data Accuracy (NSSDA)*, “Geospatial Positioning Accuracy Standards,” published by the Federal Geographic Data Committee (FGDC), 1998
- C — Appendix A, *Guidance for Aerial Mapping and Surveying*, “Guidelines and Specifications for Flood Hazard Mapping Partners,” published by the Federal Emergency Management Agency (FEMA), April 2003
- D — *Guidelines for Digital Elevation Data*, Version 1.0, published by the National Digital Elevation Program (NDEP), May 10, 2004
- E — *ASPRS Guidelines, Vertical Accuracy Reporting for LiDAR Data*, published by the American Society for Photogrammetry and Remote Sensing (ASPRS), May 24, 2004

Qualitative Assessment

The PDS qualitative assessment of Franklin County’s LiDAR data utilizes a combination of statistical analysis and interpretative methodology to assess the quality of the data for a bare-earth digital terrain model (DTM). This process looks for anomalies in the data and also identifies areas where man-made structures or vegetation points may not have been classified properly to produce a bare-earth model. Overall the data are of good quality and should satisfy most users for an accurate bare-earth elevation data product.

Overview

Within this review of the LiDAR data, two fundamental questions were addressed:

- Did the LiDAR system perform to specifications?
- Did the vegetation removal process yield desirable results for the intended bare-earth terrain product?

Mapping standards today address the quality of data by quantitative methods. If the data are tested and found to be within the desired accuracy standard, then the data set is typically accepted. Now with the proliferation of LiDAR, new issues arise due to the vast amount of data. Unlike photogrammetrically-derived DEMs where point spacing can be eight meters or more, LiDAR point spacing for this project is two meters or less. The end result is that millions of elevation points are measured to a level of accuracy previously unseen for traditional, elevation mapping technologies, and vegetated areas are measured that would be nearly impossible to survey by other means. The downside is that with millions of points, the data set is statistically bound to have some errors both in the measurement process and in the artifact removal process.

As previously stated, the quantitative analysis addresses the quality of the data based on absolute accuracy. This accuracy is directly tied to the comparison of the discreet measurement of the survey checkpoints and that of the interpolated value within the three closest LiDAR points that constitute the vertices of a three-dimensional triangular face of the TIN. Therefore, the end result is that only a small sample of the LiDAR data is actually tested. However there is an increased level of confidence with

LiDAR data due to the relative accuracy. This relative accuracy in turn is based on how well one LiDAR point "fits" in comparison to the next contiguous LiDAR measurement. Once the absolute and relative accuracy has been ascertained, the next stage is to address the cleanliness of the data for a bare-earth DTM.

By using survey checkpoints to compare the data, the absolute accuracy is verified, but this also allows us to understand if the artifact removal process was performed correctly. To reiterate the quantitative approach, if the LiDAR sensor operated correctly over open terrain areas, then it most likely operated correctly over the vegetated areas. This does not mean that the bare-earth was measured, but that the elevations surveyed are most likely accurate (including elevations of treetops, rooftops, etc.). In the event that the LiDAR pulse filtered through the vegetation and was able to measure the true surface (as well as measurements on the surrounding vegetation) then the level of accuracy of the vegetation removal process can be tested as a by-product.

To fully address the data for overall accuracy and quality, the level of cleanliness (or removal of above-ground artifacts) is paramount. Since there are currently no effective automated testing procedures to measure cleanliness, PDS employs a combination of statistical and visualization processes. This includes creating pseudo image products such as LiDAR orthos produced from the intensity returns, Triangular Irregular Network (TIN)'s, Digital Elevation Models (DEM) and 3-dimensional models. By creating multiple images and using overlay techniques, not only can potential errors be found, but the PDS team can also find where the data meets and exceeds expectations. This report will present representative examples where the LiDAR and post processing had issues as well as examples of where the LiDAR performed well.

Process

PDS utilizes GeoCue software products as the primary geospatial process management system. GeoCue is a three tier, multi-user architecture that uses .NET technology from Microsoft. .NET technology provides the real-time notification system that updates users with real-time project status, regardless of who makes changes to project entities. GeoCue uses database technology for sorting project metadata. PDS uses Microsoft SQL Server as the database of choice.

The PDS qualitative assessment process flow for Franklin County, FL incorporated the following reviews:

1. *Statistical Analysis*- A statistical analysis routine was run on the .LAS files upon receipt to verify that the .LAS files met project specifications. This routine checked for the presence of Variable Length Records, verified .LAS classifications, verified header records for min/max x,y,z, and parsed the .LAS point file to confirm that the min/max x,y,z matched the header records. These statistics were run on the all-return point data set as well as the bare-earth point data set for every deliverable tile.
 - a. All LAS files contained Variable Length Records with georeferencing information.
 - b. All LiDAR points in the LAS files were classified in accordance with project specifications: Class 1 - Unclassified, Class 2 - Ground, Class 7 - Noise, Class 9 – Water, and Class 12 – Overlap Points.
 - c. Min/max x,y,z values matched the header files.
2. *Spatial Reference Checks*- The .LAS files were imported into the GeoCue processing environment. As part of the URS process workflow the GeoCue import produced a minimum bounding polygon for each data file. This minimum bounding polygon was one of the tools used in conjunction with the statistical analysis to verify spatial reference integrity. No issues were identified with the spatial referencing of this dataset.
3. *Data Void/ Gap Checks*-The imported .LAS files were used to create LiDAR “Orthos”. The LiDAR “Orthos” were one of the tools used to verify data coverage. The standard QA process flow used Data Point Elevation and LiDAR pulse return intensity returns. The intensity returns were used as delivered with no normalization. The Franklin County LiDAR dataset was an existing collection. Due to the point density of the initial acquisition, the final product was a 4 ft pixel produced from the All Return Data Set. The maximum density area allowed to generate the pixel was 254 ft. This product was produced to review the LiDAR collection to verify data density and to review for any Data Gaps/Data Voids. It was also used as a reference image during the artifact checks. It is not intended as a final product. (Figures 1-3)

Figure 5 Lidar Ortho Sample from Franklin County. Areas in Blue are acceptable Data Voids caused by Ponds, Streams or Water Bodies.

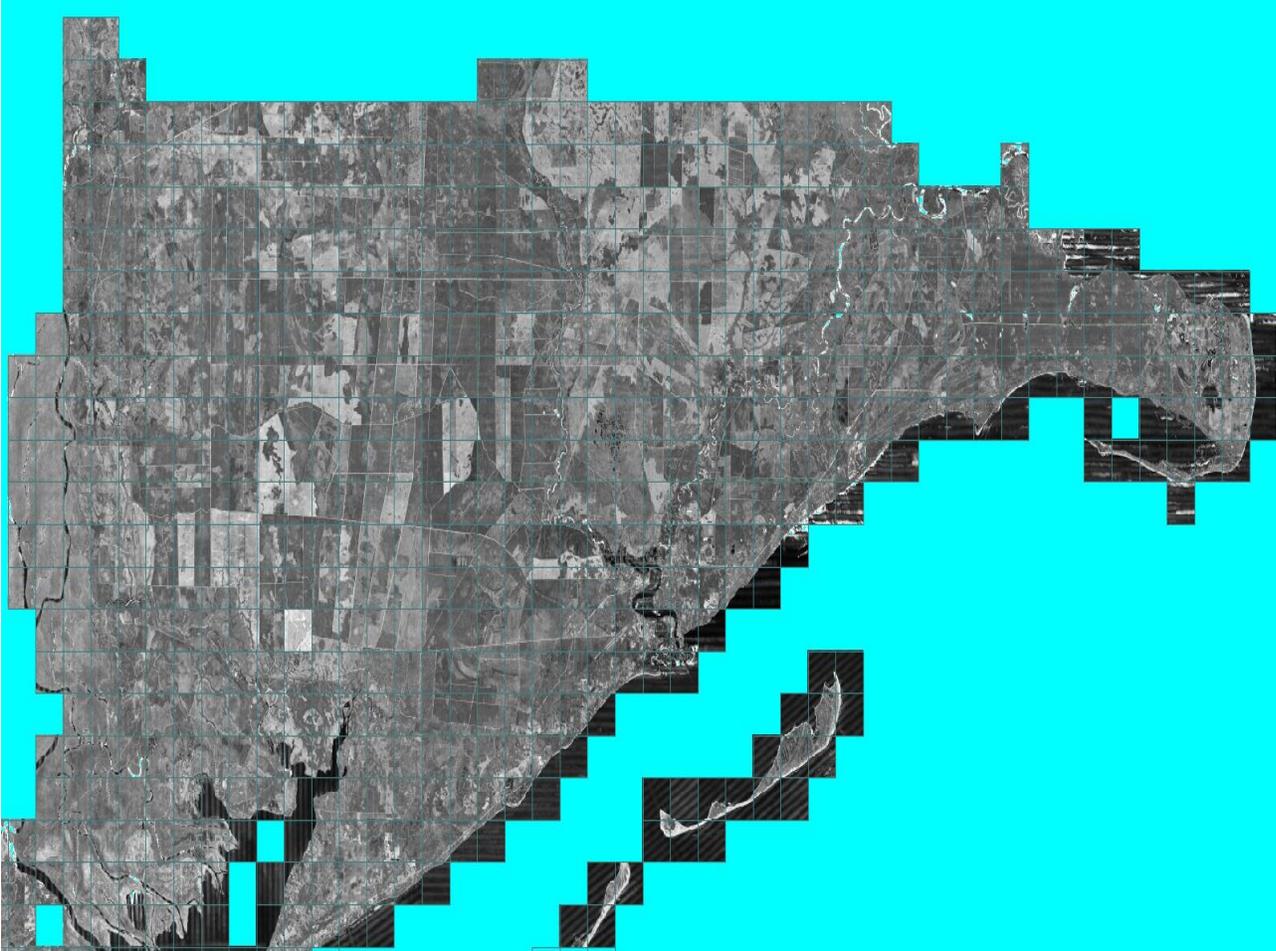


Figure 6 Tiles LID_070953 Zoom showing water bodies with acceptable data voids



4. *Initial Data Verification:* PDS performs an initial 10% random check of the data delivery by looking at each tile individually in great detail utilizing TIN surfaces and profiles. If the data set passes the 10 % the tiles continue through the process work flow where every tile is reviewed. If the data set fails the 10% check it is normally due to a systematic process error and the data set is rejected.
5. *Data Density/Elevation checks:* The .LAS files are used to produce a Digital Elevation Model. These DEMs are produced using the software package QT Modeler which produces a 3dimensional data model. This data model is created from the Class 2 ground points using the project density deliverable requirement for unobscured areas.

The QC for Franklin County was done at the most stringent data density requirement. For the FDEM project this requirement was that LiDAR point cloud data meet a maximum post spacing of 4 ft in un- obscured areas for random point data. Model statistics were produced and characterized by density as well as elevation. This data model was created from class 2 ground points and model statistics were characterized by density, scale, intensity as well as elevation. (Figure 2) The low confidence area polygons were referenced with the density grids to ensure that all low confidence areas are properly identified with a low confidence area polygon. Again, these products were produced for Quality Assessment purposes only.

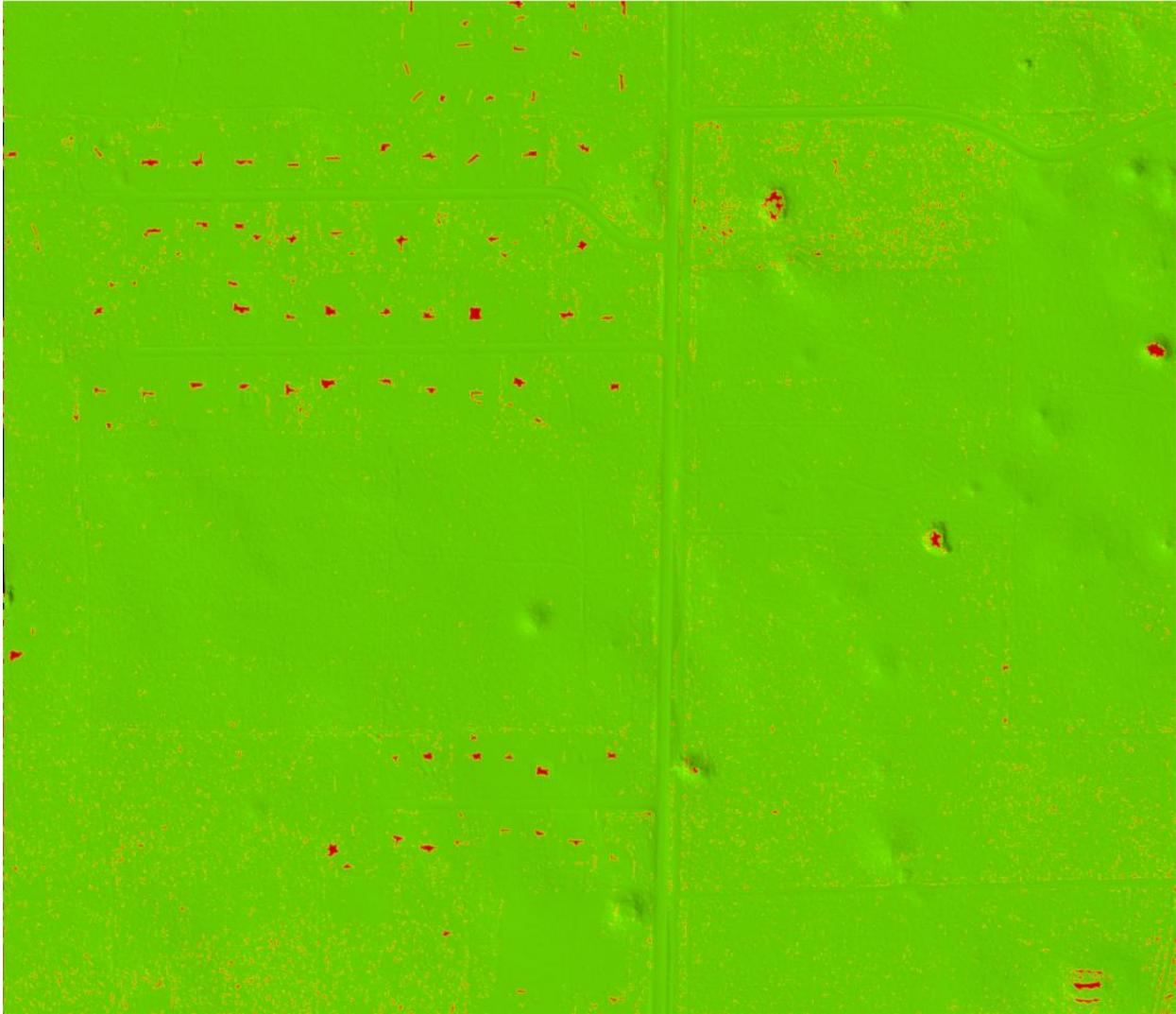


Figure 7 Sample density grid (Tile LID053696)

Zoom of area with dense vegetation. Density grids were created at a 4 foot cell size using a green to red color ramp. Green areas indicate that the grid meets the 4 foot specification. Yellow to Red indicates that the 4 foot specification is not met.

6. *Artifact Anomaly Checks.* The final step was to review every tile for anomalies that may exist in the bare-earth terrain surface. Items that were checked include, but are not limited to: buildings, bridges, vegetation and water points classified as Class 2 points and elevation “steps” that may occur in the overlap between adjacent flight lines. Any issues found are addressed in the below “General comments and issues”.

General comments and issues.

Franklin County, Florida is characterized by heavy vegetation, marshes and swamp areas. There are few developed and urban areas. The majority of the county is state forests and state parks (Figure 4)

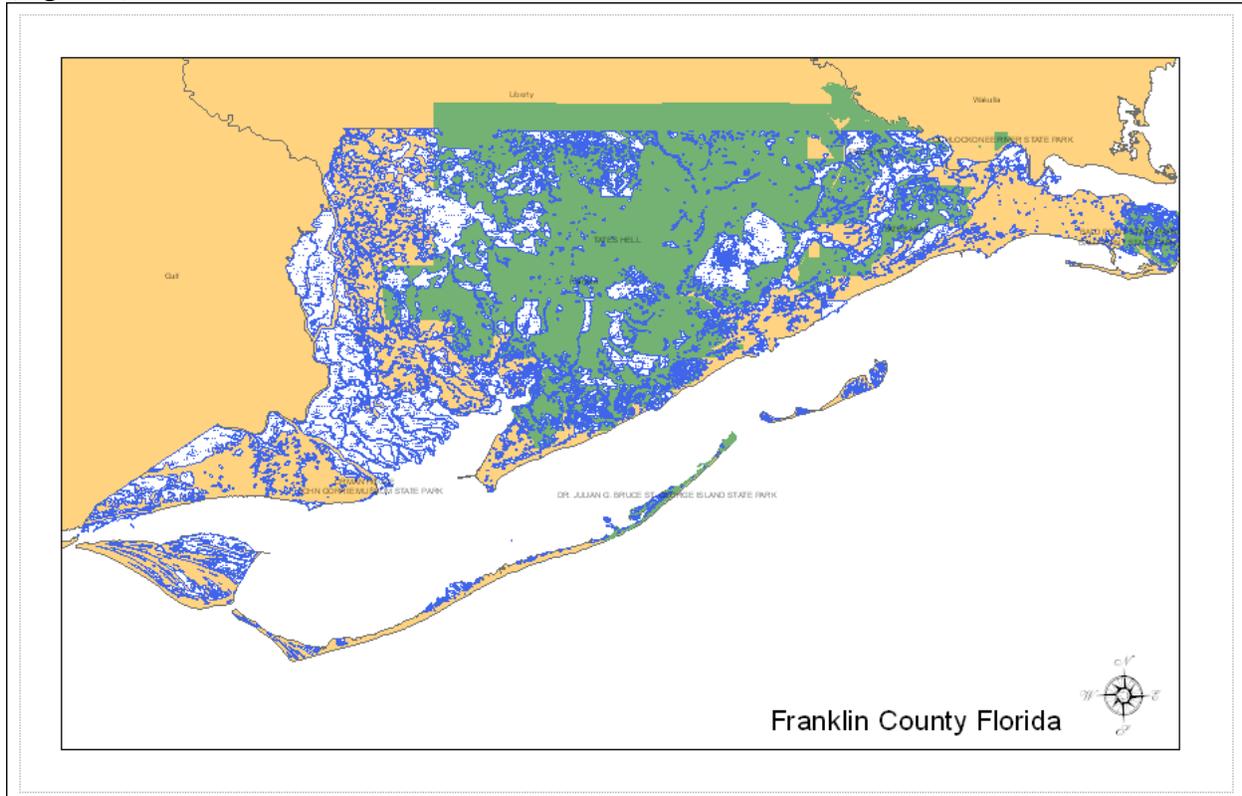


Figure 8 Map of Franklin County Florida with Marsh areas from Florida Geographic Data Library (FGDL)

The concern with this LiDAR collection for the final product is that the LiDAR would penetrate through the vegetation to produce the contract specifications for open terrain. Because of the heavy vegetation, defined low confidence areas are critical due to the deliverable requirement for topography (Contours).

The initial data acquisition was very dense. Overall the acquired point density was around 1 foot. In general, the ground data set was clean in what is defined as low confidence areas or areas of significant heavy vegetation. (See Figure 5 and 6) The algorithms used to classify and filter to ground points were very stringent. Given the overall physical characteristics of the county this does not seem inappropriate. There is a fine line in the decision-making process of which points to classify as ground. By removing points from the ground classification due to heavy vegetation there is risk of over-smoothing or “flattening” the ground surface which can have a greater impact than leaving points to maintain the ground surface model. (Figure 5 and 6) In addition, due to the lack of significant elevation changes in the physical terrain there are places where there is no visible break in the terrain between the ground surface and what in traditional mapping would be considered a hard breakline feature, for example roads. Because the project includes the collection of breaklines, this will be compensated for in the road breakline collection. The LiDAR data contained sporadic issues such as artifacts or small anomalies which

is typical of any LiDAR dataset. The low confidence area polygons and breakline acquisition is an important deliverable for this particular county.

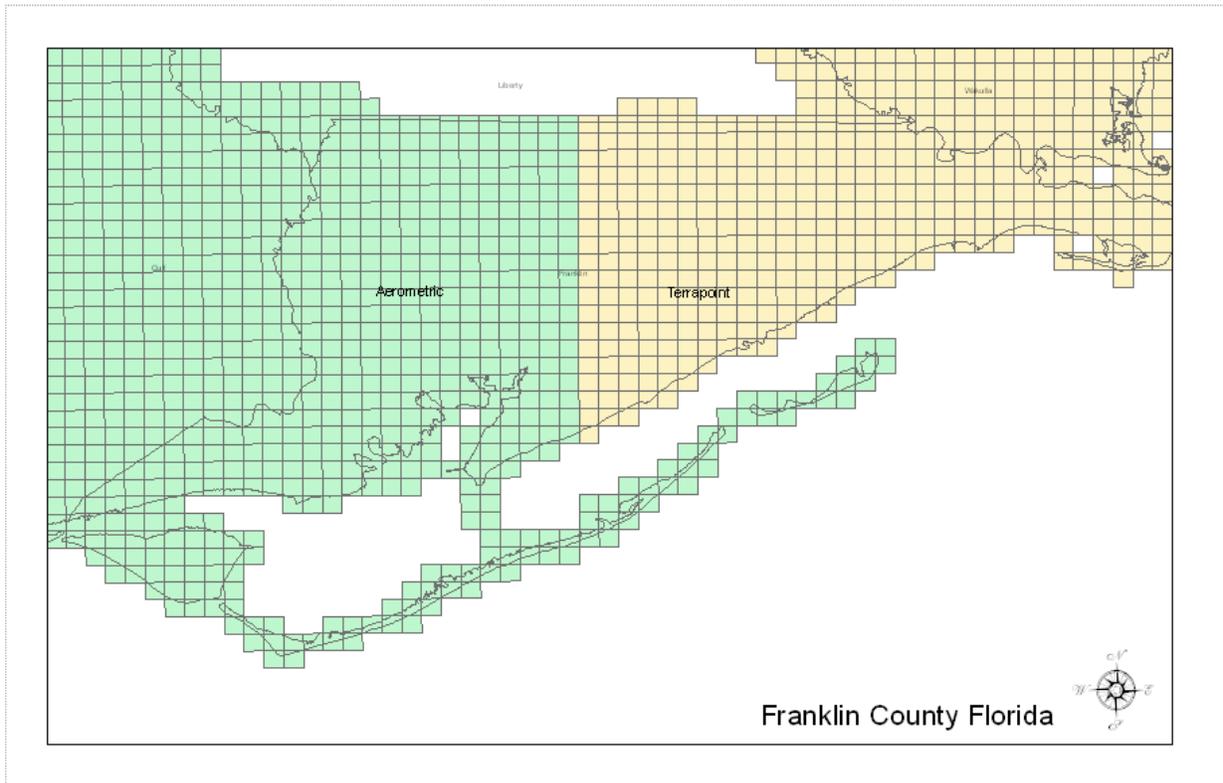


Figure 5 Tile Franklin County layout by Contractor. The County was flown by two different Contractors, the data was QC'd together.

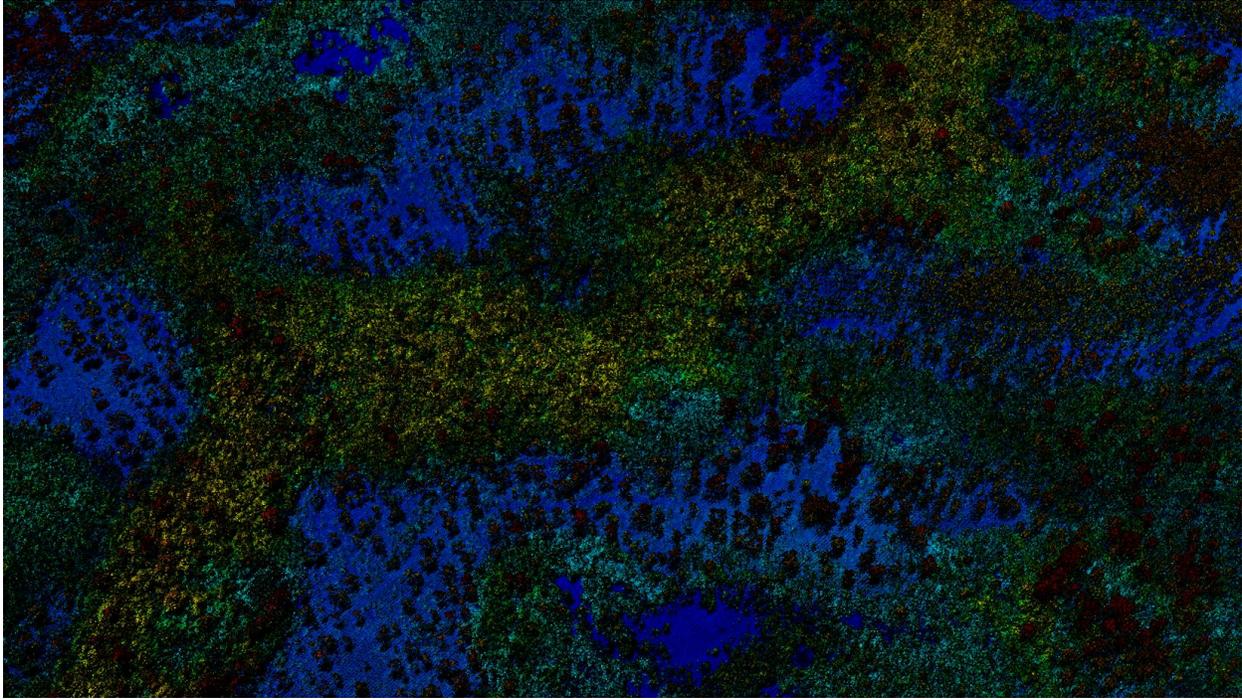


Figure 6 Tile 054216 - example of heavy vegetation in Franklin County Florida

Points		
Tile	Issue	Code
066093	Dense vegetation	Pass
072026	Standing water	Pass

Review Examples:

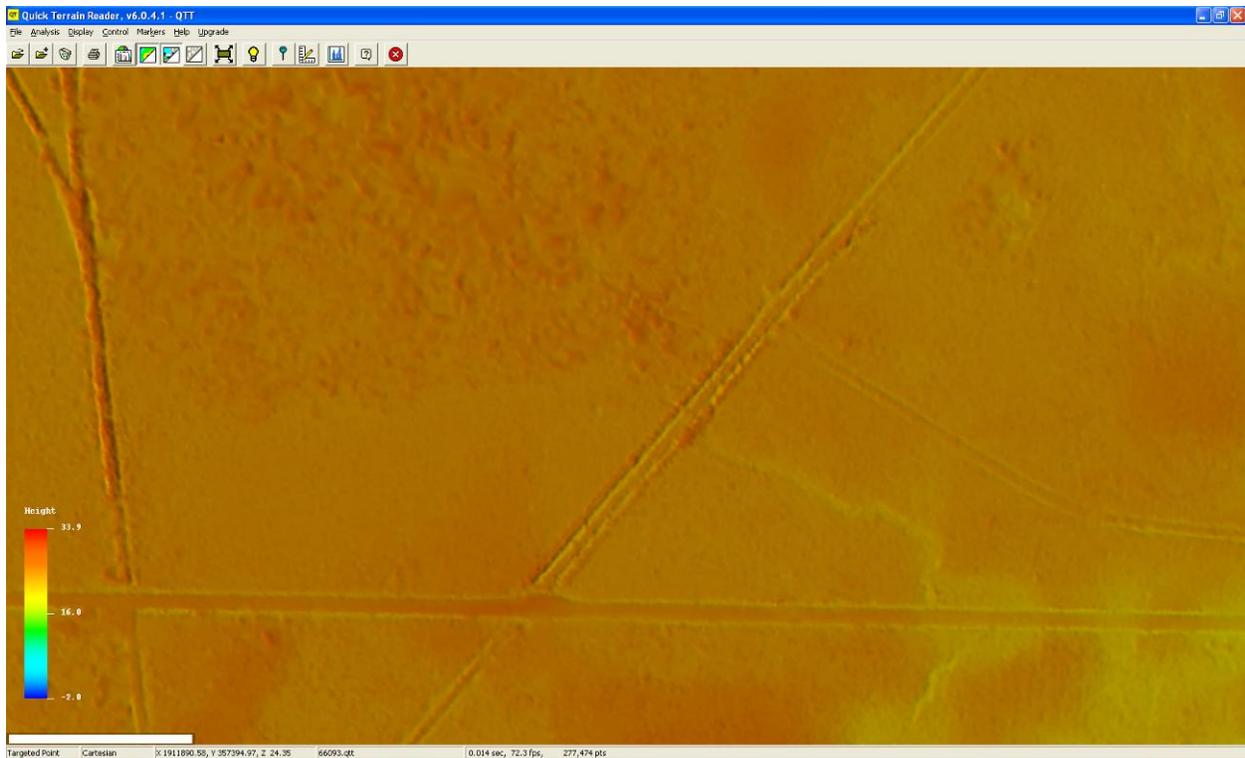


Figure 9 Tile 066093 - dense vegetation at road edge. Breaklines are necessary to define road edges for contour generation.

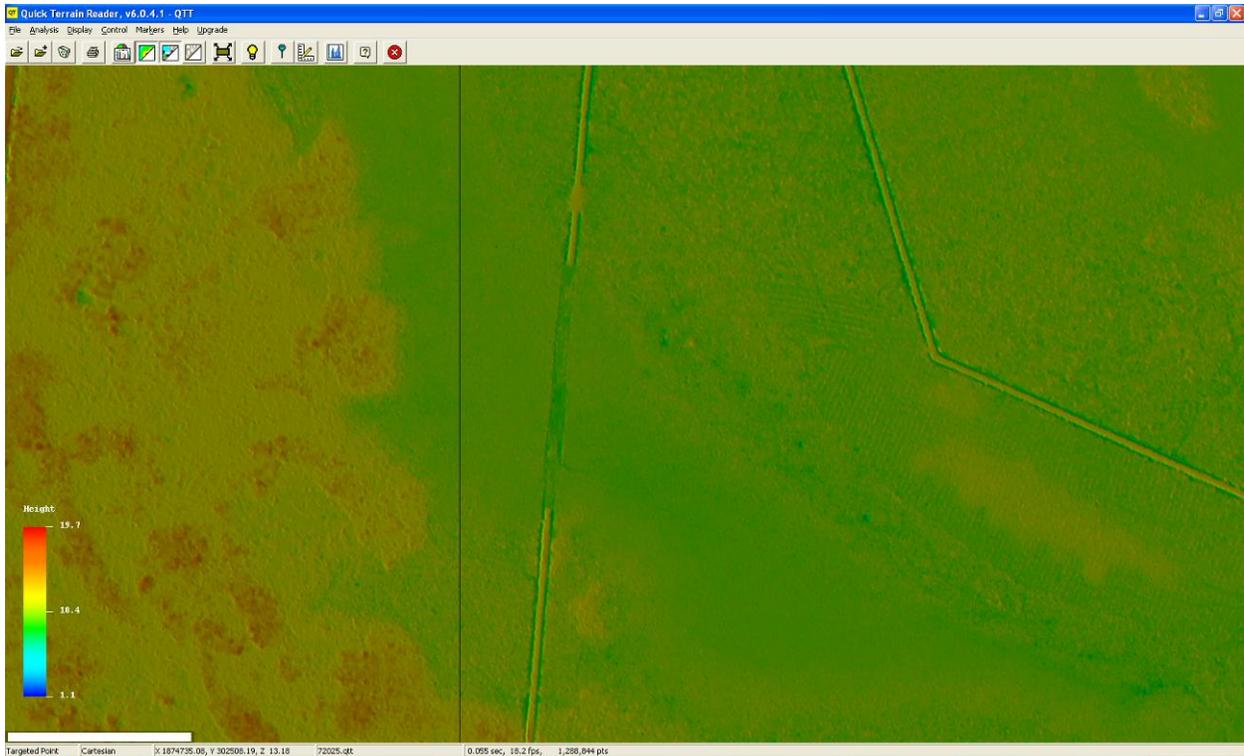
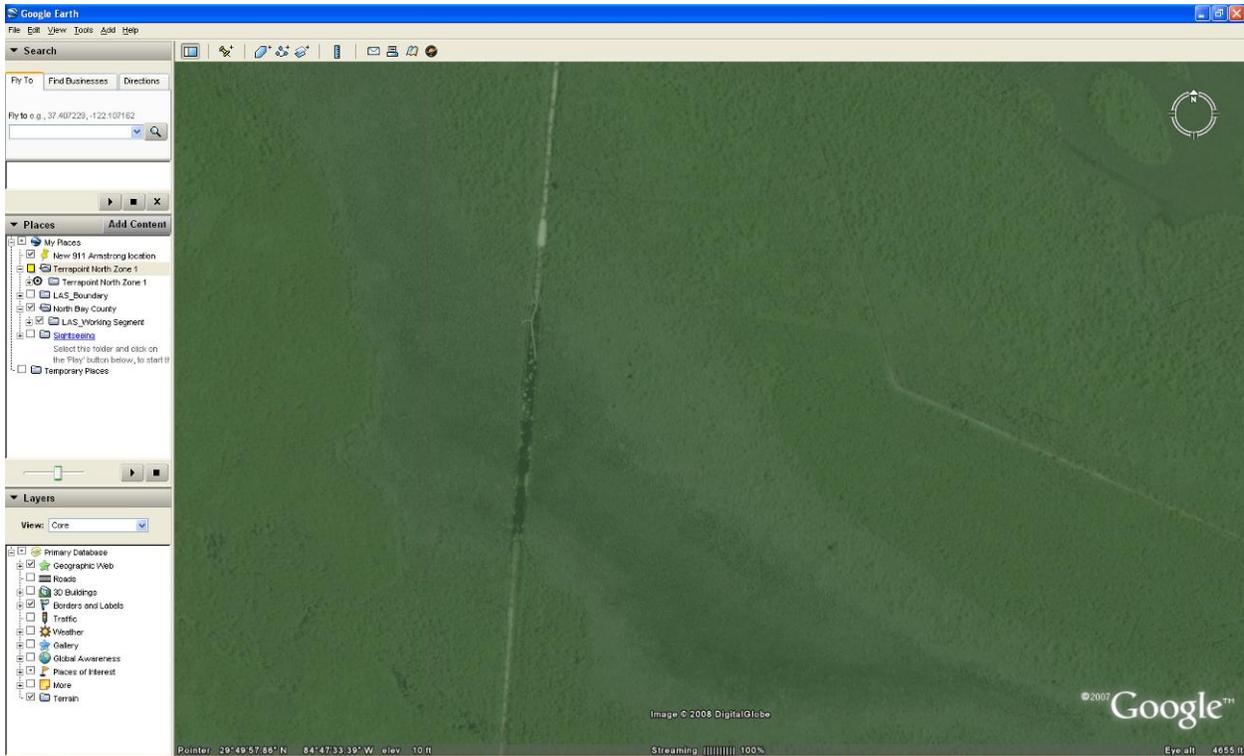


Figure 8 & 9 Tile 0072026 – There were some areas with standing water that affected some terrain features. Here is an example of water standing in the road.



Conclusion

Overall the data meets the project specifications. The processing performed well given the low relief and highly vegetated areas. The dense data collection specification helped with vegetation penetration. There are some minor issues but they are not a detriment to a usable data product.

Appendix H: Breakline/Contour Qualitative Assessment Report

Coastal Shorelines

Coastal shorelines are correctly captured as two-dimensional polygon features, extracted from the LiDAR data and not from digital orthophotos, except for manmade features with varying heights such as seawalls which are captured as three-dimensional breaklines. Coastal breaklines merge seamlessly with linear hydrographic features. Shorelines continue beneath docks and piers. There is no “stair-stepping” of coastal shorelines. Figure 1 shows example coastal breaklines and contours.



Contours

- DEPRESSION
- + DEPRESSION LOW CONFIDENCE
- INDEX
- + INDEX LOW CONFIDENCE
- INTERMEDIATE
- + INTERMEDIATE LOW CONFIDENCE
- SUPPLEMENTARY
- + SUPPLEMENTARY LOW CONFIDENCE

Breaklines

- Dual Line Feature
- Single Line Feature
- Soft Hydro Dual Line Feature
- Soft Hydro Single Line Feature
- OVERPASS
- ROADBREAKLINE
- SOFTFEATURE
- ISLAND
- WATERBODY
- COASTALSHORELINE
- LOWCONFIDENCE

Figure 1. Example coastal breaklines and contours from tile #75261

Linear Hydrographic Features

Linear hydrographic features are correctly captured as three-dimensional breaklines – single line features if the average width is 8 feet or less and dual line features if the average width is greater than 8 feet. Each vertex maintains vertical integrity. Figure 2 shows example breaklines and contours of linear hydrographic features.



Contours

- DEPRESSION
- +— DEPRESSION LOW CONFIDENCE
- INDEX
- +— INDEX LOW CONFIDENCE
- INTERMEDIATE
- +— INTERMEDIATE LOW CONFIDENCE
- SUPPLEMENTARY
- +— SUPPLEMENTARY LOW CONFIDENCE

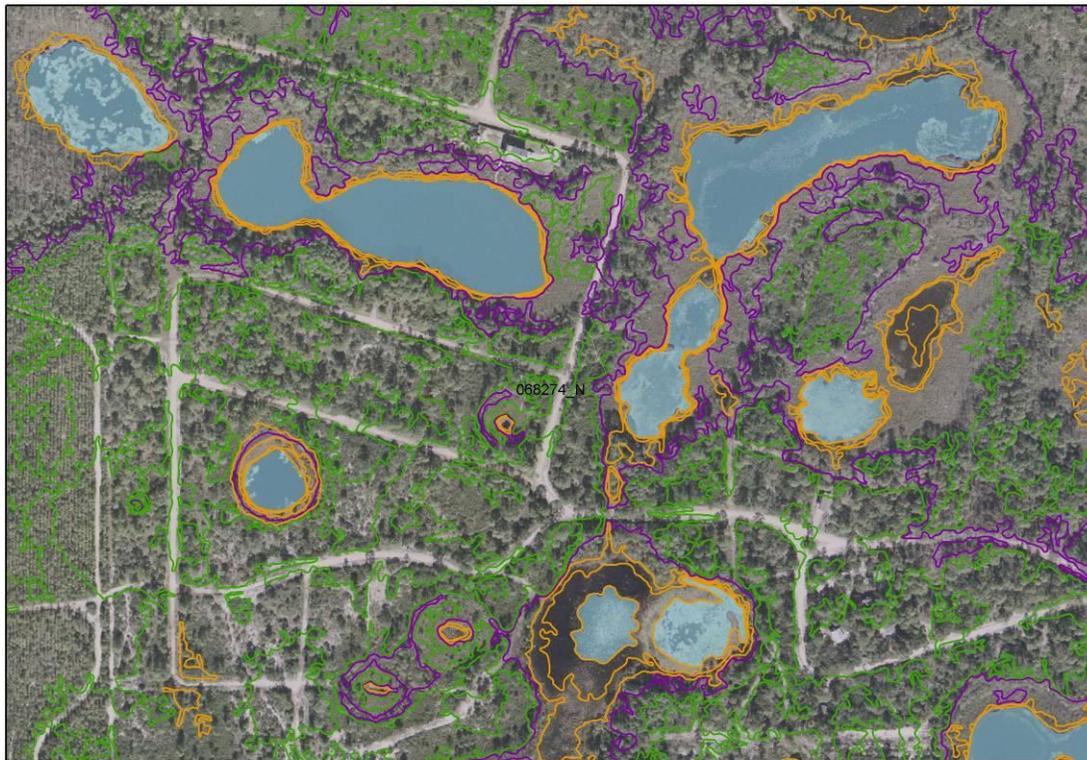
Breaklines

- Dual Line Feature
- Single Line Feature
- Soft Hydro Dual Line Feature
- Soft Hydro Single Line Feature
- OVERPASS
- ROADBREAKLINE
- SOFTFEATURE
- ISLAND
- WATERBODY
- COASTALSHORELINE
- LOWCONFIDENCE

Figure 2. Example linear hydrographic feature breaklines and contours from tile # 73107, 73106, 73647, 73646

Closed Water Body Features

Closed water body features with an area of one-half acre or greater are correctly captured as two-dimensional closed polygons with a constant elevation that reflects the best estimate of the water elevation at the time of data capture. “Donuts” exist where there are islands within a closed water body feature. Figure 3 shows example breaklines and contours of closed water body features.



Contours

- DEPRESSION
- +— DEPRESSION LOW CONFIDENCE
- INDEX
- +— INDEX LOW CONFIDENCE
- INTERMEDIATE
- +— INTERMEDIATE LOW CONFIDENCE
- SUPPLEMENTARY
- +— SUPPLEMENTARY LOW CONFIDENCE

Breaklines

- Dual Line Feature
- Single Line Feature
- Soft Hydro Dual Line Feature
- Soft Hydro Single Line Feature
- OVERPASS
- ROADBREAKLINE
- SOFTFEATURE
- ISLAND
- WATERBODY
- COASTALSHORELINE
- LOWCONFIDENCE

Figure 3. Example closed water body feature breaklines and contours from tile #68274

Road Features

Road edge of pavement features are correctly captured as three-dimensional breaklines on both sides of paved roads. Box culverts are continued as edge of pavement unless a clear guardrail system is in place; in that case, culverts are captured as a bridge or overpass feature. Each vertex maintains vertical integrity. Figure 4 shows example breaklines and contours of road features.



Contours

- DEPRESSION
- + DEPRESSION LOW CONFIDENCE
- INDEX
- + INDEX LOW CONFIDENCE
- INTERMEDIATE
- + INTERMEDIATE LOW CONFIDENCE
- SUPPLEMENTARY
- + SUPPLEMENTARY LOW CONFIDENCE

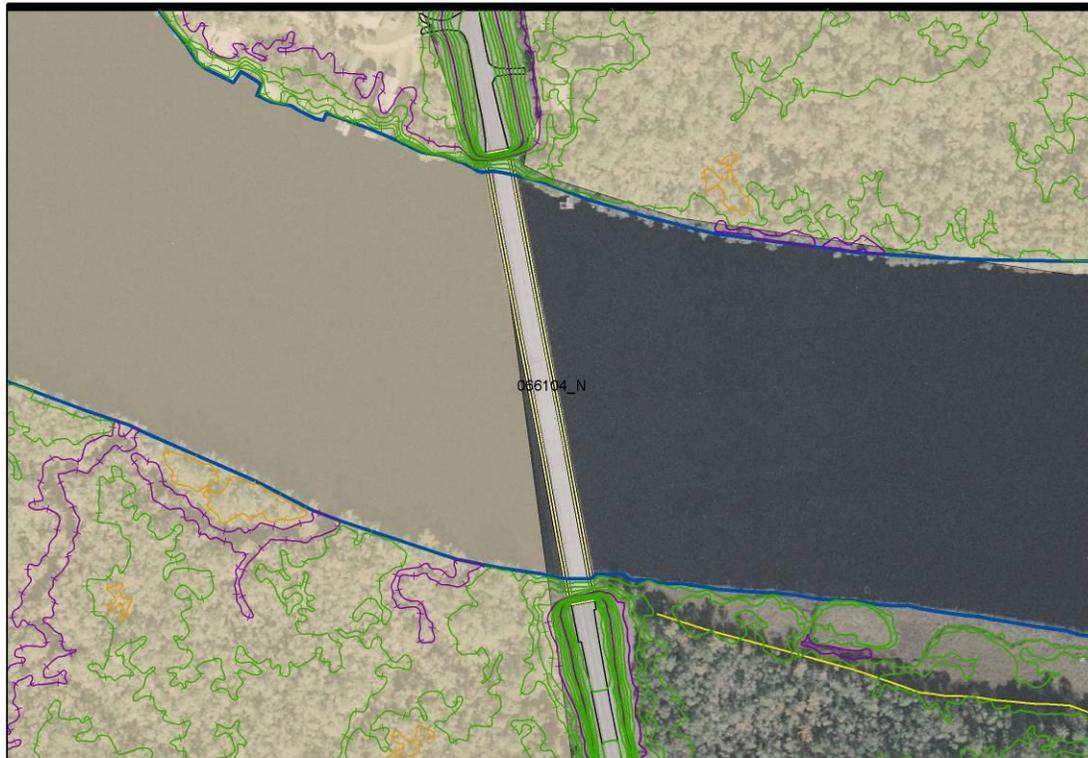
Breaklines

- Dual Line Feature
- Single Line Feature
- Soft Hydro Dual Line Feature
- Soft Hydro Single Line Feature
- OVERPASS
- ROADBREAKLINE
- SOFTFEATURE
- ISLAND
- WATERBODY
- COASTALSHORELINE
- LOWCONFIDENCE

Figure 4. Example road feature breaklines and contours from tiles #76333

Bridge and Overpass Features

Bridges and overpasses are correctly captured as three-dimensional breaklines, capturing the edge of pavement on the bridge, rather than the elevation of guard rails or other bridge surfaces. Each vertex maintains vertical integrity. Figure 5 shows example breaklines and contours of bridge and overpass features.



Contours

- DEPRESSION
- +— DEPRESSION LOW CONFIDENCE
- INDEX
- +— INDEX LOW CONFIDENCE
- INTERMEDIATE
- +— INTERMEDIATE LOW CONFIDENCE
- SUPPLEMENTARY
- +— SUPPLEMENTARY LOW CONFIDENCE

Breaklines

- Dual Line Feature
- Single Line Feature
- Soft Hydro Dual Line Feature
- Soft Hydro Single Line Feature
- OVERPASS
- ROADBREAKLINE
- SOFTFEATURE
- ISLAND
- WATERBODY
- COASTALSHORELINE
- LOWCONFIDENCE

Figure 5. Example bridge and overpass feature breaklines and contours from tile # 66104

Soft Features

Soft features such as ridges, valleys, top of banks, etc. are correctly captured as three-dimensional breaklines so as to support better hydrological modeling of the LiDAR data and contours. Each vertex maintains vertical integrity. Figure 6 shows example breaklines and contours of soft features.



Contours

- DEPRESSION
- +— DEPRESSION LOW CONFIDENCE
- INDEX
- +— INDEX LOW CONFIDENCE
- INTERMEDIATE
- +— INTERMEDIATE LOW CONFIDENCE
- SUPPLEMENTARY
- +— SUPPLEMENTARY LOW CONFIDENCE

Breaklines

- Dual Line Feature
- Single Line Feature
- Soft Hydro Dual Line Feature
- Soft Hydro Single Line Feature
- OVERPASS
- ROADBREAKLINE
- SOFTFEATURE
- ISLAND
- WATERBODY
- COASTALSHORELINE
- LOWCONFIDENCE

Figure 6. Example soft feature breaklines and contours from tile #75260

Island Features

The shoreline of islands within water bodies are correctly captured as two-dimensional breaklines in coastal and/or tidally influenced areas and as three-dimensional breaklines in non-tidally influenced areas for island features one-half acre in size or greater. All natural and man-made islands are depicted as closed polygons with constant elevation. Figure 7 shows example breaklines and contours for island features.



Contours

- DEPRESSION
- +— DEPRESSION LOW CONFIDENCE
- INDEX
- +— INDEX LOW CONFIDENCE
- INTERMEDIATE
- +— INTERMEDIATE LOW CONFIDENCE
- SUPPLEMENTARY
- +— SUPPLEMENTARY LOW CONFIDENCE

Breaklines

- Dual Line Feature
- Single Line Feature
- Soft Hydro Dual Line Feature
- Soft Hydro Single Line Feature
- OVERPASS
- ROADBREAKLINE
- SOFTFEATURE
- ISLAND
- WATERBODY
- COASTALSHORELINE
- LOWCONFIDENCE

Figure 7. Example island feature breaklines and contours from tiles # 76334

Low Confidence Areas

The apparent boundary of vegetated areas (1/2 acre or larger) that are considered obscured to the extent that adequate vertical data cannot be clearly determined to accurately define the DTM are correctly captured as two-dimensional features with no z-values. Figure 8 shows example breaklines and contours for low confidence areas.

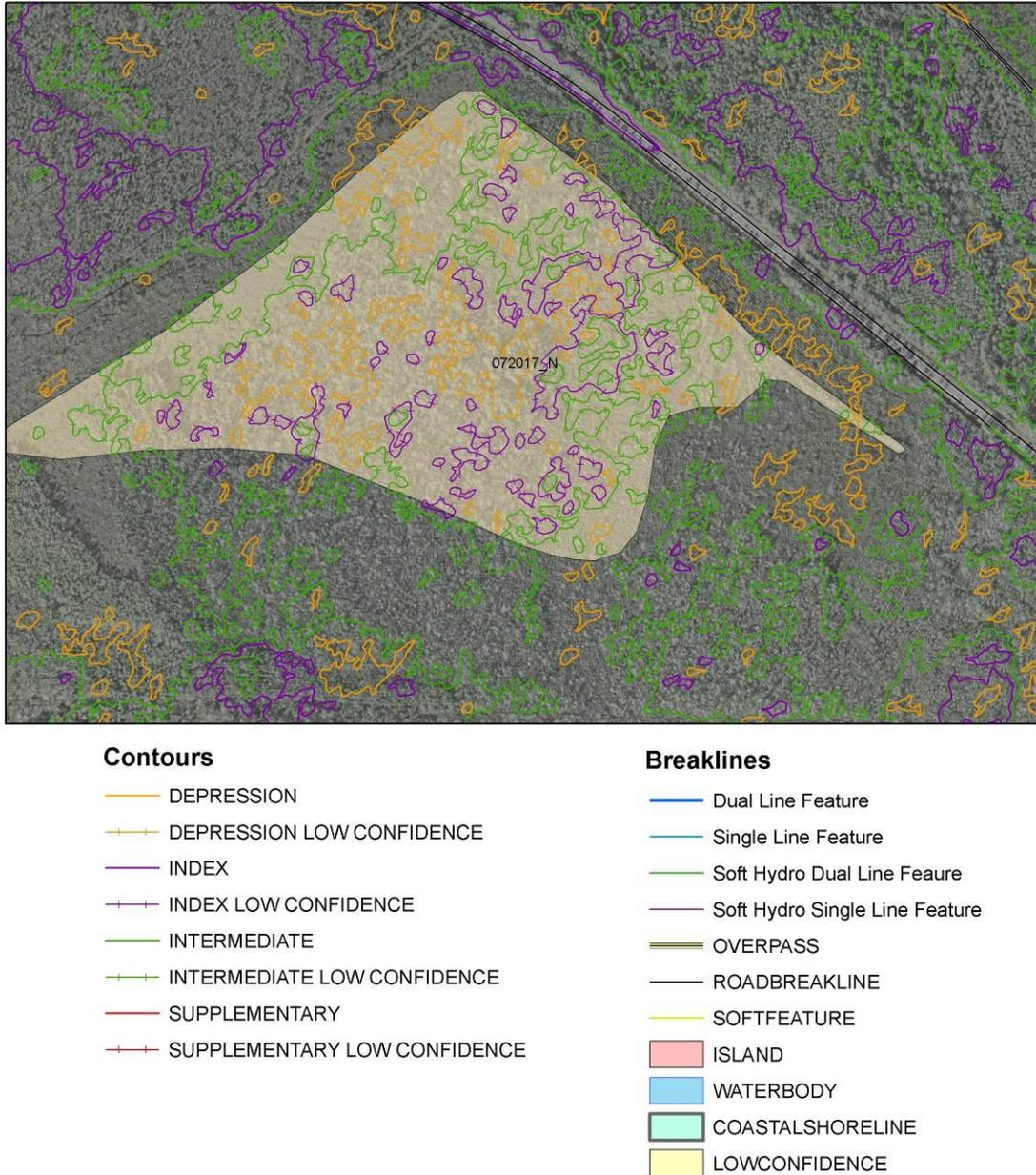


Figure 8. Example low confidence area feature breaklines and contours from tile # 72017

Appendix I: Geodatabase Structure

